Functional Logic Semantic Bidirectionalization for Free!

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> FATBIT/SSaaPP Workshop Braga - September 18th 2012

Towards Functional Logic Semantic Bidirectionalization for Free!

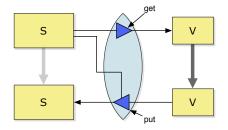
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BXs and Lenses

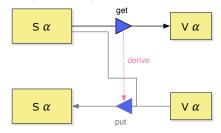
• lenses are one of the most popular BX frameworks



- existing lens systems vary on the bidirectionalization approach
- how is a lens derived from a specification?

Functional Semantic Bidirectionalization

 Voigtländer proposed the semantic bidirectionalization of Haskell functions [POPL'09]

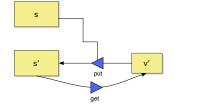


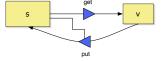
- put via the polymorphic interpretatation of get
- limited expressiveness only polymorphic get functions
- limited updatability even for the mixed approach of Voigtländer et al. [ICFP'10]

The Lens Laws

• PUTGET law put must translate view updates exactly. • GETPUT law put must preserve

empty view updates.



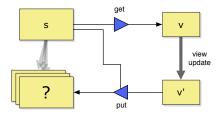


get (put v' s) \sqsubseteq v'

put (get s) s \sqsubseteq s

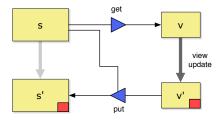
A Better GETPUT Law?

- when the view is modified there are many source updates
- anything can happen! no restriction on the permitted translations



A Better GETPUT Law?

- when the view is modified there are many source updates
- only "good" can happen only minimal source updates are permitted



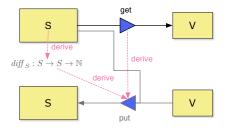
 $\forall v', s, s'. diff (put v' s) s \leq diff s' s$ PUTDIFF

• the differencing function depends on the source type

diff $_{S}: S \rightarrow S \rightarrow \mathbb{N}$

Functional Logic Semantic Bidirectionalization

- Idea: use Curry, a functional logic programming language, to compute such minimal updates
- functional programming: Haskell-like syntax
- logic programming: logic variables, built-in search (findall, best)



- derive *diff* from the source type
- derive put from get and diff

A diff for Algebraic Data Types

- a generic *diff* for algebraic data types
 - Eelco Lempsink, Sean Leather and Andres Löh Type-Safe Diff for Families of Datatypes Workshop on Generic Programming 2009.
- we implement this *diff* in Curry

$$\begin{aligned} & diffND_{List} : [a] \rightarrow [a] \rightarrow \mathbb{N} \\ & diffND_{List} [] [] = 0 \\ & diffND_{List} [] (y : ys) = 1 + diffND_{List} [] ys & -- \text{ insert} \\ & diffND_{List} (x : xs) [] = 1 + diffND_{List} xs [] & -- \text{ delete} \\ & diffND_{List} (x : xs) (y : ys) \\ & | x = := y = diffND_{List} xs ys & -- \text{ copy} \\ & | x = / = y = 1 + diffND_{List} (x : xs) ys & -- \text{ insert} \\ & ? 1 + diffND_{List} xs (y : ys) & -- \text{ delete} \end{aligned}$$

 $diff_{List} s' s = unpack \ head \ best (\lambda n \rightarrow diffND s' s =:= n) (\leqslant)$

• this *diff* calculates the sequence of insert, delete and copy operations with the minimal cost

Curry Implementation

• we implement *put* in Curry as a non-deterministic function

$$put :: V \to S \to S$$

$$put v' s = putn n v' s =:= s'$$
where $n = diff'_S v' s$

$$s' free$$

$$diff'_S v' s = unpack \$ head \$ best$$

$$(\lambda n \to let s' free in get s' =:= v' \& diffND_S s' s =:= n)$$

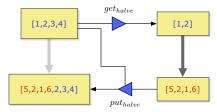
$$putn :: \mathbb{N} \to V \to S \to S$$

$$putn n v' s | get s' =:= v' \& diff_S s' s =:= n = s' where s' free$$

- calculate the minimal difference between any new source (whose view is v') and the original source s
- return any new source whose difference to the original source s is n

Example 1 (*halve*) - First Attempt

calculate the first half of a list

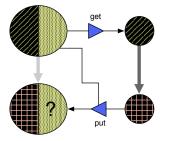


get = halve $halve :: [a] \rightarrow [a]$ halve [] = [] halve (x : xs) = x : halve' xs xswhere halve' xs [] = [] halve' xs [y] = [] halve' (x : xs) (y : z : zs) = x : halve' xs zs

• is this the best result?

Calculating a View Complement

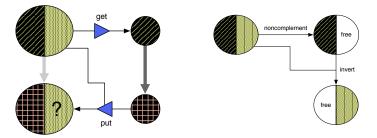
• view complement = source data not present in the view



• put should only recover data from the view complement

Calculating a View Complement

• view complement = source data not present in the view



- put should only recover data from the view complement
- how to calculate the complement in Curry?

noncomplement_S $s = findfirst (\lambda x \rightarrow get x =:= get s \& match_S x s)$ complement_S $s = invert_S s (noncomplement_S s)$ • we refine *diff* to take into account the source complement

$$\begin{array}{l} \text{diffND}_{List} : [a] \to [(a, a)] \to \mathbb{N} \\ \text{diffND}_{List} \left[\right] \left[\right] = 0 \\ \text{diffND}_{List} \left[\right] \left((v, y) : ys \right) = \textit{insert} \\ \text{diffND}_{List} \left(x : xs \right) \left[\right] = \textit{delete} \\ \text{diffND}_{List} \left(x : xs \right) \left((v, y) : ys \right) \\ | x = := y \& \textit{isVar } v = := \textit{False} = \textit{copy} \\ | x = := y \& \textit{isVar } v = := \textit{True} = \textit{insert} ? \textit{delete} \\ | x = / = y \qquad = \textit{insert} ? \textit{delete} \\ \text{diff}_{List} s' s = \textit{unpack} \$ \textit{head} \$ \textit{best} (\lambda n \to \textit{diffND} s' \textit{cs} = := n) (\leqslant) \\ \texttt{where } cs = zip (\textit{complement } s) s \end{array}$$

 we do not allow source data not in the complement to be copied

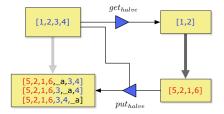
Example 1 (halve) - Second Attempt

• calculate the complement of the source

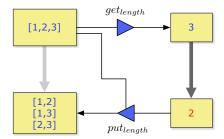
noncomplement_{List}
$$[1, 2, 3, 4] = [1, 2, _a, _b]$$

complement_{List} $[1, 2, 3, 4] = [_a, _b, 3, 4]$

• calculate the first half of a list (revisited)



• compute the length of a list



$$get = length$$

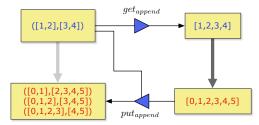
$$length :: [a] \rightarrow \mathbb{N}$$

$$length [] = 0$$

$$length (x : xs) = 1 + length xs$$

Example 3 (*append*)

append two lists into a single list



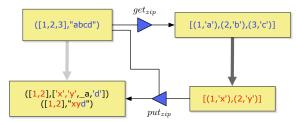
 $\begin{array}{l} get = append \\ append :: ([a], [a]) \rightarrow [a] \\ append ([], ys) = ys \\ append (x : xs, ys) = x : append (xs, ys) \end{array}$

• *diff* for pairs of lists

$$\mathsf{diff}_{\mathsf{List} \ \times \ \mathsf{List}} :: ([a], [a]) \to ([a], [a]) \to \mathbb{N}$$

Example 4 (*zip*)

• join the elements of two lists pair-wise into a single list

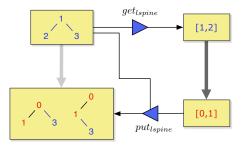


$$get = zip$$

 $zip :: ([a], [b]) \to [(a, b)]$
 $zip ([], ys) = []$
 $zip (xs, []) = []$
 $zip (x : xs, y : ys) = (x, y) : zip (xs, ys)$

Example 5 (*Ispine*)

• calculate the left spine of a binary tree



data Tree a = Empty | Node a (Tree a) (Tree a) get = lspine $lspine :: Tree a \rightarrow [a]$ lspine Empty = []lspine (Node x | r) = x : lspine l

Conclusions

- a semantic bidirectionalization approach using Curry
- users define any $get : S \rightarrow V$ function, and we derive:
 - a *diff* _S function
 - a non-deterministic $put: V \to S \to S$ function that lazily returns the "best" new sources

Scoreboard:

Future Work:

- + expressivness
- + updatability
- + properties
- efficiency

- automate the tool
- improve the reduction strategy for infinite search spaces (e.g. *filter*)
- improve diff