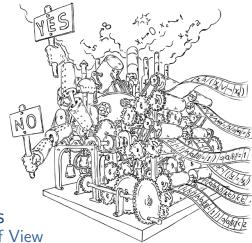
Bit-Vectors

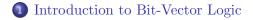
Chapter 6



Decision Procedures An Algorithmic Point of View

D.Kroening O.Strichman

Revision 1.2



2 Syntax



- Decision procedures for Bit-Vector Logic
 Flattening Bit-Vector Logic
 Incremental Elattening
 - Incremental Flattening

Bit-Vector Logic: Syntax

- $formula : formula \lor formula \mid \neg formula \mid atom$
 - atom : term rel term | Boolean-Identifier | term [constant]

$$rel$$
 : = $|$ <

 $\begin{array}{rcl}term & : & term \ op \ term \ | \ identifier \ | \ \sim term \ | \ constant \ | \\ & atom?term:term \ | \\ & term[\ constant : \ constant \] \ | \ ext(\ term \) \\ & op \ : \ + \ | \ - \ | \ \cdot \ | \ / \ | \ \ll \ | \ >> \ | \ \& \ | \ | \ \oplus \ | \ \circ \end{array}$

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- $\sim x$: bit-wise negation of x
- ext(x): sign- or zero-extension of x
- x << d: left shift with distance d
- $x \circ y$: concatenation of x and y

Danger!

$(x-y>0)\iff (x>y)$

Valid over \mathbb{R}/\mathbb{N} , but not over the bit-vectors. (Many compilers have this sort of bug)



• The meaning depends on the width and encoding of the variables.

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- Typical encodings:
 - Binary encoding

$$\langle x \rangle_U := \sum_{i=0}^{l-1} a_i \cdot 2^i$$

• Two's complement

$$\langle x \rangle_S := -2^{n-1} \cdot a_{n-1} + \sum_{i=0}^{l-2} a_i \cdot 2^i$$

• But maybe also fixed-point, floating-point, ...

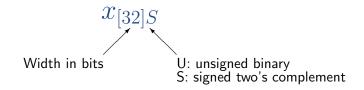
$$\langle 11001000 \rangle_U = 200$$

 $\langle 11001000 \rangle_S = -128 + 64 + 8 = -56$
 $\langle 01100100 \rangle_S = 100$

Notation to clarify width and encoding:

 $x_{[32]S}$

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Definition (Bit-Vector)

A *bit-vector* is a vector of Boolean values with a given length *l*:

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The value of bit number i of x is x(i).

We also write x_i for x(i).

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Examples:

• The vector of length *l* that consists of zeros:

 $\lambda i \in \{0, \dots, l-1\}.0$

• A function that inverts (flips all bits in) a bit-vector: $bv\text{-}invert(x) := \lambda i \in \{0, \dots, l-1\}. \neg x_i$

• A bit-wise OR:

$$bv \text{-} or(x, y) := \lambda i \in \{0, \dots, l-1\}.(x_i \lor y_i)$$

 \implies we now have semantics for the bit-wise operators.

Decision Procedures - Bit-Vectors

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• Final result:

$$(\lambda i.(i < 5)?y_i : x_{i-5})(14) \iff x_9$$

Decision Procedures - Bit-Vectors

What is the output of the following program?

```
unsigned char number = 200;
number = number + 100;
printf("Sum: %d\n", number);
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 \implies Bit-vector arithmetic uses modular arithmetic!

Semantics for addition, subtraction:

$$\begin{aligned} a_{[l]} +_U b_{[l]} &= c_{[l]} & \iff \quad \langle a \rangle_U + \langle b \rangle_U &= \langle c \rangle_U \mod 2^l \\ a_{[l]} -_U b_{[l]} &= c_{[l]} & \iff \quad \langle a \rangle_U - \langle b \rangle_U &= \langle c \rangle_U \mod 2^l \end{aligned}$$

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We can even mix the encodings:

$$a_{[l]U} +_U b_{[l]S} = c_{[l]U} \iff \langle a \rangle_U + \langle b \rangle_S = \langle c \rangle_U \mod 2^d$$

Semantics for <, \leq , \geq , and so on:

$$\begin{array}{lll} a_{[l]U} < b_{[l]U} & \Longleftrightarrow & \langle a \rangle_U < \langle b \rangle_U \\ a_{[l]S} < b_{[l]S} & \Longleftrightarrow & \langle a \rangle_S < \langle b \rangle_S \end{array}$$

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Mixed encodings:

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Note that most compilers don't support comparisons with mixed encodings.

• Satisfiability is undecidable for an unbounded width, even without arithmetic.

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• It is NP-complete otherwise.

A Simple Decision Procedure

- Transform Bit-Vector Logic to Propositional Logic
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Bit-Vector Flattening

- Convert propositional part as before
- Add a Boolean variable for each bit of each sub-expression (term)
- 3 Add constraint for each sub-expression

We denote the new Boolean variable for bit i of term t by $\mu(t)_i$.

Algorithm 6.2.1: BV-FLATTENING Input: A formula φ in bit-vector arithmetic **Output:** An equisatisfiable Boolean formula \mathcal{B} 1. function **BV-FLATTENING** 2. $\mathcal{B}:=e(\varphi);$ \triangleright the propositional skeleton of φ for each $t_{[l]} \in T(\varphi)$ do 3. for each $i \in \{0, ..., l-1\}$ do 4. set $e(t)_i$ to a new Boolean variable; 5.6. for each $a \in At(\varphi)$ do 7. $\mathcal{B}:=\mathcal{B}\wedge \text{BV-CONSTRAINT}(e,a);$ 8. for each $t_{[l]} \in T(\varphi)$ do $\mathcal{B}:=\mathcal{B}\wedge \text{BV-CONSTRAINT}(e,t);$ 9. 10. return \mathcal{B} :

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- This is easy for the bit-wise operators.
- Example for $a|_{[l]}b$:

$$\bigwedge_{i=0}^{l-1} (\mu(t)_i = (a_i \lor b_i))$$

(read x = y over bits as $x \iff y$)

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• We can transform this into CNF using Tseitin's method.

How to flatten a + b?

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→ we can build a *circuit* that adds them!

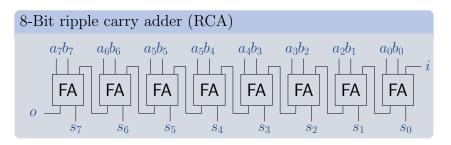
 $a \ b \ i$ Full Adder FA $s \equiv (a+b+i) \mod 2 \equiv a \oplus b \oplus i$ $o \equiv (a+b+i) \operatorname{div} 2 \equiv a \cdot b + a \cdot i + b \cdot i$

The full adder in CNF:

 $\begin{array}{l} (a \lor b \lor \neg o) \land (a \lor \neg b \lor i \lor \neg o) \land (a \lor \neg b \lor \neg i \lor o) \land \\ (\neg a \lor b \lor i \lor \neg o) \land (\neg a \lor b \lor \neg i \lor o) \land (\neg a \lor \neg b \lor o) \end{array}$

Ok, this is good for one bit! How about more?

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- Also called carry chain adder
- Adds *l* variables
- Adds $6 \cdot l$ clauses

- Multipliers result in very hard formulas
- Example:

$$a \cdot b = c \land b \cdot a \neq c \land x < y \land x > y$$

CNF: About 11000 variables, unsolvable for current SAT solvers

- Similar problems with division, modulo
- Q: Why is this hard?

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- Example:

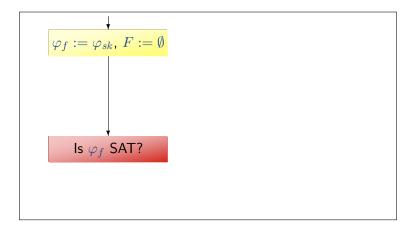
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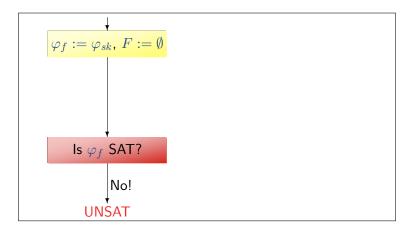
- Similar problems with division, modulo
- Q: Why is this hard?
- Q: How do we fix this?

$$\varphi_f := \varphi_{sk}, \ F := \emptyset$$

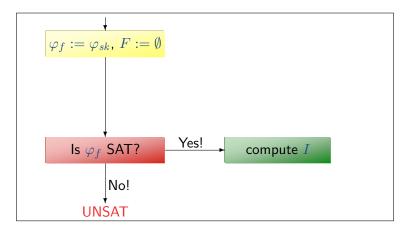
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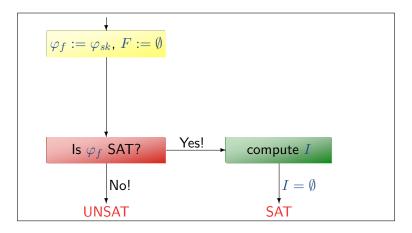


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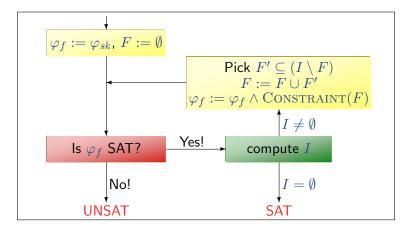
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• Idea: add 'easy' parts of the formula first

• Only add hard parts when needed

• φ_f only gets stronger – use an incremental SAT solver

Hey: initially, we only have the skeleton!
 How do we know what terms are inconsistent with the current assignment if the variables aren't even in φ_f?

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 How do we know what terms are inconsistent with the current assignment if the variables aren't even in φ_f?
- Solution: guess some values for the missing variables. If you guess right, it's good.

Algorithm 6.3.1: INCREMENTAL-BV-FLATTENING
$\begin{array}{llllllllllllllllllllllllllllllllllll$
1. function Incremental-BV-Flattening(φ)
2. $\mathcal{B} := e(\varphi);$ \triangleright propositional skeleton of φ
3. for each $t_{[l]} \in T(\varphi)$ do
4. for each $i \in \{0, \ldots, l-1\}$ do
5. set $e(t)_i$ to a new Boolean variable;
6. while $(TRUE)$ do
7. $\alpha := \text{SAT-SOLVER}(\mathcal{B});$
8. if α ="Unsatisfiable" then
9. return "Unsatisfiable";
10. else
11. Let $I \subseteq T(\varphi)$ be the set of terms that are inconsistent with the
satisfying assignment;
12. if $I = \emptyset$ then
13. return "Satisfiable";
14. else
15. Select "easy" $F' \subseteq I$;
16. for each $t_{[l]} \in F'$ do
17. $\mathcal{B}:=\mathcal{B} \land \text{BV-CONSTRAINT}(e,t);$

- Hey: initially, we only have the skeleton!
 How do we know what terms are inconsistent with the current assignment if the variables aren't even in φ_f?
- Solution: guess some values for the missing variables. If you guess right, it's good.
- Ideas:
 - All zeros
 - Sign extension for signed bit-vectors
 - Try to propagate constants (a = b + 1)