

Program verification

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Program verification Lecture 5

Procedures

- Until now we consider a program as a sequence of commands
- The treatment of subroutines is challenging from the point of view of verification: procedures or functions)
- The treatment of procedures and functions includes the following aspects:
 - recursive calls (that can lead to non termination in the evaluation of expressions);
 - parameters;
- A program will be a set of procedures annotated with contracts.
- We will not consider here an operational semantics for procedures but assume that there exists one and the program logic will be adequate.
- We start with procedures without parameters.

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Procedures and Recursion

We suppose that procedures have no parameters.

- **proc** $p = C_p$ defines a procedure p ;
- the command C_p is the body of the procedure p (**body**(p));
- the new command **call** p invokes the procedure, transferring execution to the body of p ;
- A natural semantics rule could be:

$$\frac{\langle \mathbf{body}(p), s \rangle \longrightarrow s'}{\langle \mathbf{call} \ p, s \rangle \longrightarrow s'}$$

- for non recursive procedures the rule of Hoare logic is

$$\frac{\{\varphi\}\mathbf{body}(p)\{\psi\}}{\{\varphi\}\mathbf{call } p\{\psi\}}$$

Example

Consider the procedure

```

proc FACT =
  f ← 1;
  i ← 1;
  while i ≤ n do
    {f = fact(i - 1) and i ≤ n + 1}
    f ← f × i;
    i ← i + 1

```

By the correction of the body we have:

$$\{n \geq 0 \wedge n = n_0\}\mathbf{body}(\mathbf{FACT})\{f = \mathit{fact}(n) \wedge n = n_0\}$$

Allying the above rule we have:

$$\{n \geq 0 \wedge n = n_0\}\mathbf{call } \mathbf{FACT}\{f = \mathit{fact}(n) \wedge n = n_0\}$$

Adaptation

We can use the adapted consequence rule for sistem \mathcal{H}

$$\frac{\{\varphi\}C\{\psi\}}{\{\varphi'\}C\{\psi'\}} \text{ se } \varphi' \rightarrow \forall \bar{x}_f. (\forall \bar{y}_f. (\varphi[\bar{y}_f/\bar{y}] \rightarrow \psi[\bar{y}_f/\bar{y}, \bar{x}_f/\bar{x}]) \rightarrow \psi'[\bar{x}_f/\bar{x}])$$

to reuse the above deduction for a stronger precondition

$$\frac{\{n \geq 0 \wedge n = n_0\}\mathbf{call } \mathbf{FACT}\{f = \mathit{fact}(n) \wedge n = n_0\}}{\{n = 10\}\mathbf{call } \mathbf{FACT}\{f = \mathit{fact}(10)\}}$$

and we obtain the side condition

$$n = 10 \rightarrow \forall n_f, f_f. ((\forall n_{0f}. n \geq 0 \wedge n = n_{0f} \rightarrow f_f = \mathit{fact}(n_f) \wedge n_f = n_{0f}) \rightarrow f_f = \mathit{fact}(10))$$

For the system \mathcal{H}_g this is not possible because it lacks a consequence rule, but we may have a specific rule to dela with recursive procedures.

Notation $\tilde{}$

In practice specification languages avoid the generality allowed by auxiliary variables and forbid their use in the procedure specifications.

Given a variable x we denote \tilde{x} its value in the prestate.

For the previous example we have

$$\{n \geq 0\} \mathbf{call} \text{ FACT} \{f = \mathit{fact}(n) \wedge n = \tilde{n}\}$$

The new consequence rule is

$$\frac{\{\varphi\}C\{\psi\}}{\{\varphi'\}C\{\psi'\}} \text{ se } \varphi' \rightarrow \forall \overline{x_f}. ((\varphi \rightarrow \lfloor \psi[\overline{x_f}/\overline{x}] \rfloor) \rightarrow \psi'[\overline{x_f}/\overline{x}])$$

and $\lfloor \psi[\overline{x_f}/\overline{x}] \rfloor$ denotes the result of substituting in $\psi[\overline{x_f}/\overline{x}]$ every variable \tilde{x} by the corresponding x .

The triple can be derived by

$$\frac{\{n \geq 0\} \mathbf{call} \text{ FACT} \{f = \mathit{fact}(n) \wedge n = \tilde{n}\}}{\{n = 10\} \mathbf{call} \text{ FACT} \{f = \mathit{fact}(10)\}}$$

and we obtain the side condition

$$n = 10 \rightarrow \forall n_f, f_f. ((n \geq 0 \rightarrow f_f = \mathit{fact}(n_f) \wedge n_f = n) \rightarrow f_f = \mathit{fact}(10))$$

To derive the triple with \tilde{x} one needs to modify call rule as follows

$$\frac{\{\varphi \wedge x = x_1 \tilde{} \wedge \dots \wedge x_n = x_n \tilde{}\} \mathbf{body}(p)\{\psi\}}{\{\varphi'\} \mathbf{call} p\{\psi'\}}$$

where x_1, \dots, x_n are the program variables

Recursive procedures

- In recursive procedures, $\mathbf{body}(p)$ can contain commands $\mathbf{call} p$
- The application of the rule for procedures given above can lead to infinite derivations.
- The following rule was proposed by Hoare

$$\frac{\begin{array}{c} \{\varphi\} \mathbf{call} p\{\psi\} \\ \vdots \\ \{\varphi\} \mathbf{body}(p)\{\psi\} \end{array}}{\{\varphi\} \mathbf{call} p\{\psi\}}$$

Assuming $\{\varphi\}\mathbf{call} p\{\psi\}$ we can derive $\{\varphi\}\mathbf{body}(p)\{\psi\}$, then $\{\varphi\}\mathbf{call} p\{\psi\}$ can be derived without hypotheses (and that is why the hypothesis had square brackets).

- It is an axiomatic counterpart of fixpoint induction.

Example

Consider the procedure

```

proc FACTR =
  if  $n == 0$  then
     $f \leftarrow 1$ 
  else
     $n \leftarrow n - 1$ ;
    call FACTR;
     $n \leftarrow n + 1$ ;
     $f \leftarrow n \times f$ 

```

then

$$\{n \geq 0 \wedge n = n_0\}\mathbf{call} \text{FACTR}\{f = \text{fact}(n) \wedge n = n_0\}$$

can be derived using the adapted consequence rule.

Procedure calls in \mathcal{H}_g

In this case the side conditions of the rule for procedures should include an adaptation condition

$$\frac{\{\varphi\}\mathbf{body}(p)\{\psi\}}{\{\varphi'\}\mathbf{call} p\{\psi'\}} \text{ if } \varphi' \rightarrow \forall \bar{x}_f. (\forall \bar{y}_f. \varphi[\bar{y}_f/\bar{y}] \rightarrow \psi[\bar{y}_f/\bar{y}, \bar{x}_f/\bar{x}]) \rightarrow \psi'[\bar{x}_f/\bar{x}]$$

where \bar{y} are the auxiliary variables of $\{\varphi\}\mathbf{body}(p)\{\psi\}$, \bar{x} are the program variables of $\mathbf{body}(p)$, and \bar{y}_f, \bar{x}_f fresh. The idea of the rule is that the body of p is proved correct with respect to (φ, ψ) , then this specification should be strong enough to adapt the procedure to weaker specifications.

[AFPMdS11] Chap. 8.1

References

- [AFPMdS11] José Bacelar Almeida, Maria João Frade, Jorge Sousa Pinto, and Simão Melo de Sousa. *Rigorous Software Development: An Introduction to Program Verification*. Springer, 2011.