

# Data Mining

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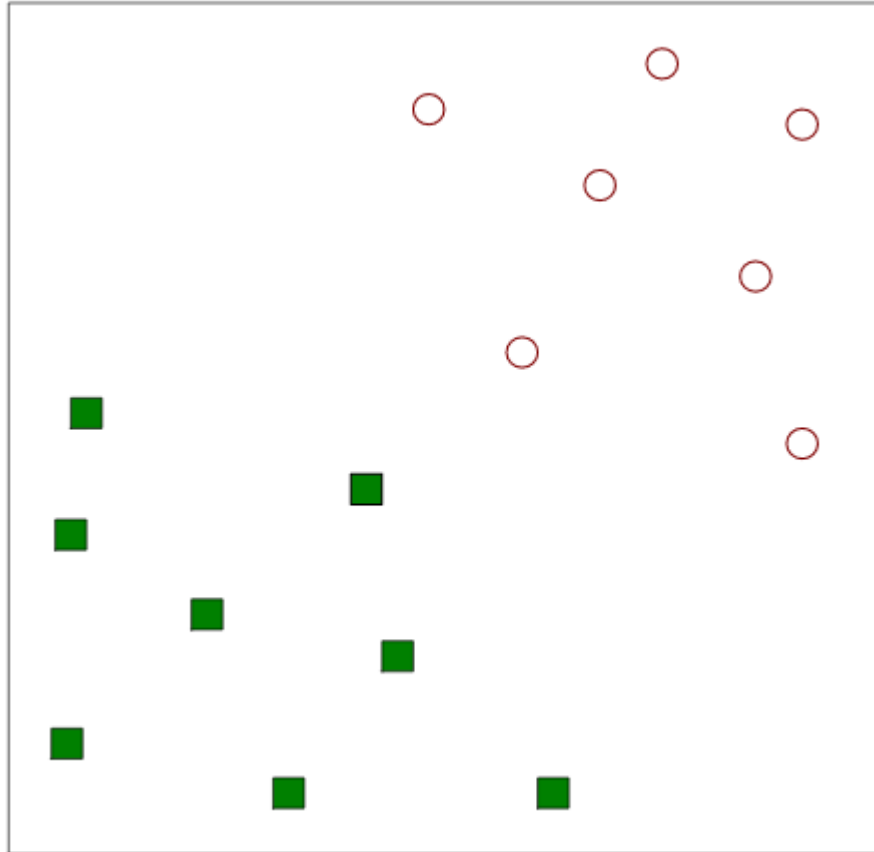
## Support Vector Machines

**Introduction to Data Mining, 2<sup>nd</sup> Edition**  
**by**  
**Tan, Steinbach, Karpatne, Kumar**

# Support Vector Machines

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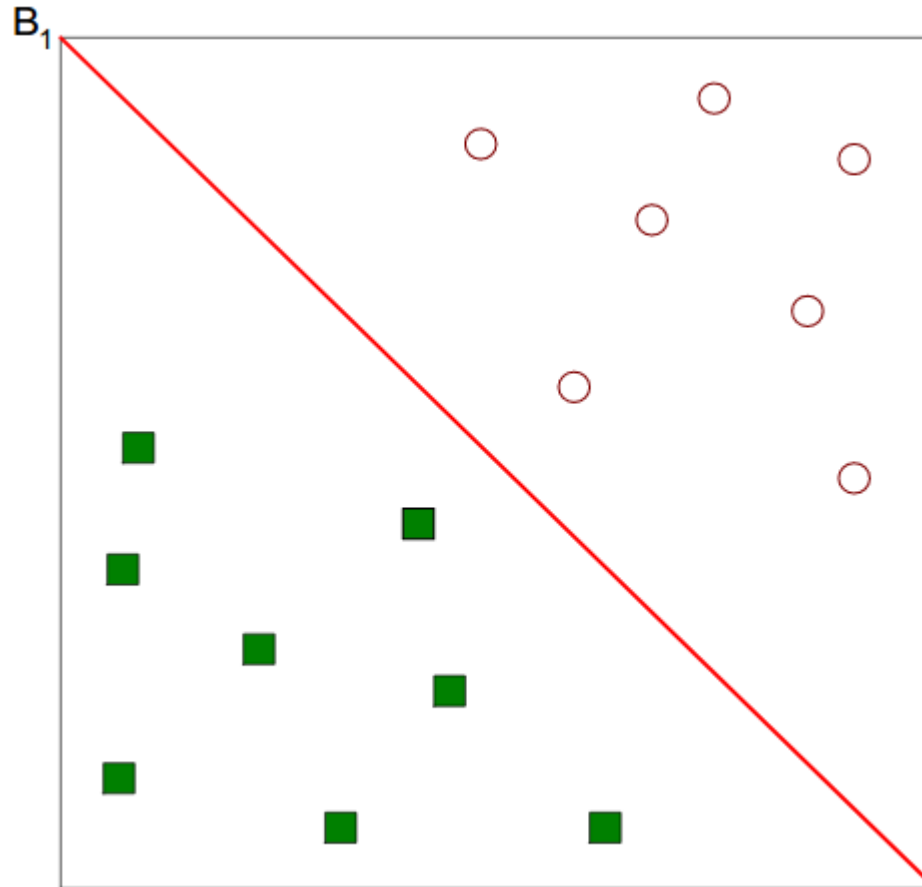


- Find a linear hyperplane (decision boundary) that will separate the data

# Support Vector Machines

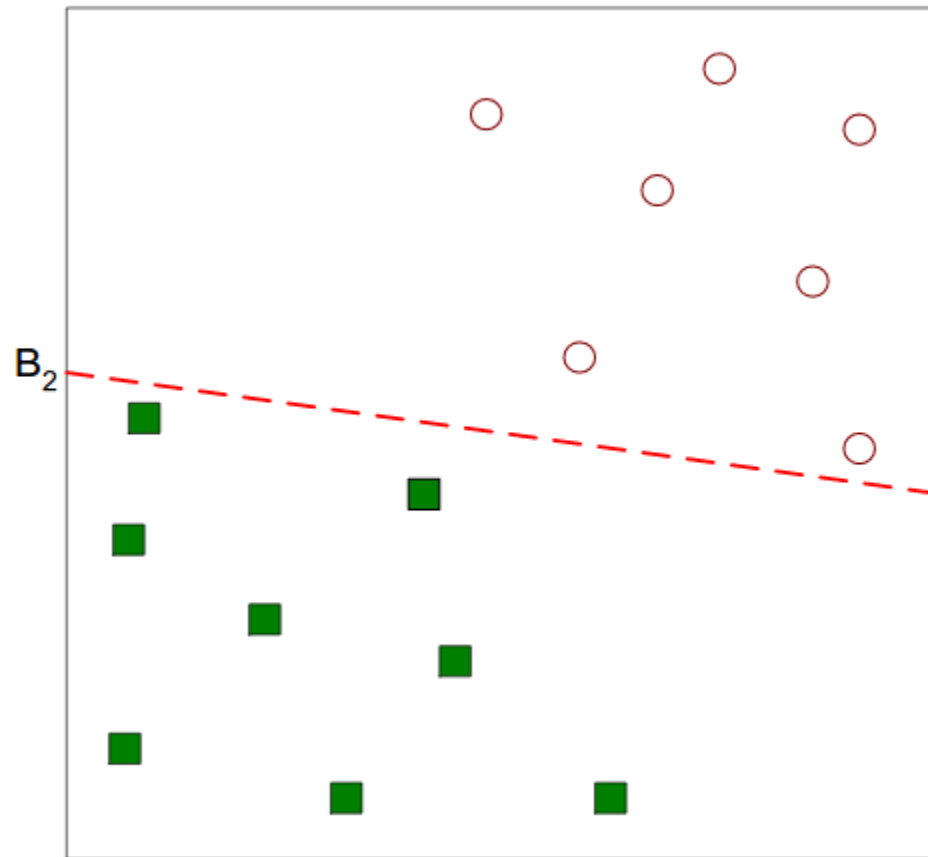
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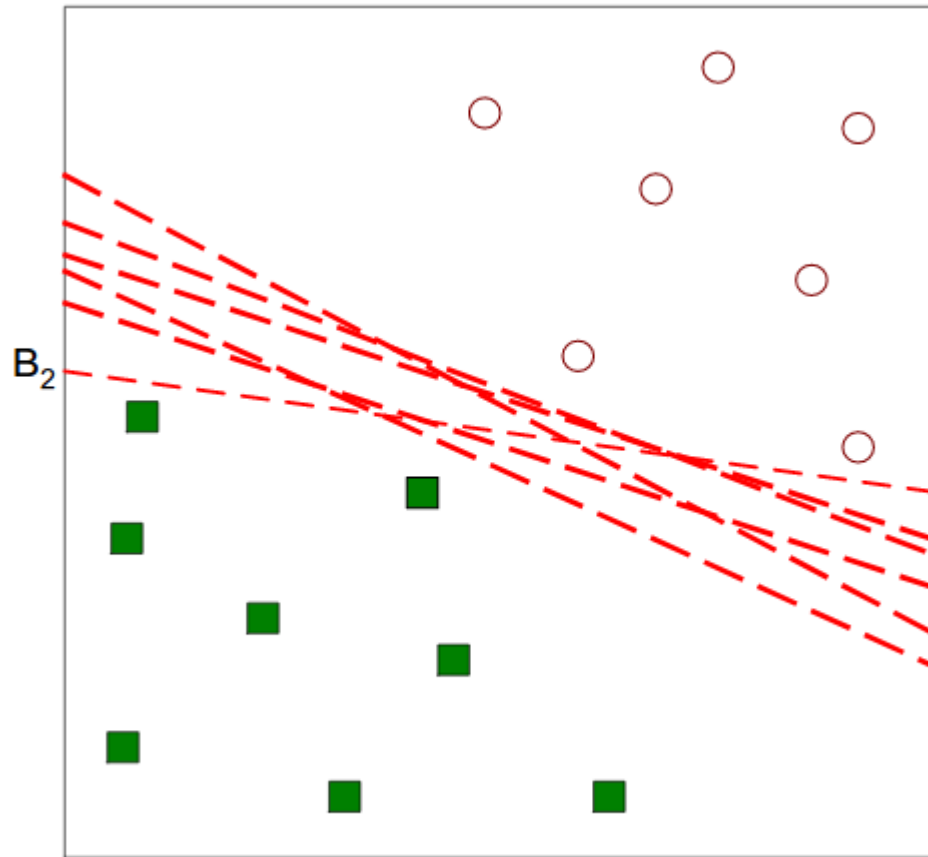
- One Possible Solution

# Support Vector Machines



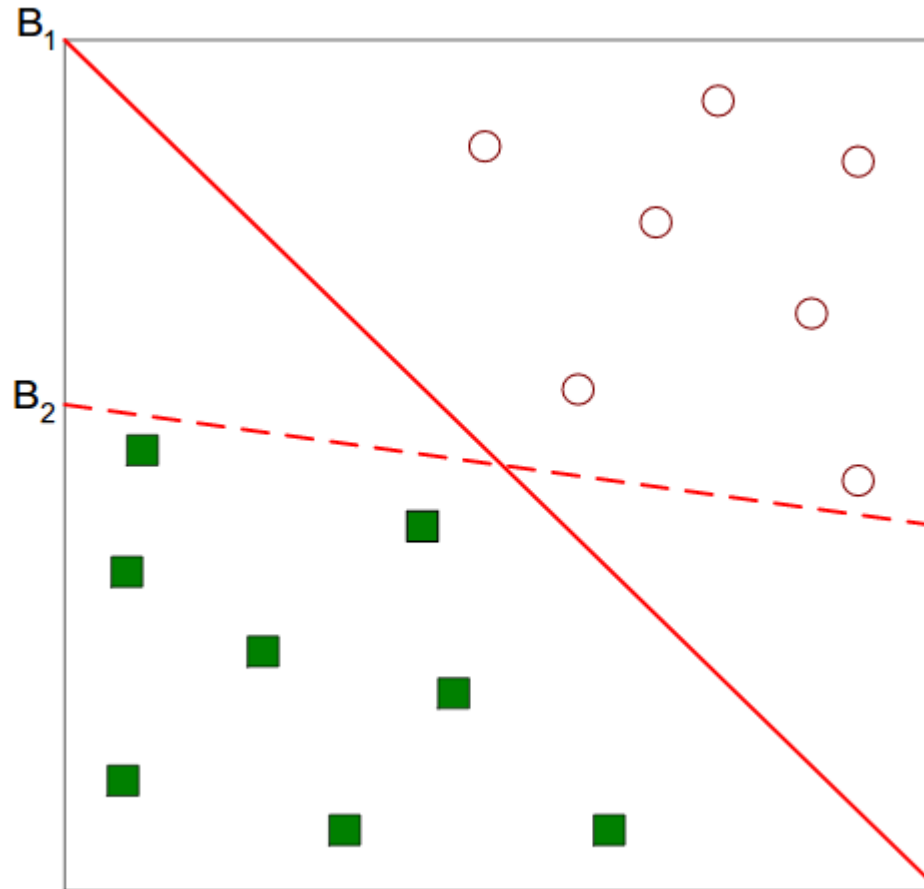
- Another possible solution

# Support Vector Machines



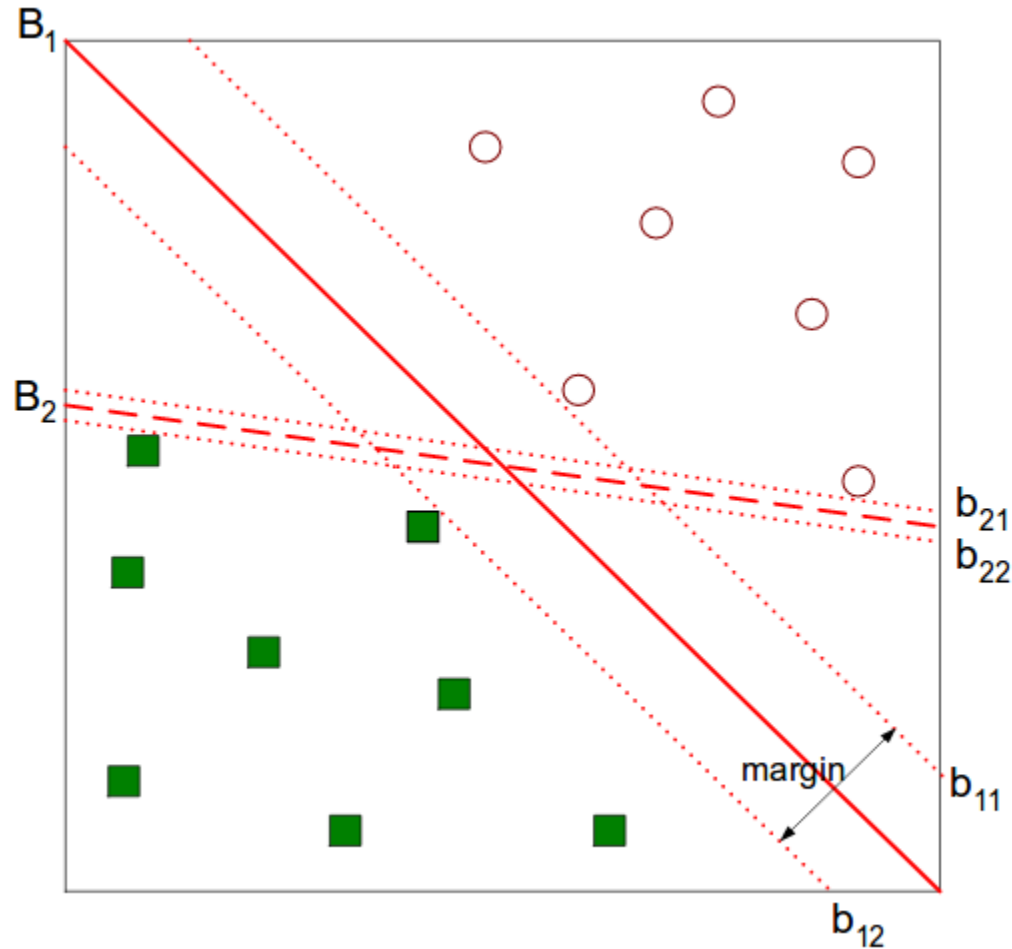
- Other possible solutions

# Support Vector Machines



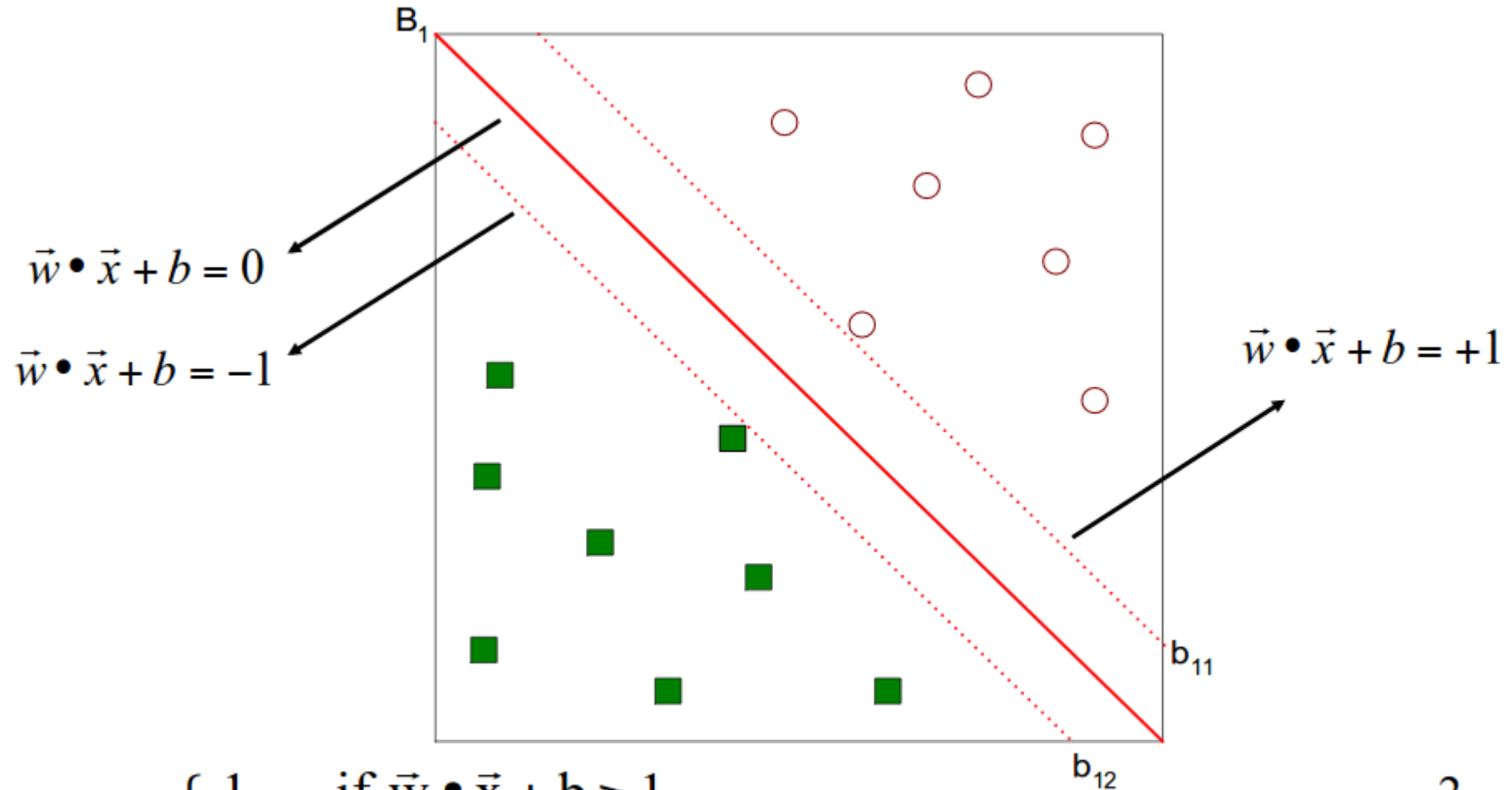
- Which one is better?  $B_1$  or  $B_2$ ?
- How do you define better?

# Support Vector Machines



- Find hyperplane **maximizes** the margin => B1 is better than B2

# Support Vector Machines



$$f(\vec{x}) = \begin{cases} 1 & \text{if } \vec{w} \cdot \vec{x} + b \geq 1 \\ -1 & \text{if } \vec{w} \cdot \vec{x} + b \leq -1 \end{cases}$$

$$\text{Margin} = \frac{2}{\|\vec{w}\|}$$



# Linear SVM

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- **Linear model:**

$$f(\vec{x}) = \begin{cases} 1 & \text{if } \vec{w} \cdot \vec{x} + b \geq 1 \\ -1 & \text{if } \vec{w} \cdot \vec{x} + b \leq -1 \end{cases}$$

- **Learning the model is equivalent to determining the values of  $\vec{w}$  and  $b$** 
  - **How to find  $\vec{w}$  and  $b$  from training data?**

# Learning Linear SVM

- **Objective is to maximize:** Margin =  $\frac{2}{\|\vec{w}\|}$

- Which is equivalent to minimizing:  $L(\vec{w}) = \frac{\|\vec{w}\|^2}{2}$
- Subject to the following constraints:

$$y_i = \begin{cases} 1 & \text{if } \vec{w} \cdot \vec{x}_i + b \geq 1 \\ -1 & \text{if } \vec{w} \cdot \vec{x}_i + b \leq -1 \end{cases}$$

or

$$y_i (w \cdot x_i + b) \geq 1, \quad i = 1, 2, \dots, N$$

- ◆ This is a constrained optimization problem
  - Solve it using Lagrange multiplier method

# Learning Linear SVM

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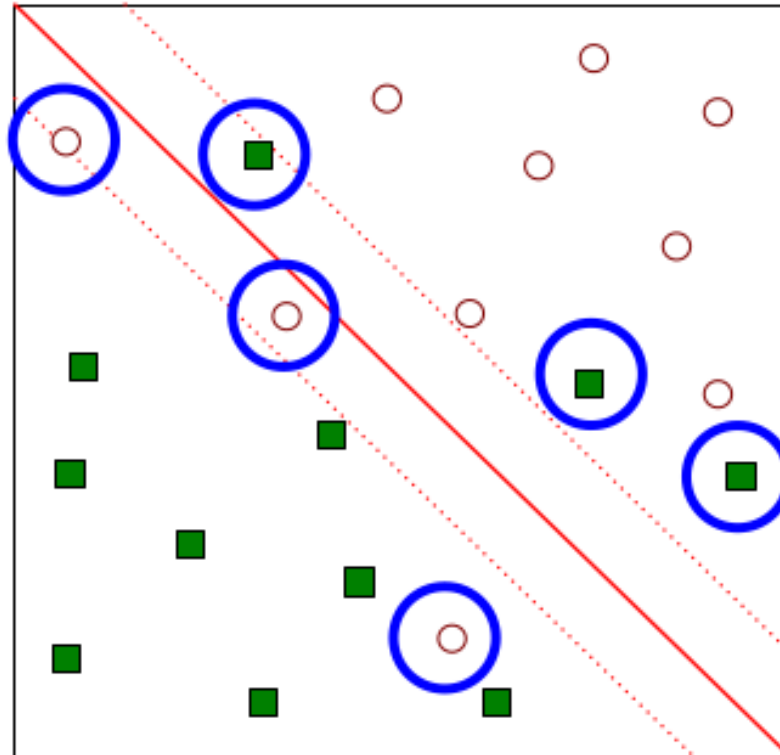
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- **Decision boundary depends only on support vectors**
  - **If you have data set with same support vectors, decision boundary will not change**
  - **How to classify using SVM once  $w$  and  $b$  are found? Given a test record,  $x_i$**

$$f(\vec{x}_i) = \begin{cases} 1 & \text{if } \vec{w} \cdot \vec{x}_i + b \geq 1 \\ -1 & \text{if } \vec{w} \cdot \vec{x}_i + b \leq -1 \end{cases}$$

# Support Vector Machines

- What if the problem is not linearly separable?



# Support Vector Machines

- What if the problem is not linearly separable?

- Introduce slack variables

- ◆ Need to minimize:

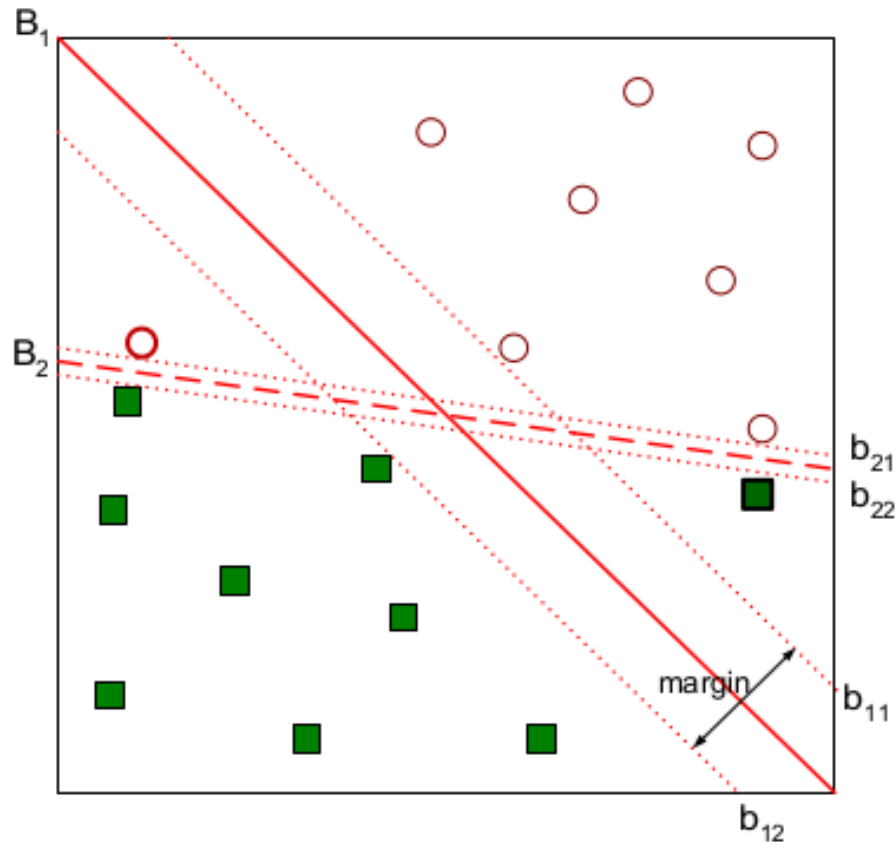
$$L(w) = \frac{\|\vec{w}\|^2}{2} + C \left( \sum_{i=1}^N \xi_i^k \right)$$

- ◆ Subject to:

$$y_i = \begin{cases} 1 & \text{if } \vec{w} \cdot \vec{x}_i + b \geq 1 - \xi_i \\ -1 & \text{if } \vec{w} \cdot \vec{x}_i + b \leq -1 + \xi_i \end{cases}$$

- ◆ If  $k$  is 1 or 2, this leads to same objective function as linear SVM but with different constraints (see textbook)

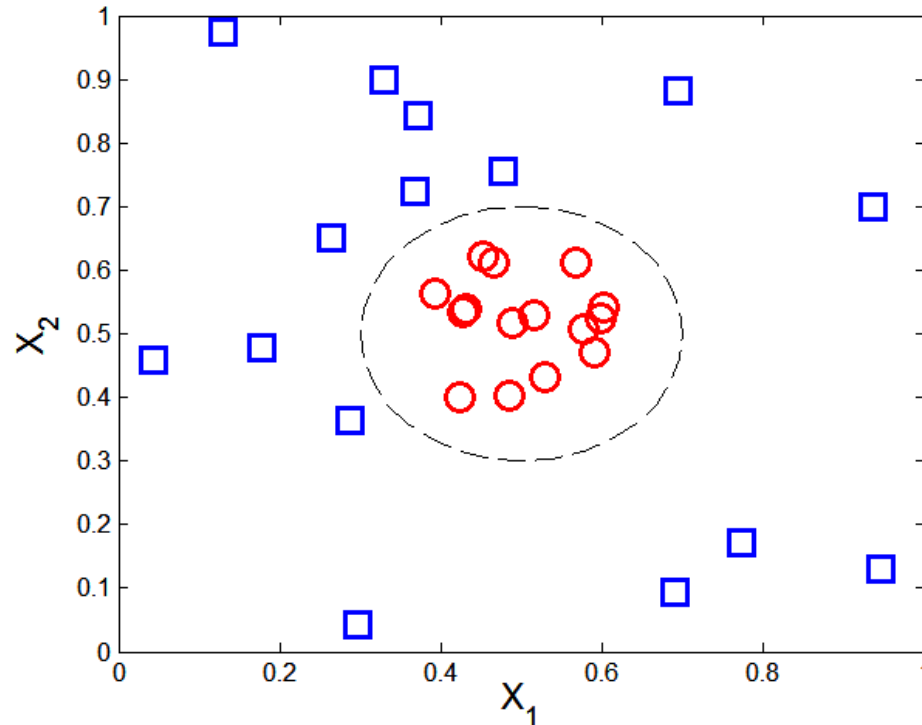
# Support Vector Machines



- Find the hyperplane that optimizes both factors

# Nonlinear Support Vector Machines

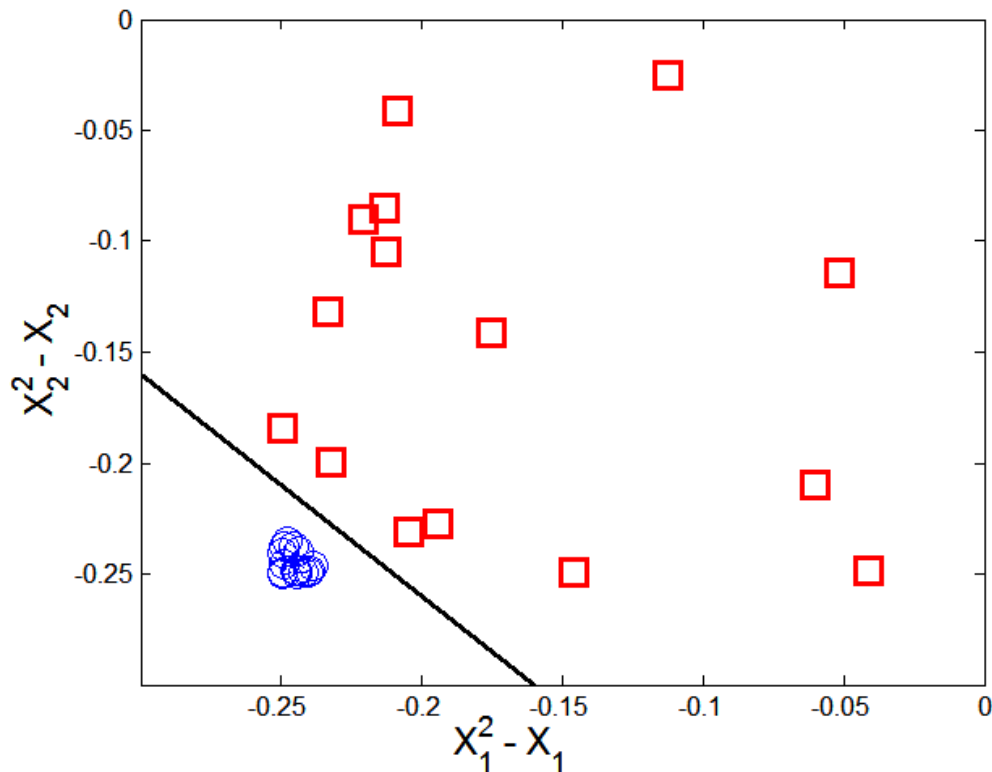
- What if decision boundary is not linear?



$$y(x_1, x_2) = \begin{cases} 1 & \text{if } \sqrt{(x_1 - 0.5)^2 + (x_2 - 0.5)^2} > 0.2 \\ -1 & \text{otherwise} \end{cases}$$

# Nonlinear Support Vector Machines

- Trick: Transform data into higher dimensional space



$$x_1^2 - x_1 + x_2^2 - x_2 = -0.46.$$

$$\Phi : (x_1, x_2) \longrightarrow (x_1^2, x_2^2, \sqrt{2}x_1, \sqrt{2}x_2, 1).$$

$$w_4x_1^2 + w_3x_2^2 + w_2\sqrt{2}x_1 + w_1\sqrt{2}x_2 + w_0 = 0.$$

**Decision boundary:**

$$\vec{w} \cdot \Phi(\vec{x}) + b = 0$$



# Learning Nonlinear SVM

- Optimization problem:

$$\min_w \frac{\|\mathbf{w}\|^2}{2}$$

subject to  $y_i(\mathbf{w} \cdot \Phi(\mathbf{x}_i) + b) \geq 1, \forall \{(\mathbf{x}_i, y_i)\}$

- Which leads to the same set of equations (but involve  $\Phi(\mathbf{x})$  instead of  $\mathbf{x}$ )

$$L_D = \sum_{i=1}^n \lambda_i - \frac{1}{2} \sum_{i,j} \lambda_i \lambda_j y_i y_j \Phi(\mathbf{x}_i) \cdot \Phi(\mathbf{x}_j) \quad \mathbf{w} = \sum_i \lambda_i y_i \Phi(\mathbf{x}_i)$$
$$\lambda_i \{ y_i (\sum_j \lambda_j y_j \Phi(\mathbf{x}_j) \cdot \Phi(\mathbf{x}_i) + b) - 1 \} = 0,$$

$$f(\mathbf{z}) = \text{sign}(\mathbf{w} \cdot \Phi(\mathbf{z}) + b) = \text{sign}\left(\sum_{i=1}^n \lambda_i y_i \Phi(\mathbf{x}_i) \cdot \Phi(\mathbf{z}) + b\right).$$

# Learning NonLinear SVM

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- Issues:

- What type of mapping function  $\Phi$  should be used?
- How to do the computation in high dimensional space?
  - ◆ Most computations involve dot product  $\Phi(x_i) \bullet \Phi(x_j)$
  - ◆ Curse of dimensionality?

# Learning Nonlinear SVM

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- Kernel Trick:

- $\Phi(\mathbf{x}_i) \bullet \Phi(\mathbf{x}_j) = K(\mathbf{x}_i, \mathbf{x}_j)$

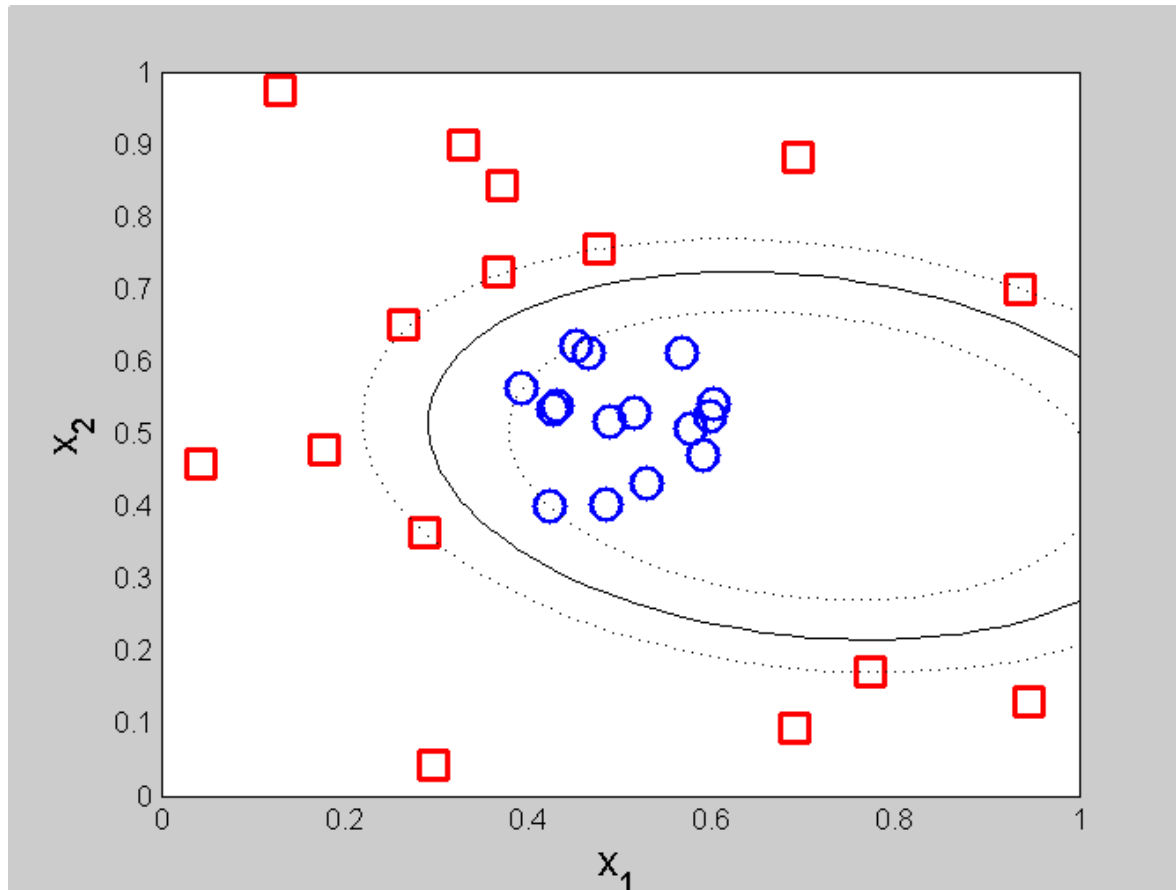
- $K(\mathbf{x}_i, \mathbf{x}_j)$  is a kernel function (expressed in terms of the coordinates in the original space)

- ◆ **Exempl**  $K(\mathbf{x}, \mathbf{y}) = (\mathbf{x} \cdot \mathbf{y} + 1)^p$

- $K(\mathbf{x}, \mathbf{y}) = e^{-\|\mathbf{x}-\mathbf{y}\|^2/(2\sigma^2)}$

- $K(\mathbf{x}, \mathbf{y}) = \tanh(k\mathbf{x} \cdot \mathbf{y} - \delta)$

# Example of Nonlinear SVM



**SVM with polynomial  
degree 2 kernel**

# Learning Nonlinear SVM

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- Advantages of using kernel:
  - Don't have to know the mapping function  $\Phi$
  - Computing dot product  $\Phi(x_i) \bullet \Phi(x_j)$  in the original space avoids curse of dimensionality
- Not all functions can be kernels
  - Must make sure there is a corresponding  $\Phi$  in some high-dimensional space
  - Mercer's theorem (see textbook)

# Characteristics of SVM

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- **Since the learning problem is formulated as a convex optimization problem, efficient algorithms are available to find the global minima of the objective function (many of the other methods use greedy approaches and find locally optimal solutions)**
- **Overfitting is addressed by maximizing the margin of the decision boundary, but the user still needs to provide the type of kernel function and cost function**
- **Difficult to handle missing values**
- **Robust to noise**
- **High computational complexity for building the model**