MAP-I Seminar 17 December 2014

A Practical Approach on Vehicular Networks

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Connecting Vehicles

Why communication in the roads?

mobile data

(telcos are seeking WiFi offloading solutions to cope with 1800% growth in traffic until 2016) continuous connectivity (connectivity anywhere, everytime) connected cars (all Internet-based

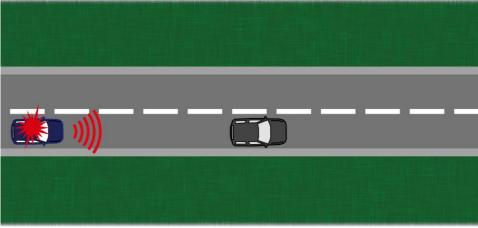
services in the cars)

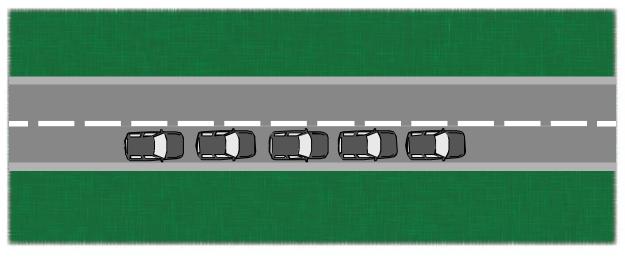
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Safety Applications







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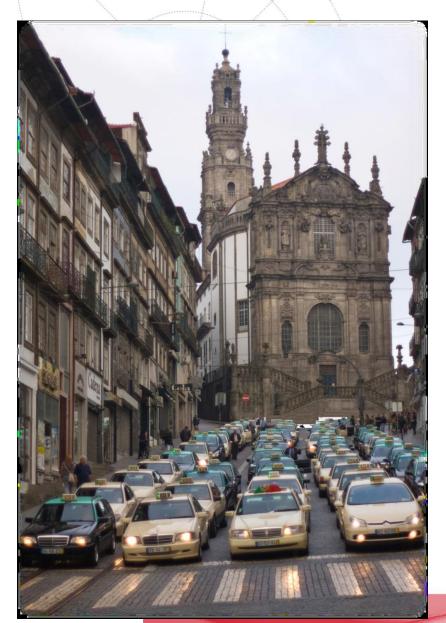
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Traffic and Fleet Management Applications





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M2M Applications



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Entertainment Applications





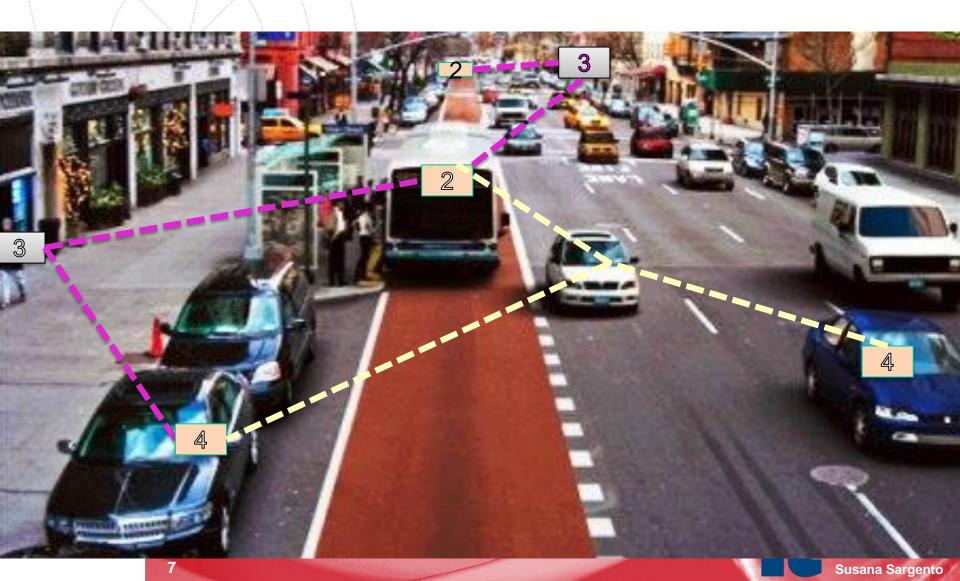
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How do Vehicular Networks Work?



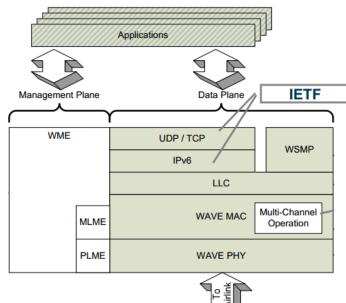
Vehicular Technology: DSRC - IEEE 802.11p and WAVE

Improves transmission range

Reduces the amount of necessary overhead when joining a BSS in 802.11

IEEE 802.11p/1609.4 specify MAC sub-layer functionalities

Channel routing, coordination of access to the



channels, channel switching, time synchronization

Número do canal	172	174	176	178	180	182	184
	SCH	SCH	SCH	ССН	SCH	SCH	SCH
Frequência (GHz)	5.86	5.87	5.88	5.89	5.9	5.91	5.92

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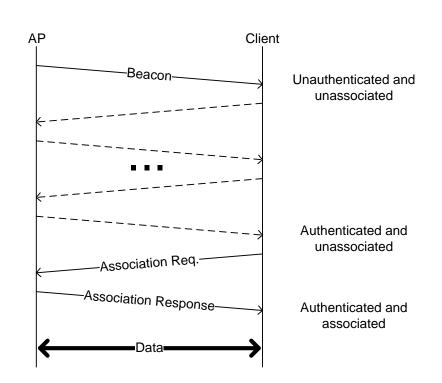
Wi-Fi: Joining

3 Phases

Too many messages

Too much time

The car could be out of the range before the process was complete



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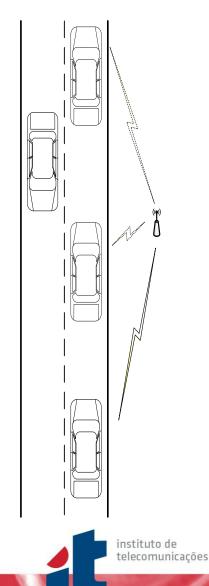
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WAVE Approach: MAC level

When a car is moving, the time it is covered by a BSS may be very short
No time for negotiation, handshakes or complex processes
WAVE BSS

- WBSS is formed just by sending a demand beacon
- The demand beacon has information about the services provided by the WBSS and all the necessary data to join the BSS
- One beacon is enough for a station to join a WBSS



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How does it behave in reality?

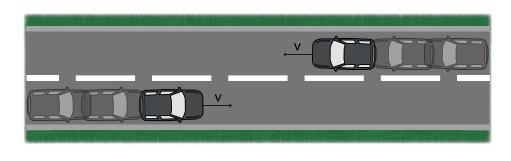
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A Framework for VANET Experimentation Real-world Measurements



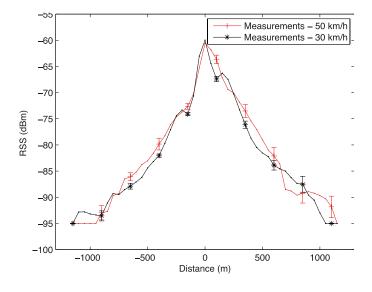


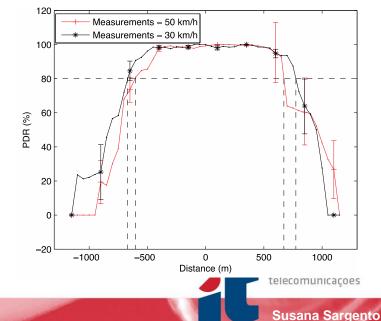
LoS

30 Km/h and 50 Km/h 20 dBm Up to 950m

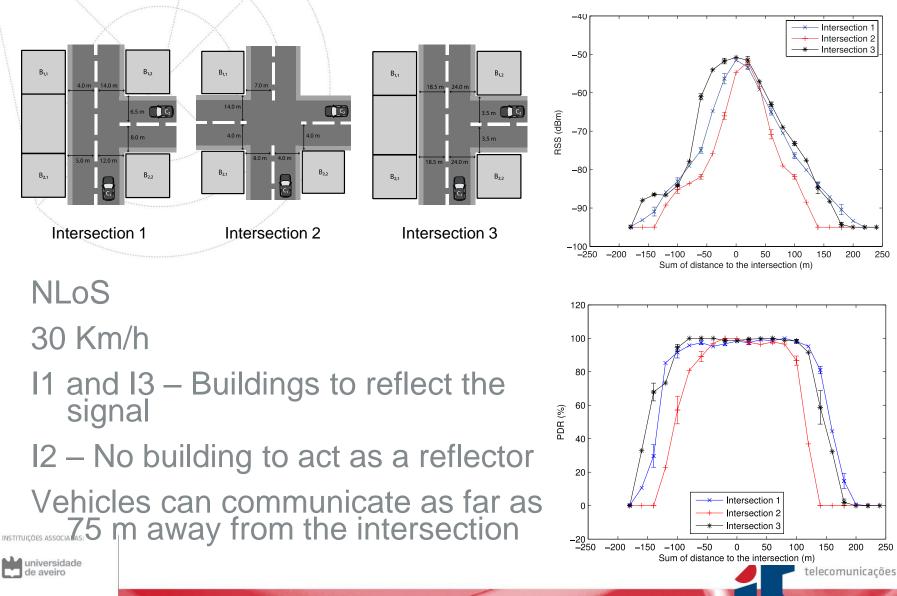
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A Framework for VANET Experimentation Real-world Measurements

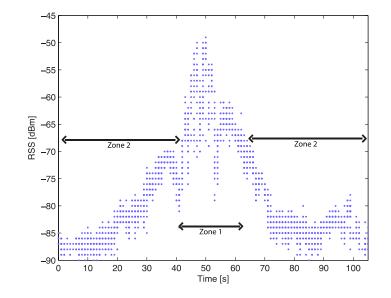


Simulation Vs. Experimentation Observations

Two zones with distinct received signal strength variation patterns

Gaussian distribution

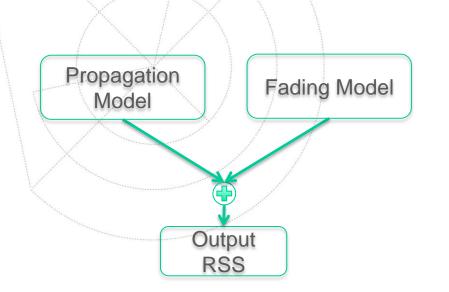
Zero mean (µ)



$$g(x) = \frac{\sqrt{1}}{\sigma} \frac{1}{2\pi} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

	Relative Speed (Km/h)	σ _{zone1}	σ _{zone2}			
	30	2.76	1.62	TX Power (dBm)	σ _{zone1}	σ _{zone2}
				23	2.76	1.62
	60	2.89	1.72	18	2.06	1.30
ти	100	2.81	1.66	10	2.00	
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Simulation Vs. Experimentation The Model and Simulator





Parameter	Value
TxPowerLevels	1
TxPowerStart	12.51 dBm
TxPowerEnd	12.51 dBm
TxGain	2 dBi
RxGain	2 dBi
EnergyDetectionThreshold	-95 dBm

Propagation Model: Two-ray ground

The output of the propagation model is combined with the output of the fading model, yielding the final received signal strength

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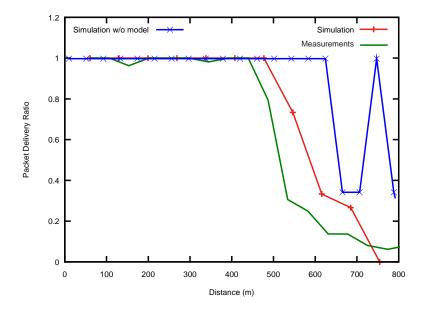


Simulation Vs. Experimentation Validation

Figure of merit:

$$C_{a,b} = \left(1 - \frac{|d_{a80\%} - d_{b80\%}|}{d_{a80\%}}\right) \times 100$$

Based on the distance at which a PDR of 80% is achieved in simulation and in the measurements



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One vehicle travelling away from the other at 30 Km/h

Transmission Power: 12 dBm

Concordance with model: 91.3%

Concordance without model: 69.4%

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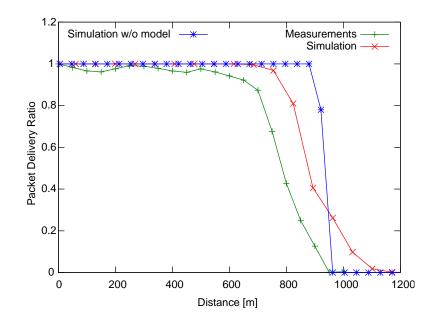
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Simulation Vs. Experimentation Results

Figure of merit:

$$C_{a,b} = \left(1 - \frac{|d_{a80\%} - d_{b80\%}|}{d_{a80\%}}\right) \times 100$$

Based on the distance at which a PDR of 80% is achieved in simulation and in the measurements



One vehicle travelling away from the other at 50 Km/h

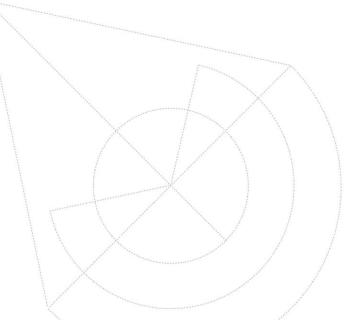
Transmission Power: 23 dBm

Concordance with model: 84.9%

Concordance without model: 71.8%

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How many cars in a city?

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3-D Infrastructure Provisioning and Connectivity Analysis

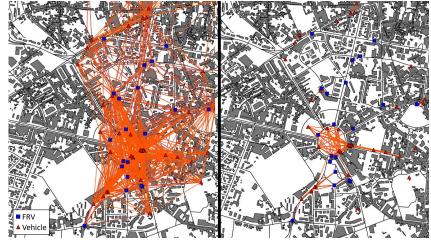
Infrastructure is important to:

Ensure full-connectivity of the network

Alleviate congestion in very dense scenarios

Mobile infrastructure can improve the connectivity and ease the deployment process

Considering buildings in VANET infrastructure planning is crucial



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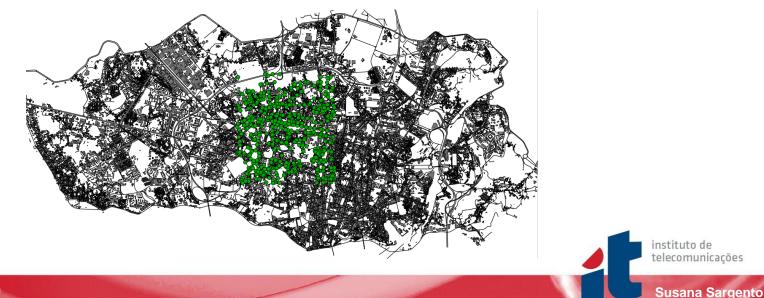
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3-D Infrastructure Provisioning and Connectivity Analysis: Method

Genetic Algorithm Fixed-route vehicle selection mechanism Topology and topography of the area Real-world mobility traces from a fleet of Taxis and public buses in the city of Porto

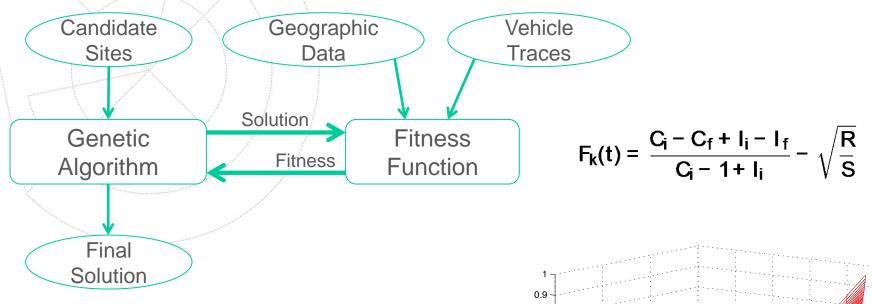
List of suitable sites for RSU deployment



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3-D Infrastructure Provisioning and Connectivity Analysis: Genetic Algorithm



Candidate sites are encoded as a bit string Genetic Algorithm and fitness function are independent

0.8 € 0.6 ≝ Fitness 0.5 0 0.3 10^{-0} 200 400 2 0 600 Nr. of RSUs (N_{RSU}) Nr. of Clusters (C_f) instituto de telecomunicações Susana Sargento

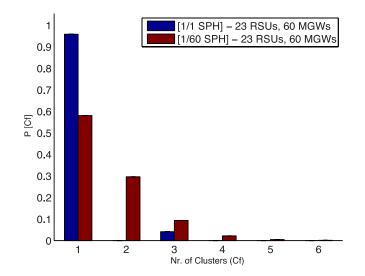
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3-D Infrastructure Provisioning and Connectivity Analysis: Results

Mobile gateways are not capable of connecting the whole network alone

There is a threshold above which more MGWs do not bring further improvement



- RSUs can connect the network by themselves
- However, MGWs can reduce the number of RSUs when combined with them
- Reduction of 25% on the number of RSUs (8) at the expense of 60 MGWs

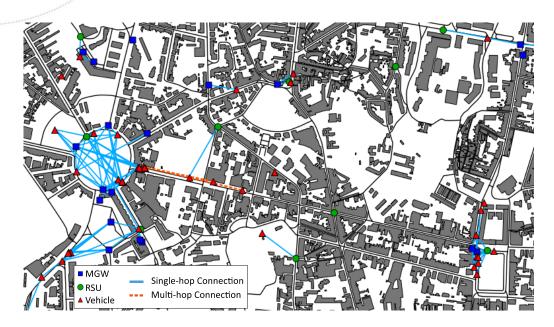
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3-D Infrastructure Provisioning and Connectivity Analysis: Results

 With RSUs and MGWs, most of the communications are performed within a 1-hop and 2-hop distance

Nr. of Hops	Conn. Time (%)
1	90.24
2	9.45
3	0.28
4	0.03



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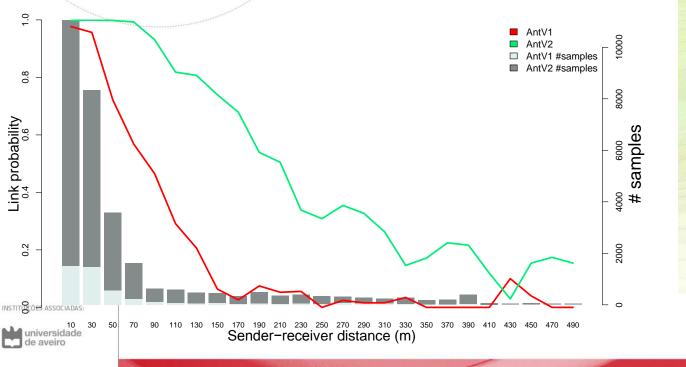
3-D Infrastructure Provisioning and Connectivity Analysis: Taking real connectivity results

City environment; installation in taxis: real even more real

Example:

Antenna height

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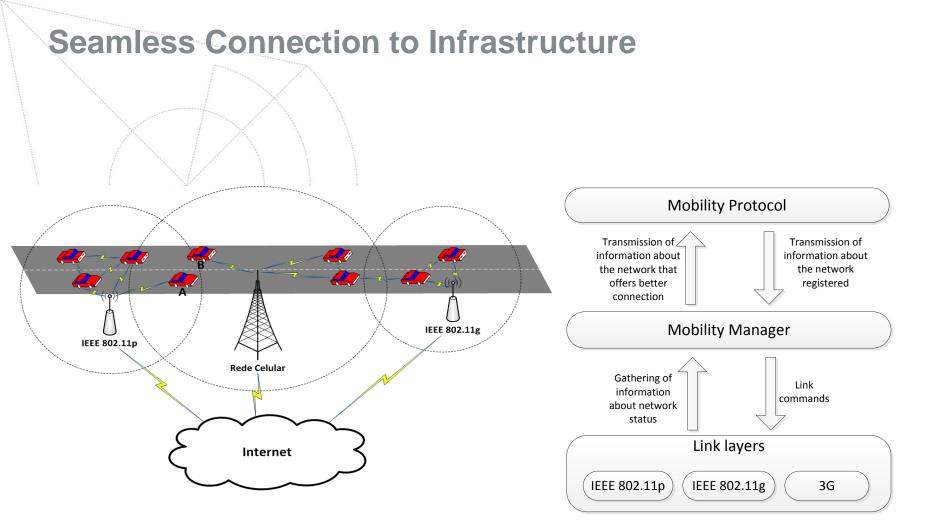
3-D Infrastructure Provisioning and Connectivity Analysis: Taking real connectivity results

X /	\times \wedge \wedge		
Nr. of Hops	Conn. Time (%)	Nr. of Hops	Conn. Time (%)
 1	90.24	1	94,70
2	9.45	2	5,17
3	0.28	3	0,11
4	0.03	4	0,02
SRSUs (100-600			SUs (real radio range
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How to seamlessly interconnect to infrastructure and provide mobility?

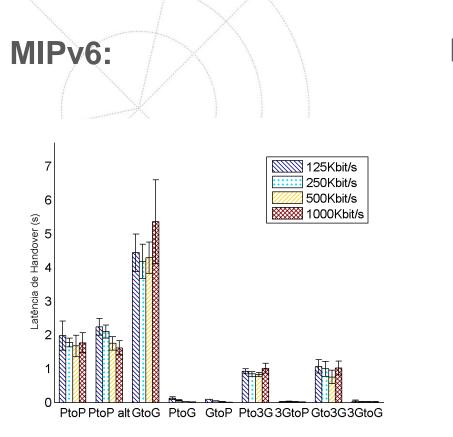
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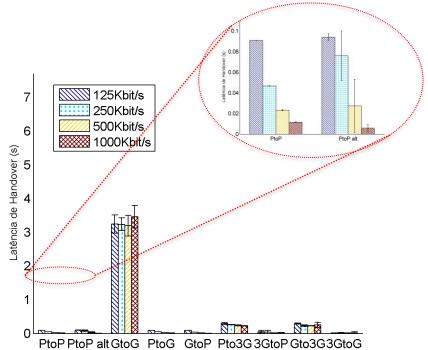




Handover Latency: lab environment



PMIPv6:



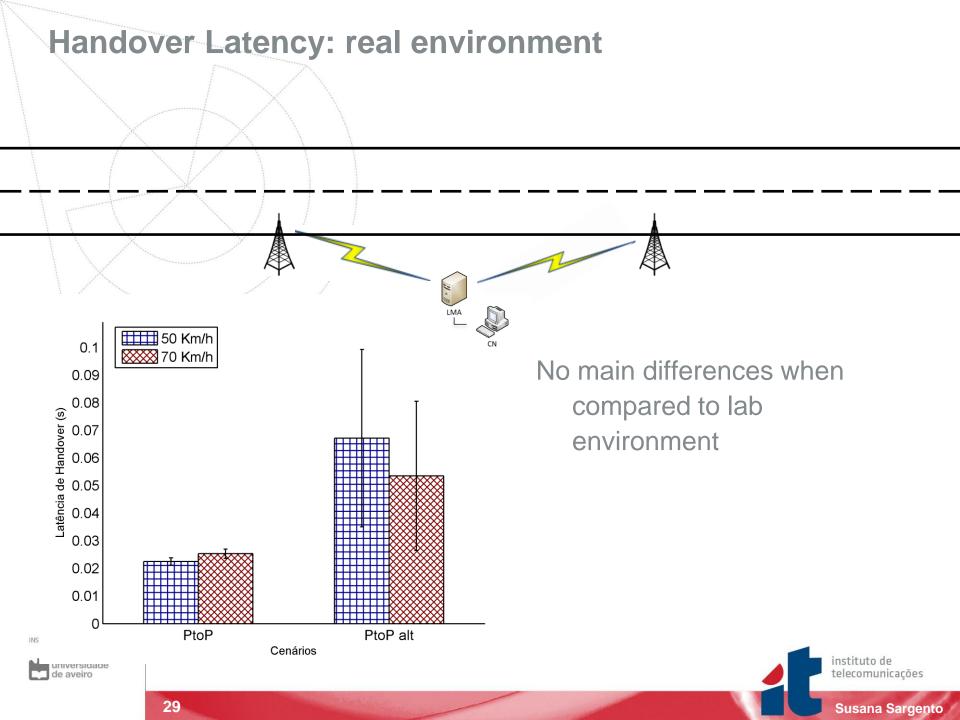
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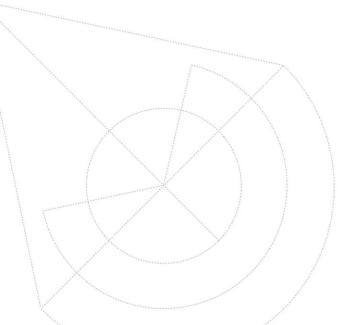
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Deployed Plaforms

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How everything started...

CMU|Portugal Project DRIVE-IN through a real need...

We were crazy enough to promise to connect 500 vehicles (by far the largest vehicular testbed in the world)...

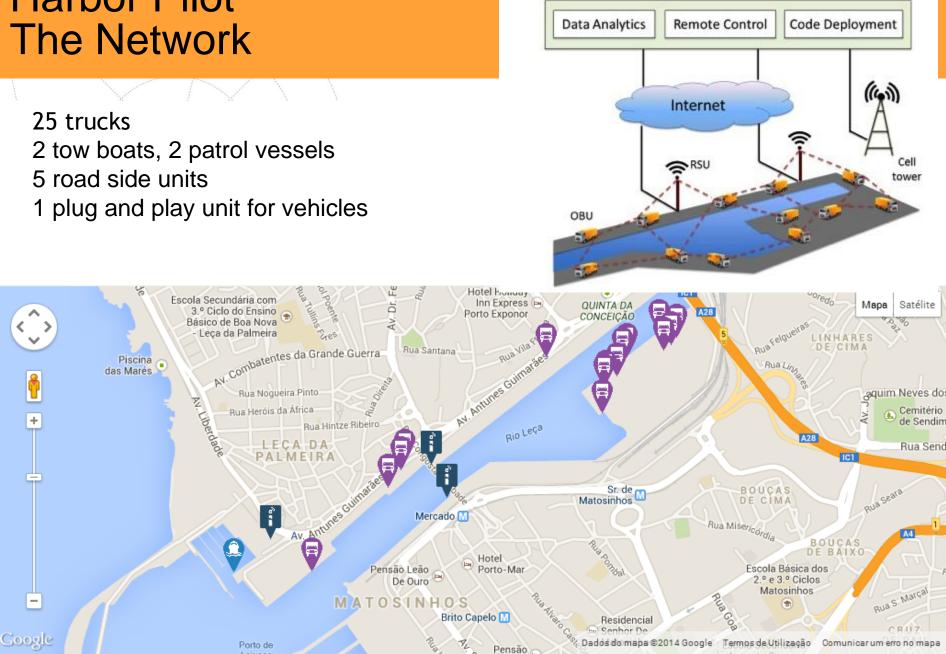
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... it was not easy...

But we did it! 🙂

Harbor Pilot



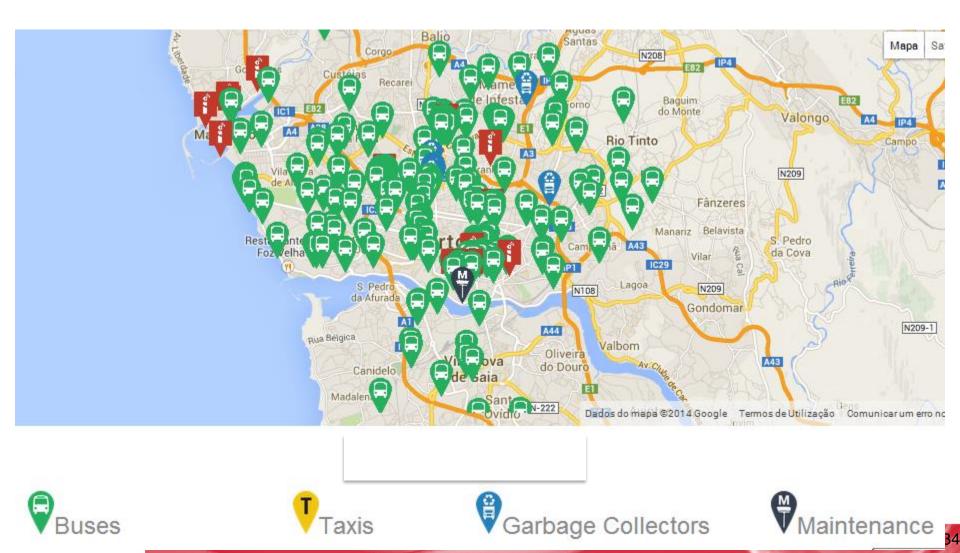
Harbor Pilot Results

5 road side units Latency in the .11p network <= 10 msec Congestion latency <= 100 msec Handover time <= 100 msec Density of vehicles in rush hour: 25 trucks in the harbor Coverage >= 600m in LoS



City Pilot The Network

400 buses, 150 taxis, 20 municipality vehicles, 8 road side units



City Pilot Results

Bandwidth > 10 Mb/sec

```
Latency in the .11p network <= 10 msec
```

Congestion latency <= 100 msec

Handover time <= 100 msec

Density of vehicles in rush hour (in the map, 1Km²): >90 buses

```
Coverage >= 600m in LoS
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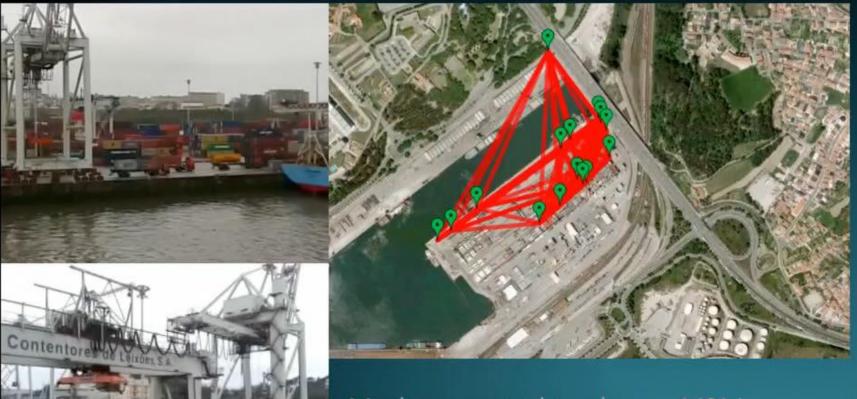
Up to 6 videos in the bus, simultaneously

Many internet access users



Vehicular Network at Leixões Harbor





Contentore Bellon Sa

Mesh connected trucks use M2M connections over IEEE 802.11p links to upload big data for harbor management.

DTN - Overview

DTN: Delay-/Disruption-Tolerant Networking

- Permanent storage allows tolerance to delay and disruption.
- PDU: Bundle. Contains all information for transaction (authentication, options, etc.).
- Congestion: concern at storage level, as well as at link level.

Routing:

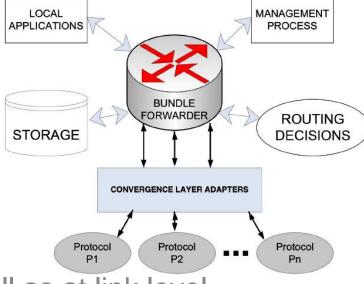
Considers that nodes may carry data in space

Decides when to forward.

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DTN Routing Protocols

Three routing protocols were used:

Epidemic: bundles flooded to neighbors at each contact. **Static**: routes are pre-configured so that OBUs relay only directly to RSUs.

PRoPHET:

- Probabilistic Routing Protocol using History of Encounters and Transitivity (PRoPHET)
- Gradient-based, uses concept of delivery predictabilities between nodes, looks at past contacts.

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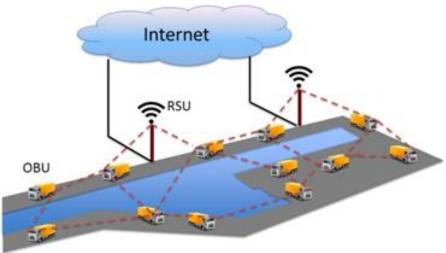


Tests - Harbor Trucks

Setup:

Registering GPS location each second and sending to database:

≈ 35 KB files sent each 10
 minutes, from each truck's OBU
 to server on the Internet.



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Duration = 24h ; Bundle storage limit = 3 MB ; Bundle lifetime = 6h

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Results – Summary Table

Metrics Routing Protocols	Bundles Delivered	Delay*	Number of Useless Replicas*	Number of Useless Transmissions*
Epidemic	98.8 %	341 ± 55 s	4.4 ± 0.2	31.0 ± 2.1
Static	92.8 %	926 ± 167 s	2.8 ± 0.1	22.5 ± 1.0
PRoPHET	86.0 %	$1893 \pm 409 s$	2.3 ± 0.2	6.7 ± 0.7

*Per bundle average for delivered bundles. 95% confidence intervals.

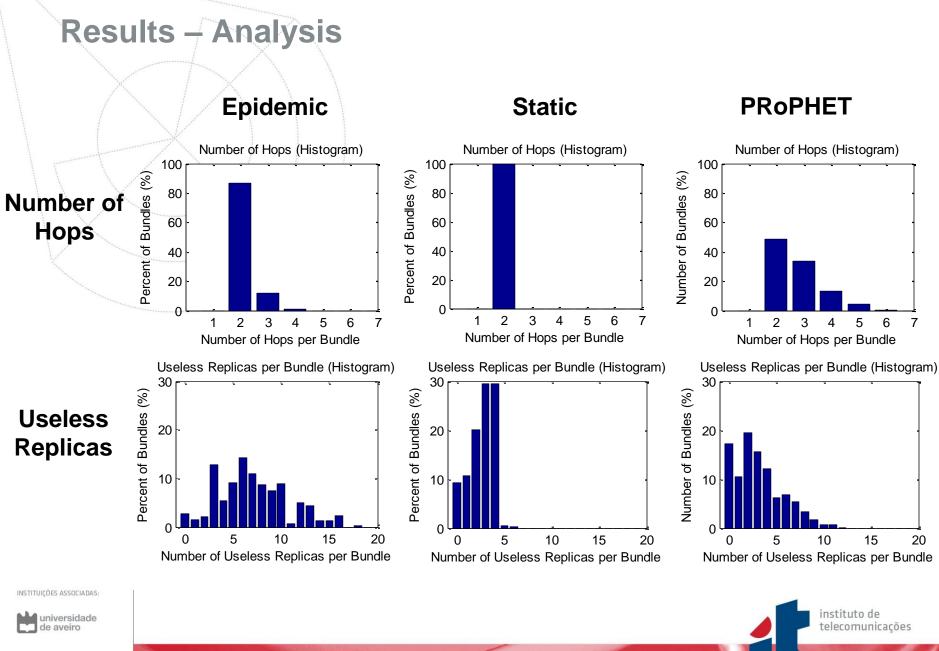
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- **Trade-off:** Delay and Delivery Rates vs. Number of Transmissions and Replicas
- **PROPHET:** Delay much higher than static routing: means nodes are not transmitting whenever they see an RSU.

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Results – Measured Observations

High levels of replication improve delay and delivery rates, as

long as network is not saturated.

 \Rightarrow Need to find an equilibrium point.

Transmissions keep occurring even after bundles have already been delivered to the destination, wasting resources.

⇒ Need of a strategy to deliver acknowledgements to the concerned elements of the network.



Final Thoughts

Theory and reality can be very apart

However, with reality knowledge we can develop new theory models that can match the real environment

Real platforms are the key!

They are costly to deploy

They take much resources effort

But it is the only way to develop accurate network mechanisms!

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Thanks!

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> Credits to: André Cardote, Carlos Ameixieira, Jorge Dias, Filipe Neves, Luís Coelho, Rui Meireles, Romeu Monteiro, Luís Guedes, Tiago Condeixa

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