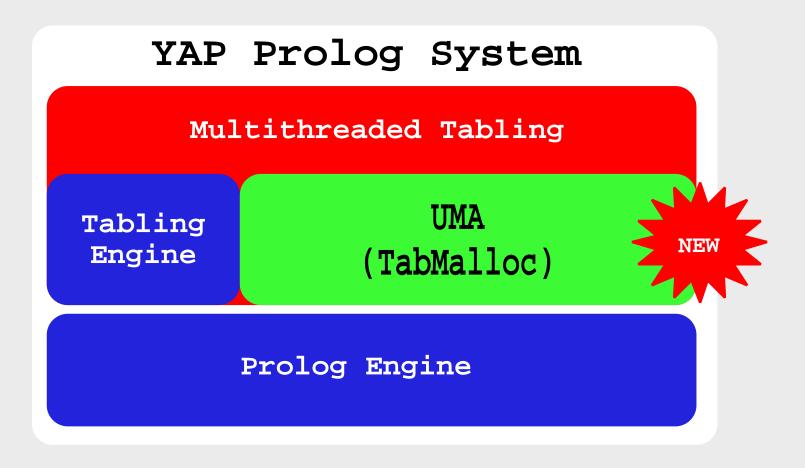
An Efficient and Scalable Memory Allocator for Multithreaded Tabled Evaluation of Logic Programs

Miguel Areias and Ricardo Rocha CRACS & INESC-TEC LA Faculty of Sciences, University of Porto, Portugal miguel-areias@dcc.fc.up.pt ricroc@dcc.fc.up.pt

ICPADS, Singapore, December 2012

Motivation of This Work

A New User Level Memory Allocator(UMA) aimed to improve the scalability of our Multithreaded Tabling engine.



Prolog Resolution

Prolog systems are known to have good performances and flexibility, but their standard resolution, limits the potential of the Logic Programing paradigm.

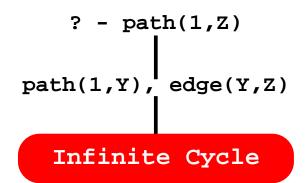
> Prolog resolution cannot deal properly with the following situations:

- Positive Infinite Cycles (insufficient expressiveness)
- Negative Infinite Cycles (inconsistency)
- Redundant Computations (inefficiency)

```
path(X,Z) :- path(X,Y), edge(Y,Z).
path(X,Z) :- edge(X,Z).
edge(1,2).
edge(2,1).
```

? - path(1,Z)

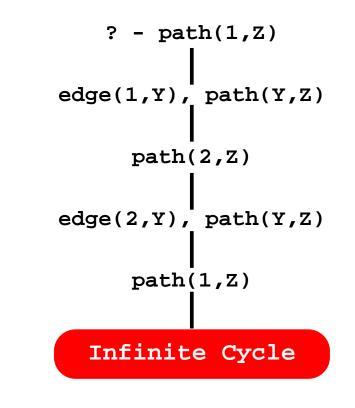
```
path(X,Z) :- path(X,Y), edge(Y,Z).
path(X,Z) :- edge(X,Z).
edge(1,2).
edge(2,1).
```



```
path(X,Z) :- edge(X,Y), path(Y,Z).
path(X,Z) :- edge(X,Z).
edge(1,2).
edge(2,1).
```

? - path(1,Z)

```
path(X,Z) :- edge(X,Y), path(Y,Z).
path(X,Z) :- edge(X,Z).
edge(1,2).
edge(2,1).
```



Tabling in Prolog Systems

Tabling is an implementation technique that overcomes some of the limitations of Prolog resolution.

- Tabled subgoals are evaluated by storing their answers in an appropriate data space, called the table space.
- Variant calls to tabled subgoals are resolved by consuming the answers already stored in the table instead of being re-evaluated against the program clauses.

Tabling in Prolog Systems

Tabling is an implementation technique that overcomes some of the limitations of Prolog resolution.

- Tabled subgoals are evaluated by storing their answers in an appropriate data space, called the table space.
- Variant calls to tabled subgoals are resolved by consuming the answers already stored in the table instead of being re-evaluated against the program clauses.

Implementations of Tabling are currently available in systems like:

- ♦ XSB Prolog
- Yap Prolog
- ♦ B-Prolog
- ♦ ALS-Prolog
- Mercury
- ♦ Ciao Prolog

Table Space - Overview

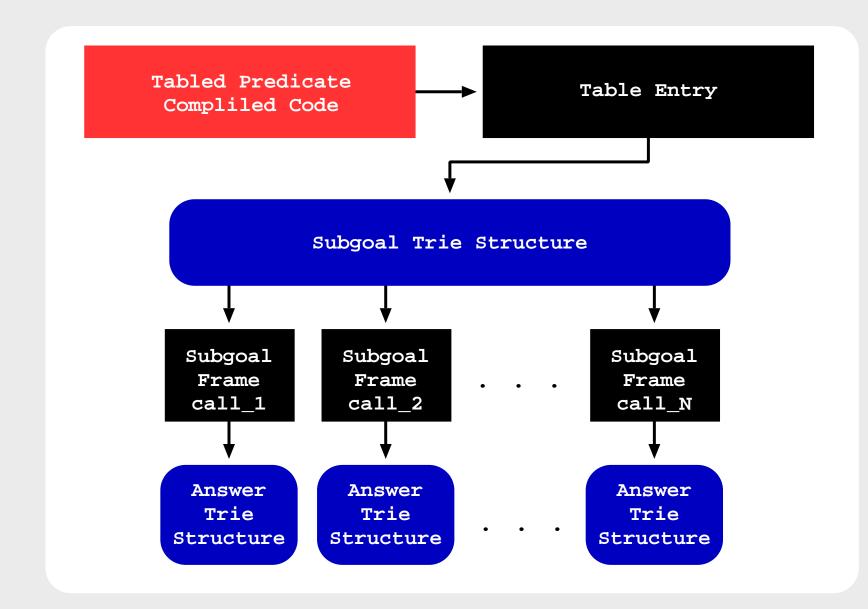


Table Space - Example

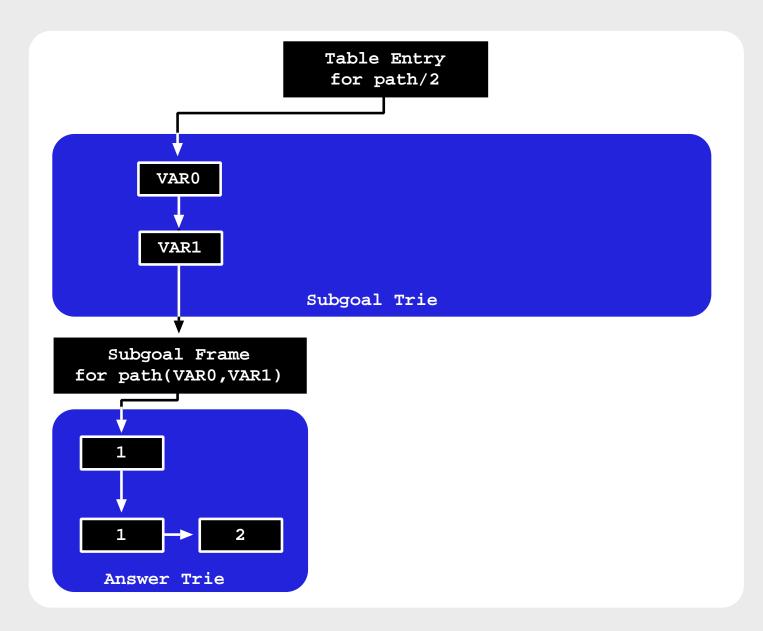
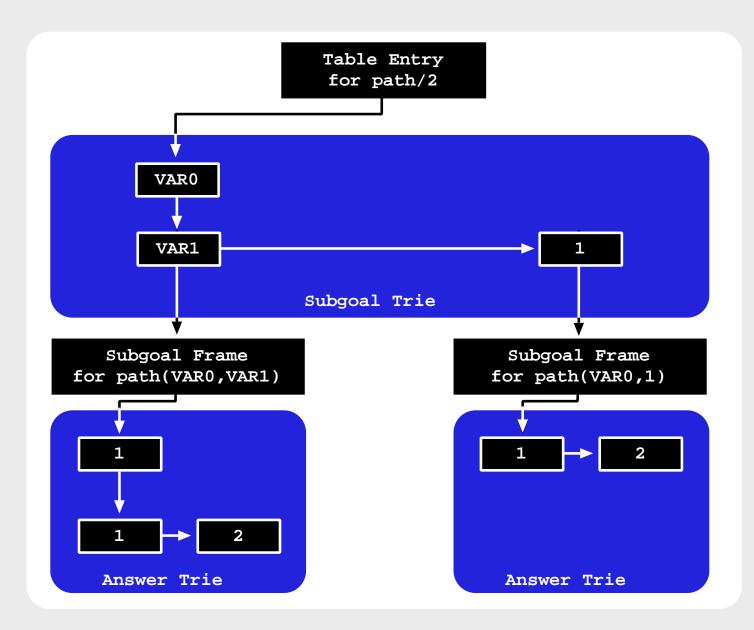


Table Space - Example



Multithreaded Tabling

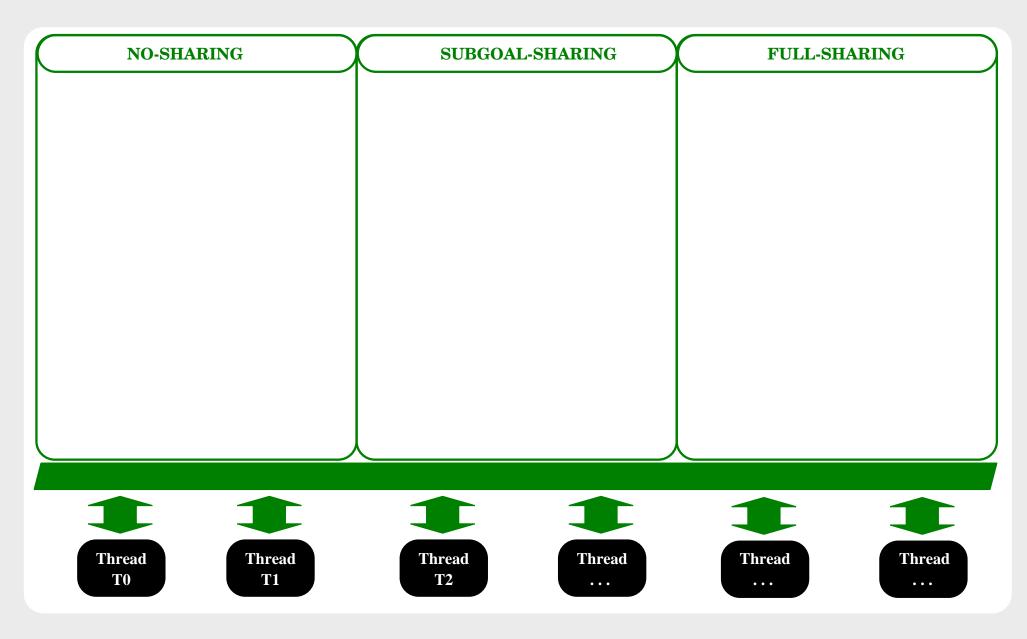
Multithreading in Prolog is the ability to concurrently perform computations, in which each computation runs independently but shares the program clauses.

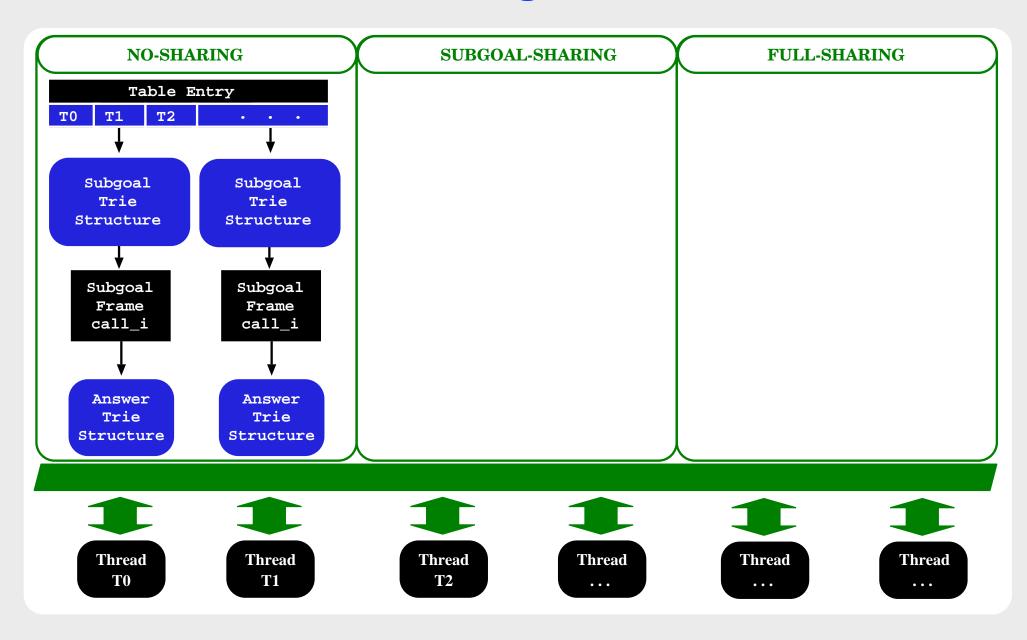
Multithreaded Tabling

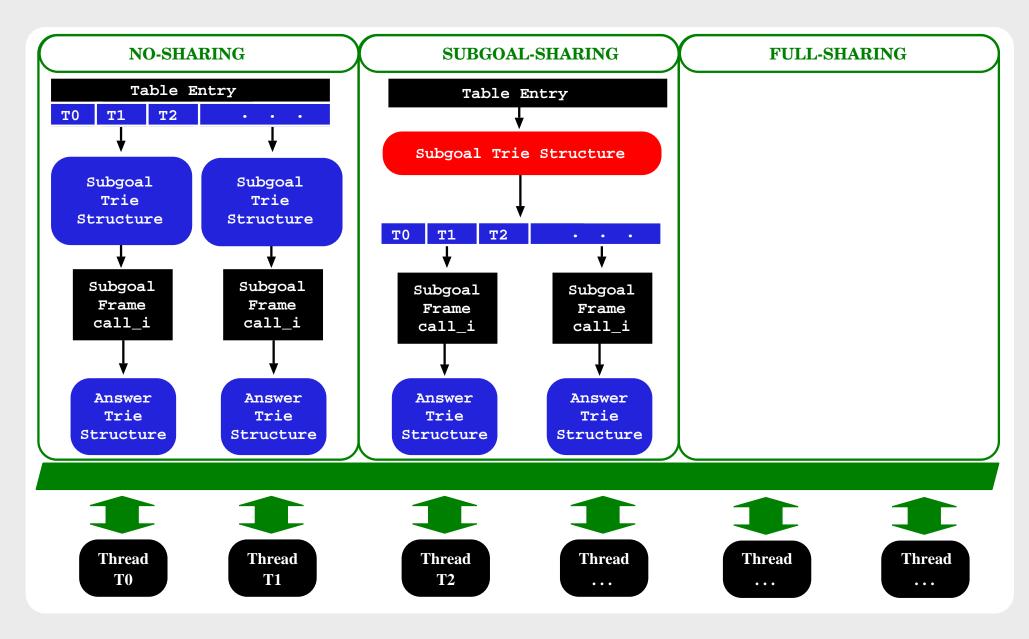
- Multithreading in Prolog is the ability to concurrently perform computations, in which each computation runs independently but shares the program clauses.
- ➤ When Multithreading is combined with Tabling, we have the best of both worlds, since we can exploit the combination of higher procedural control with higher declarative semantics.

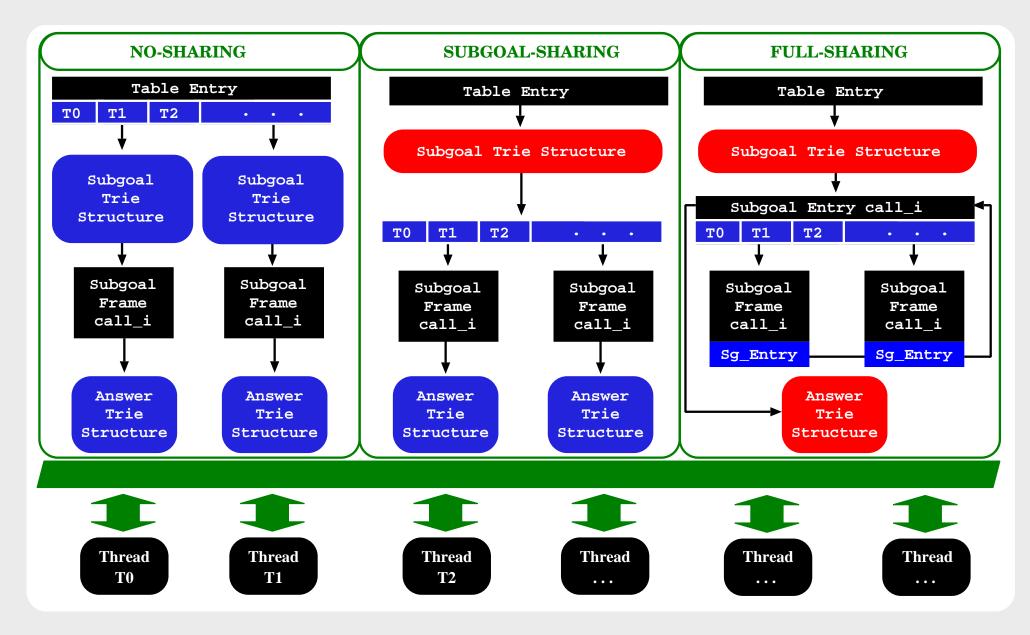
Multithreaded Tabling

- Multithreading in Prolog is the ability to concurrently perform computations, in which each computation runs independently but shares the program clauses.
- ➤ When Multithreading is combined with Tabling, we have the best of both worlds, since we can exploit the combination of higher procedural control with higher declarative semantics.
- Multithreading is currently supported by several well-known Prolog systems, but until now, XSB and Yap Prolog [ICLP 2012] were the only systems that were able to combine Multithreading with Tabling.
- In Yap Prolog, each thread views its tables as private but, at the engine level, Yap Prolog uses three different designs to support the table space.









User Level Memory Allocators - State-of-the-art

- A UMA is responsible for managing the Heap, which is an area of memory that is reserved for data.
- In a Multithreaded environment, all threads share the same Heap, thus the allocation and deallocation of objects on this area of memory must be performed concurrently.

User Level Memory Allocators - State-of-the-art

- A UMA is responsible for managing the Heap, which is an area of memory that is reserved for data.
- In a Multithreaded environment, all threads share the same Heap, thus the allocation and deallocation of objects on this area of memory must be performed concurrently.
- > Several Concurrent UMAs are currently available:
 - Hoard
 - PtMalloc
 - ♦ TcMalloc
 - ♦ JeMalloc
 - . . .

► Hoard:

- Multiple **Global** and **Local Heaps**.
- Per Heap locking.
- Emptiness groups and Blowup avoidance algorithm.

► Hoard:

- Multiple **Global** and **Local Heaps**.
- Per Heap locking.
- Emptiness groups and Blowup avoidance algorithm.

PtMalloc:

- Arenas with different **Bins** for small and large objects.
- Per Arena locking.
- Allocation/Deallocation of objects inside the same arena.

► Hoard:

- Multiple **Global** and **Local Heaps**.
- Per Heap locking.
- Emptiness groups and Blowup avoidance algorithm.

PtMalloc:

- Arenas with different **Bins** for small and large objects.
- Per Arena locking.
- Allocation/Deallocation of objects inside the same arena.

TcMalloc:

- Thread Cache used for small objects (\leq 32KB).
- Central Heap for large objects.
- Locking required when accessing the Central Heap.
- A garbage collection operation is done by a thread when a deallocation makes a Thread Cache bigger than a adjustable threshold.

► JeMalloc:

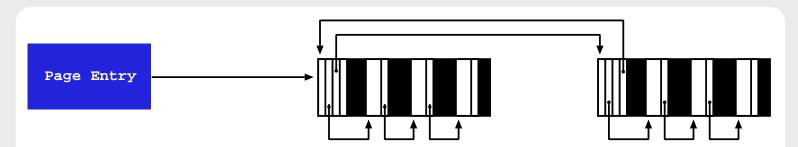
- Thread Cache used for small objects (\leq 32KB).
- Arenas with different **Bins** for small and large objects.
- Per **Bin locking** for small objects and/or per **Arena locking**.
- Allocation/Deallocation of objects inside the same Arena.
- Red-black trees improve Allocation/Deallocation of objects.

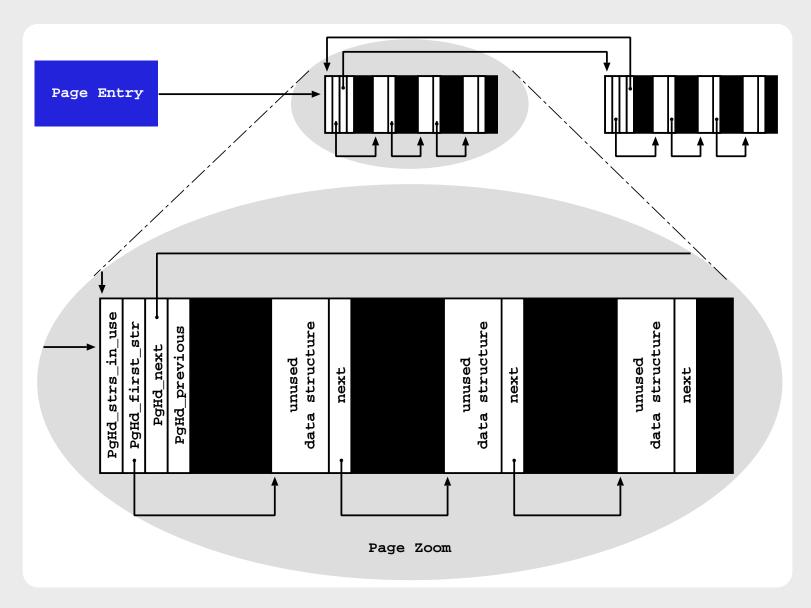
► JeMalloc:

- Thread Cache used for small objects (\leq 32KB).
- Arenas with different **Bins** for small and large objects.
- Per **Bin locking** for small objects and/or per **Arena locking**.
- Allocation/Deallocation of objects inside the same Arena.
- Red-black trees improve Allocation/Deallocation of objects.

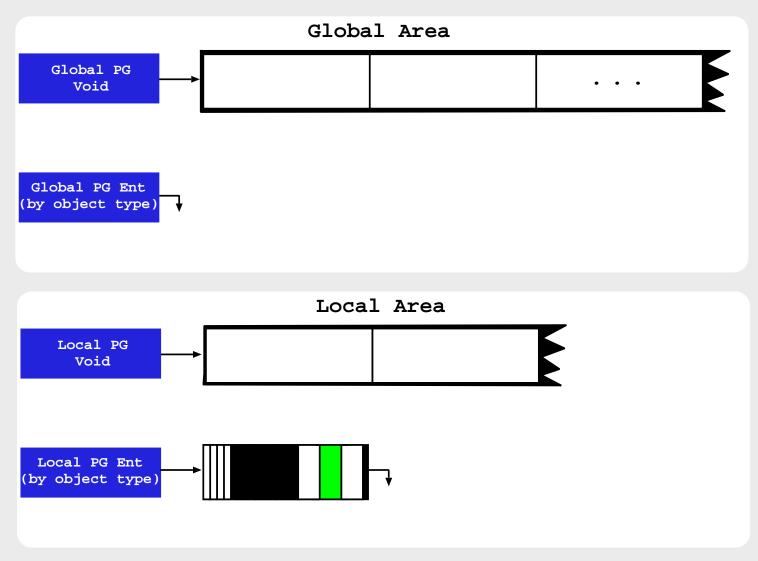
TabMalloc:

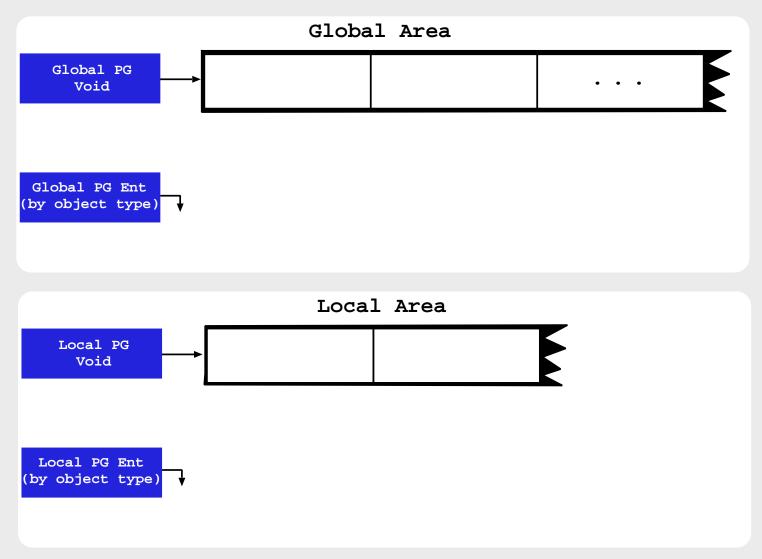
- Local and Global Page Heaps per object type.
- Global and Local Void Heaps for the allocation of objects when Local Page Heaps run empty.
- Per Global Heap locking.
- **Global Page Heaps** used for the deallocation of shared objects.
- Allocation/Deallocation of objects is always done via Local Page Heaps, except for the main thread that performs garbage collection on the Global Page Heaps.

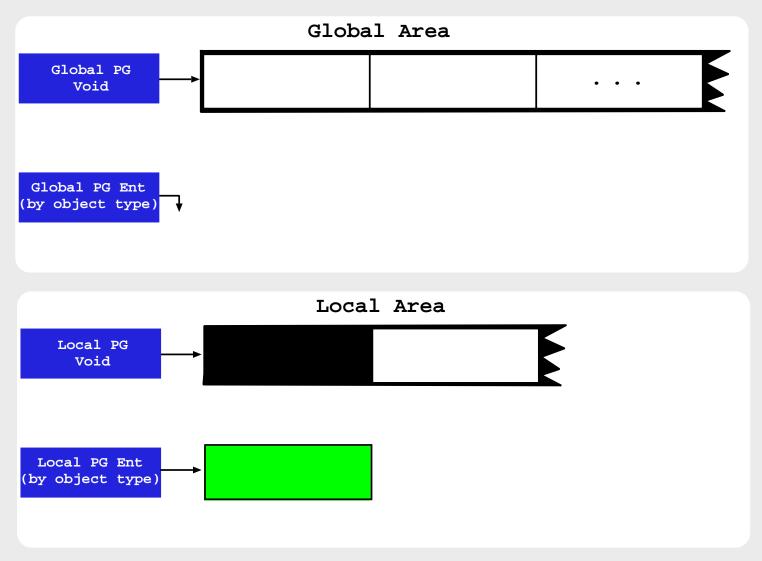


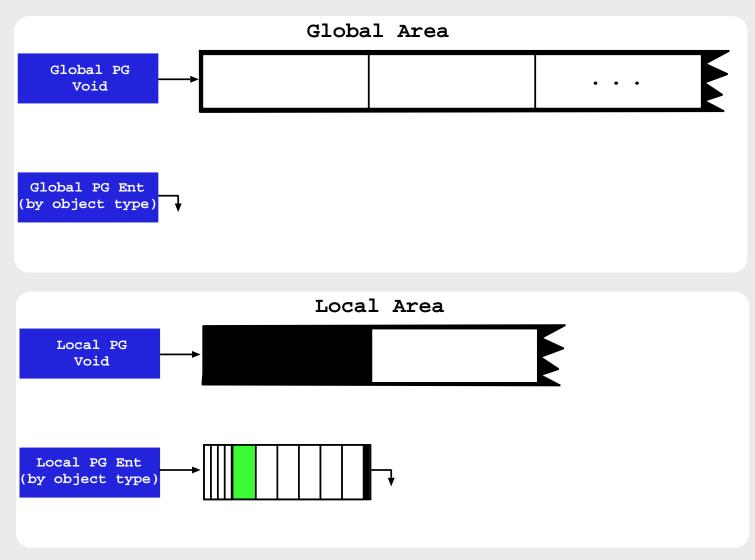


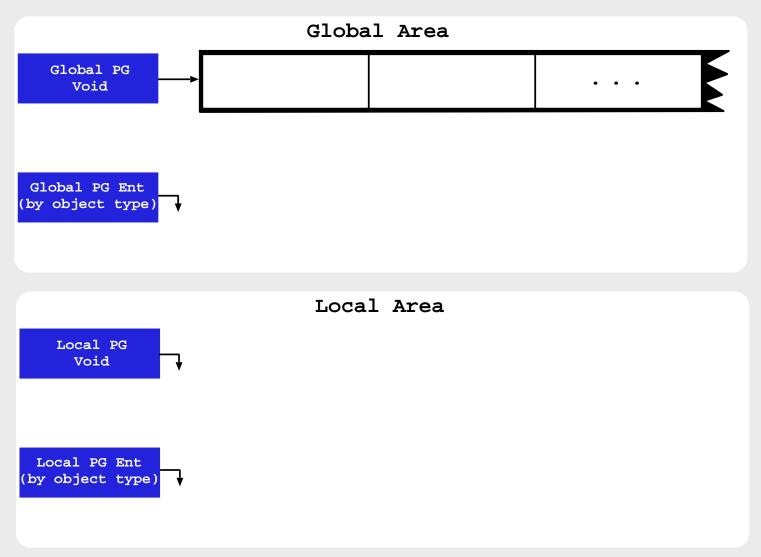
Case 1: Allocation of objects. Local Page Heap.

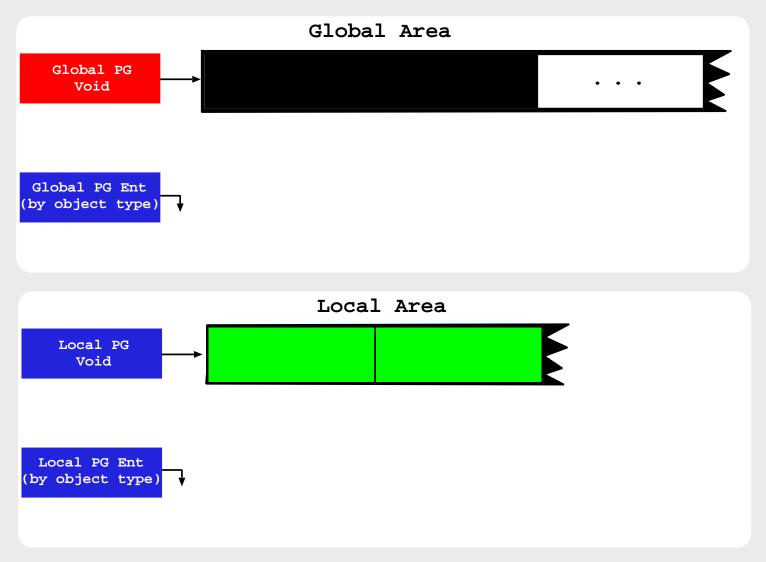




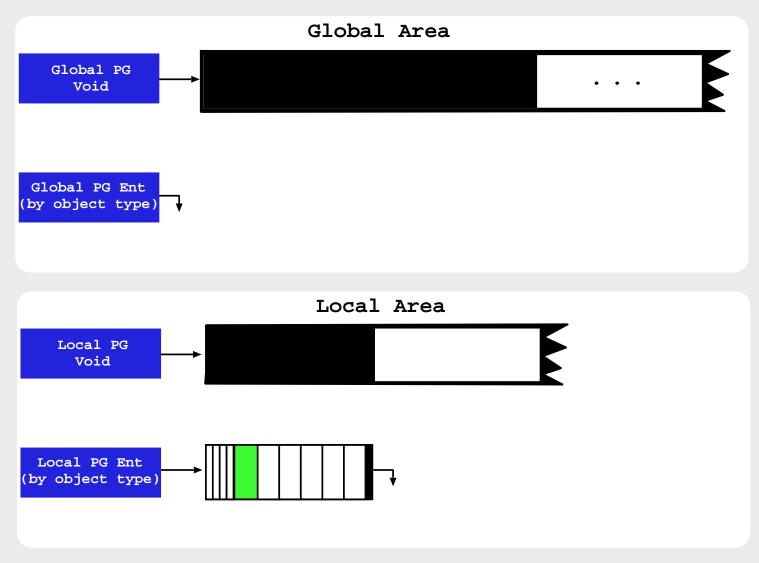


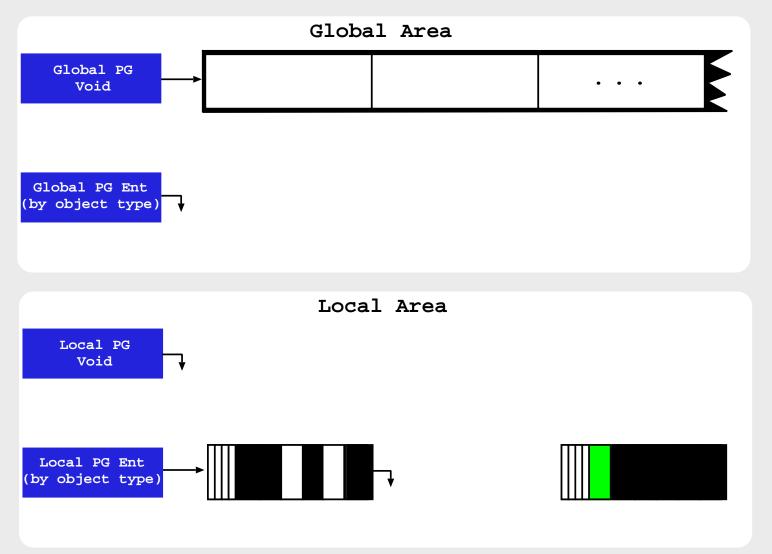


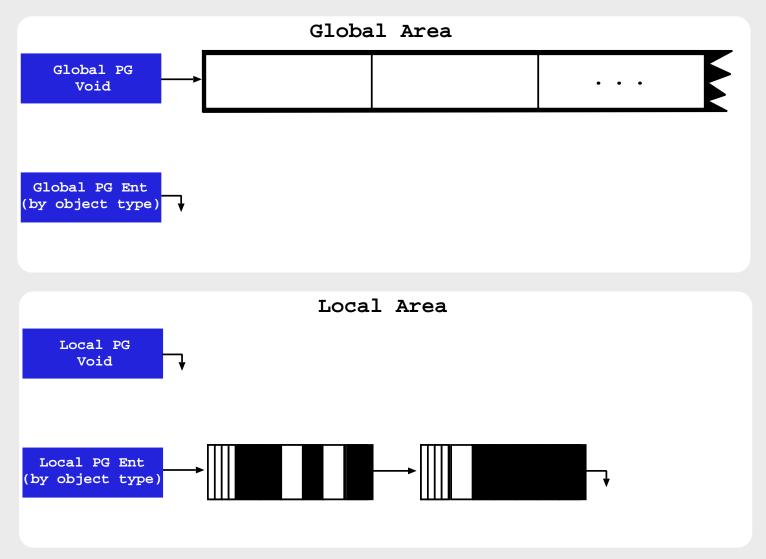


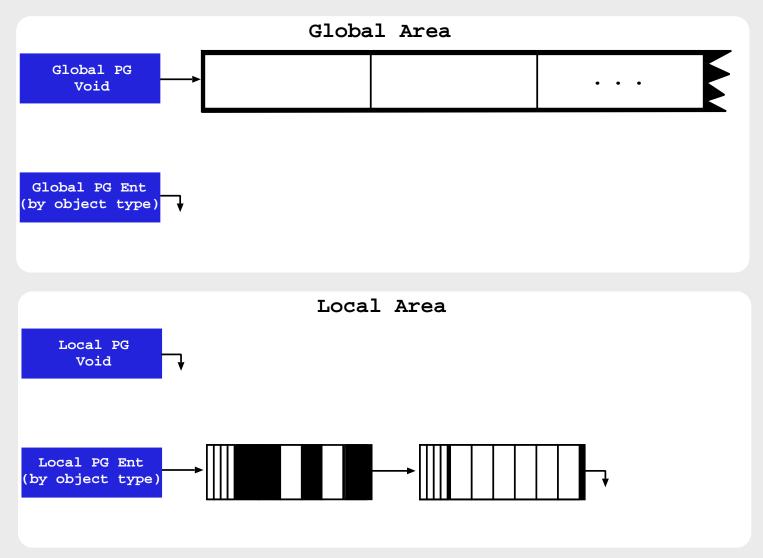


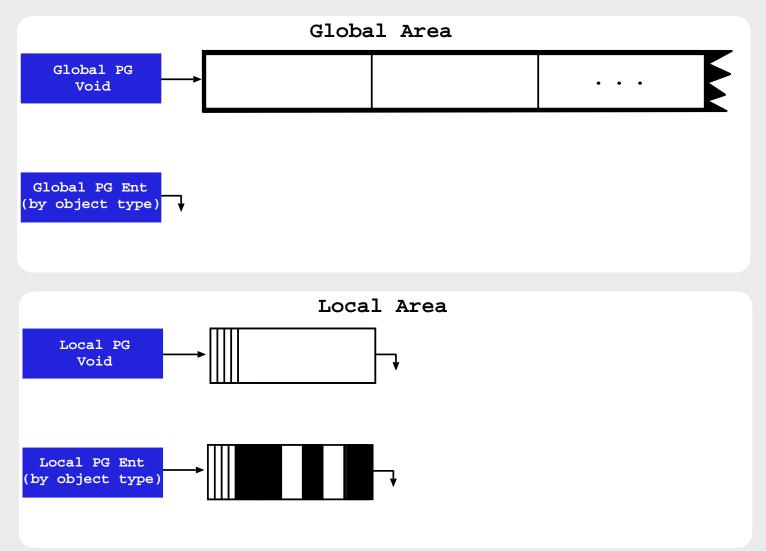
Case 3: **Allocation of objects**. Global Void Heap.

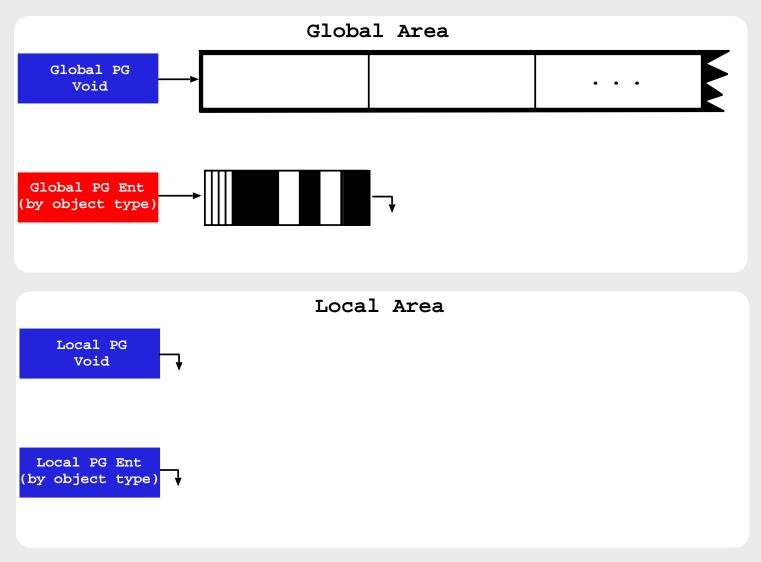










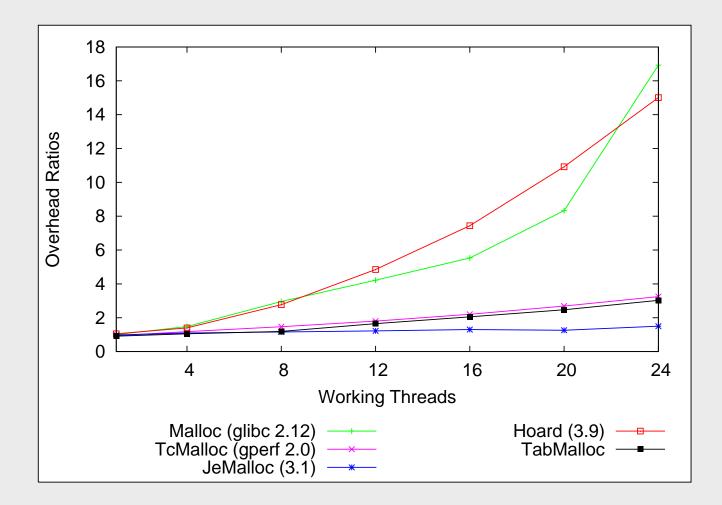


Experimental Results - Benchmark Statistics

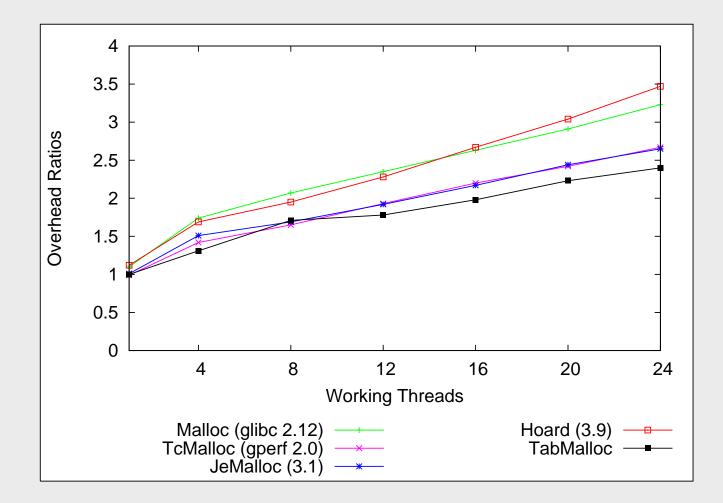
Bench -	Tabled Subgoals			Tabled Answers				Time (s)
	Calls	Trie Nodes	Trie Depth	Unique	Repeated	Trie Nodes	Trie Depth	NS
Model Checking								
IProto	1	6	5/5/5	134,361	385,423	1,554,896	4/51/67	2.4
Leader	1	5	4/4/4	1,728	574,786	41,788	15/80/97	3.7
Sieve	1	7	6/6/6	380	1,386,181	8,624	21/53/58	24.6
Large Joins								
Join2	1	6	5/5/5	2,476,099	0	2,613,660	5/5/5	3.7
Mondial	35	42	3/4/4	2,664	2,452,890	14,334	6/7/7	0.7
Path Left								
BTree	1	3	2/2/2	1,966,082	0	2,031,618	2/2/2	1.5
Pyramid	1	3	2/2/2	3,374,250	1,124,250	3,377,250	2/2/2	3.3
Cycle	1	3	2/2/2	4,000,000	2,000	4,002,001	2/2/2	4.0
Grid	1	3	2/2/2	1,500,625	4,335,135	1,501,851	2/2/2	1.9
Path Right								
BTree	131,071	262,143	2/2/2	3,801,094	0	3,997,700	1/2/2	2.3
Pyramid	3,000	6,001	2/2/2	6,745,501	2,247,001	6,751,500	1/2/2	2.7
Cycle	2,001	4,003	2/2/2	8,000,000	4,000	8,004,001	1/2/2	3.0
Grid	1,226	2,453	2/2/2	3,001,250	8,670,270	3,003,701	1/2/2	2.3

Characteristics Of The Benchmarks: 1 Working Thread

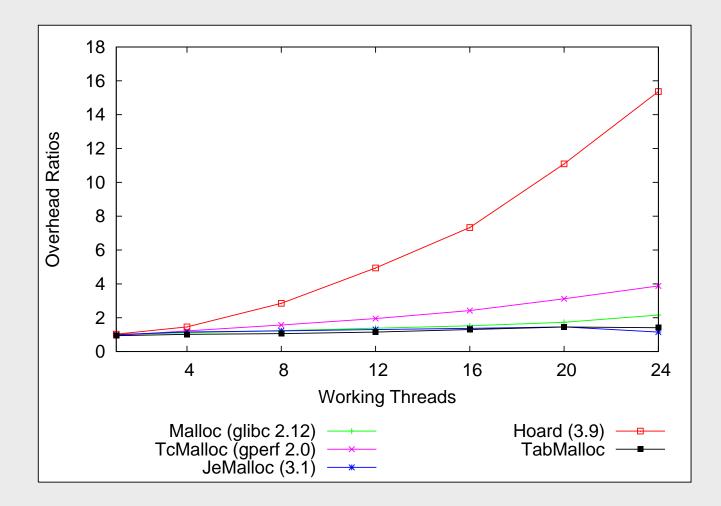
Experimental Results - First Runs (NS Design)



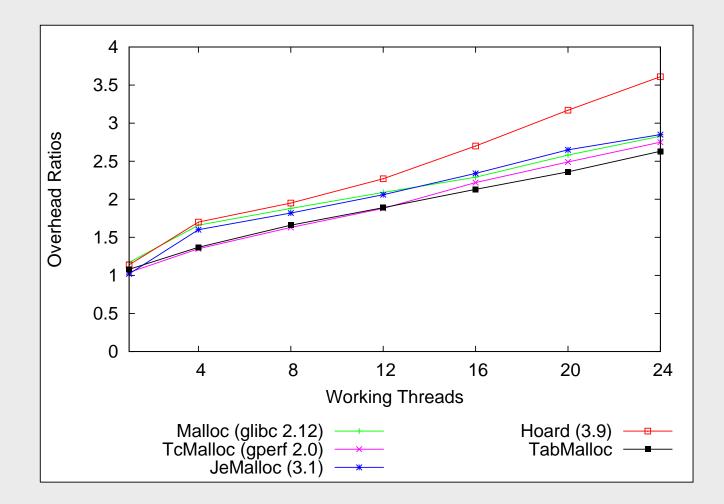
Experimental Results - First Runs (FS Design)



Experimental Results - Second Runs (NS Design)



Experimental Results - Second Runs (FS Design)



Conclusions

- We have presented a novel, efficient and scalable memory allocator for Multithreaded tabled evaluations of logic programs:
 - Has a page based mechanism, where data structures of the same type are allocated within a page.
 - Splits memory among specific data structures and different threads, by using a different Global and Local Heaps.

Conclusions

- We have presented a novel, efficient and scalable memory allocator for Multithreaded tabled evaluations of logic programs:
 - Has a page based mechanism, where data structures of the same type are allocated within a page.
 - Splits memory among specific data structures and different threads, by using a different Global and Local Heaps.
- Experimental results show a good performance in the running time, when compared with other state-of-the-art UMAs.
- > Further work will include following features:
 - Studying even further the alternative memory allocators.
 - Support for wait-free synchronization.

Thank You !!!

Miguel Areias and Ricardo Rocha CRACS & INESC-TEC LA University of Porto, Portugal miguel-areias@dcc.fc.up.pt ricroc@dcc.fc.up.pt

Yap Prolog : http://www.dcc.fc.up.pt/~vsc/Yap

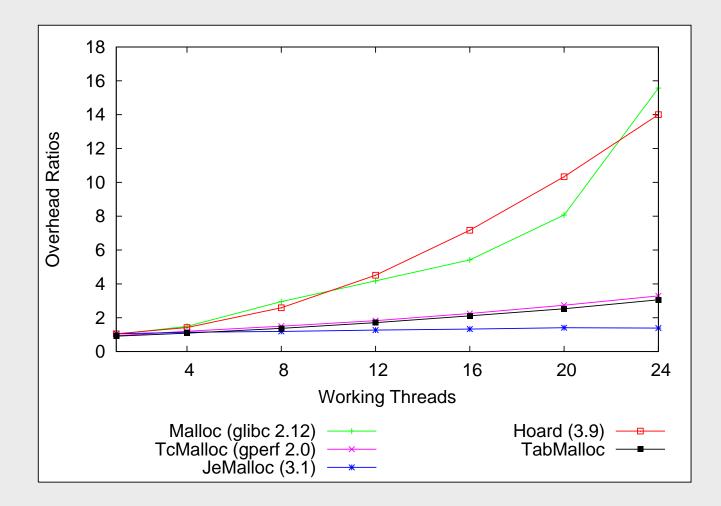
Projects LEAP and HORUS: *http://cracs.fc.up.pt/*



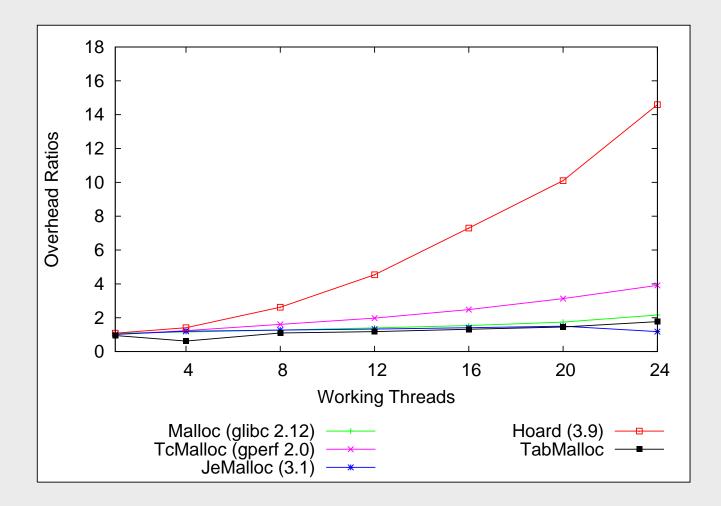




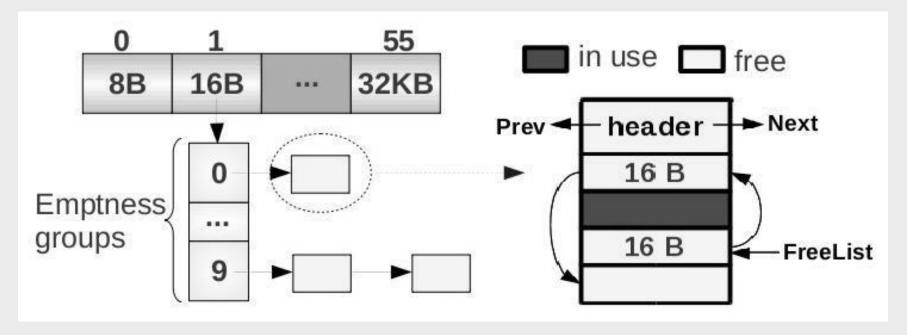
Experimental Results - First Runs (SS Design)



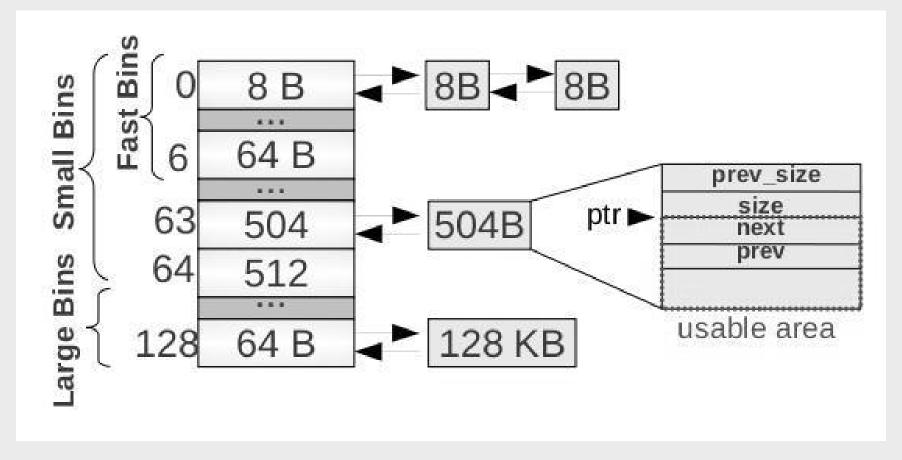
Experimental Results - Second Runs (SS Design)



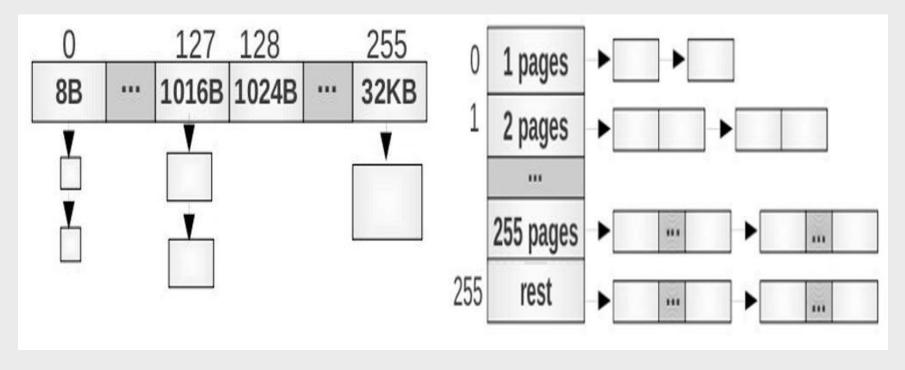
UMA - Hoard



UMA - PtMalloc



UMA - TcMalloc



UMA - JeMalloc

