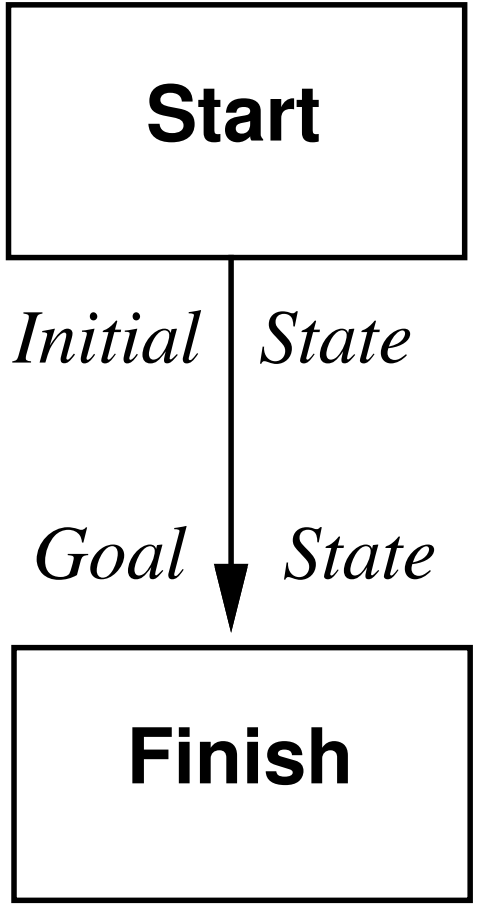
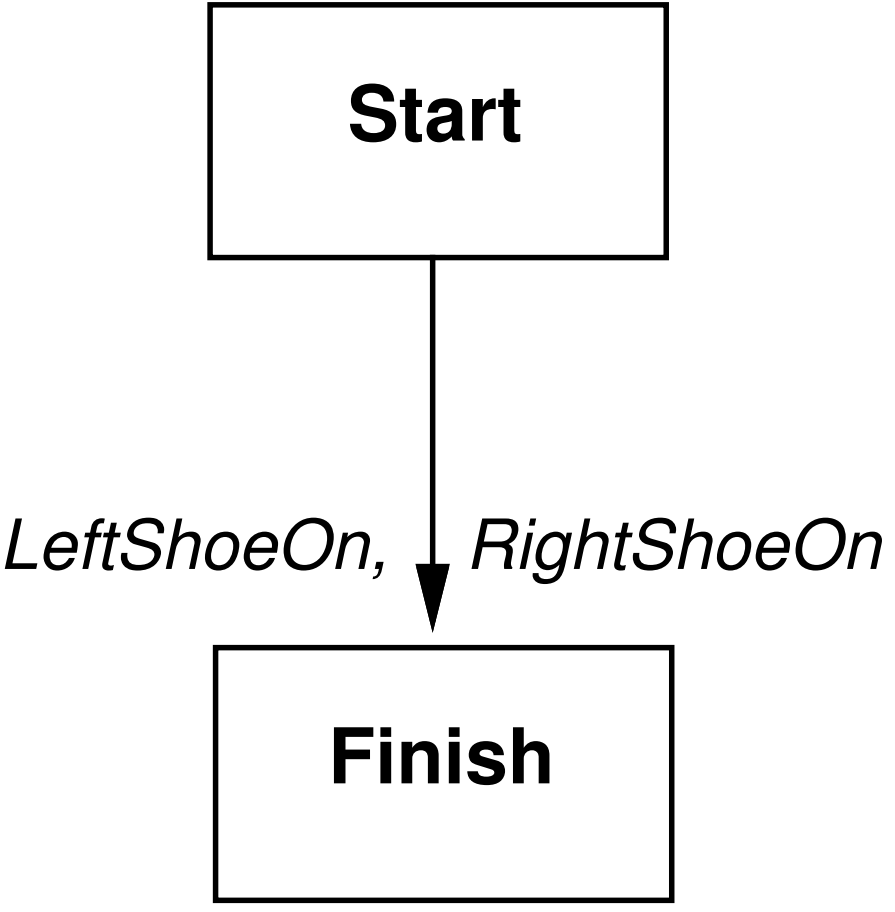

Start
Initial State
Goal State
Finish

(a)


Start
LeftShoeOn, RightShoeOn
Finish

(b)