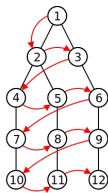


# Graphs: Breadth-First Search (BFS)

L.EIC

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P Ribeiro, AP Tomas

# Breadth-First Search - BFS

- A **breadth-first search (BFS)** is very similar to a DFS. Essentially, it only changes the **order** in which the nodes are visited!
- Instead of using recursion (and its *stack*), we will explicitly keep a **queue** of unvisited nodes ( $q$ )

**Backbone of a BFS - time:  $\mathcal{O}(|V| + |E|)$  (adj. list)**

**bfs(node  $v$ ):**

$q \leftarrow \emptyset$  /\* queue of unvisited nodes \*/

$q.enqueue(v)$

mark  $v$  as visited /\* all other nodes should initially be unvisited \*/

**While**  $q \neq \emptyset$  /\* while there are still unprocessed nodes \*/

$u \leftarrow q.dequeue()$  /\* remove first element of  $q$  \*/

**For** all neighbors  $w$  of  $u$  **do**

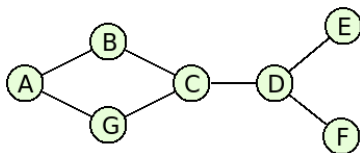
**If**  $w$  has not yet been visited **then** /\* new node! \*/

$q.enqueue(w)$

        mark  $w$  as visited

# Breadth-First Search - BFS

- Here is a graph and an illustration of a BFS starting on node A:



- Initially we have  $q = \{A\}$
- We visit and remove A, adding its unvisited neighbors ( $q = \{B, G\}$ )
- We visit and remove B, adding its unvisited neighbors ( $q = \{G, C\}$ )
- We visit and remove G, adding its unvisited neighbors ( $q = \{C\}$ )
- We visit and remove C, adding its unvisited neighbors ( $q = \{D\}$ )
- We visit and remove D, adding its unvisited neighbors ( $q = \{E, F\}$ )
- We visit and remove E, adding its unvisited neighbors ( $q = \{F\}$ )
- We visit and remove F, adding its unvisited neighbors ( $q = \{\}$ )
- $q$  empty, we finished our BFS

# BFS: Implementation

- Let's see a possible implementation with some *livecoding*

```
void bfs(int v) {  
    // initialize all nodes as unvisited  
    for (int v=1; v<=n; v++) nodes[v].visited = false;  
    queue<int> q; // queue of unvisited nodes  
    q.push(v);  
    nodes[v].visited = true;  
    while (!q.empty()) { // while there are still unprocessed nodes  
        int u = q.front(); q.pop(); // remove first element of q  
        cout << u << " "; // show node order  
        for (auto e : nodes[u].adj) {  
            int w = e.dest;  
            if (!nodes[w].visited) { // new node!  
                q.push(w);  
                nodes[w].visited = true;  
            }  
        }  
    }  
}
```

# BFS: Implementation

- Example execution (assuming graph  $g$  was already created)

```
g.bfs(1);
```

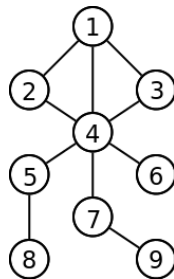
```
1 2 3 4 5 6 7 8 9
```

```
g.bfs(9);
```

```
9 7 4 1 2 3 5 6 8
```

```
g.bfs(5);
```

```
5 4 8 1 2 3 6 7 9
```



# BFS: Computing distances

- Almost everything than can be done with DFS can also be done with BFS!
- An important difference is that with BFS we visit the nodes in **increasing order of distance** (in terms of number of edges) to the initial node!
- In this way, BFS can be used to compute **shortest distances** between nodes on an **unweighted graph** (with or without direction).
- Let's see what really changes in the code

# BFS: Computing distances

- In red the lines that were added.  
*node.distance* stores the distance to *node*.

## BFS - Computing distances

**bfs**(node *v*):

*q*  $\leftarrow \emptyset$  /\* Queue of unvisited nodes \*/

*q.enqueue*(*v*)

*v.distance*  $\leftarrow 0$  /\* distance from *v* to itself it's zero \*/

mark *v* as visited /\* all other nodes should initially be unvisited \*/

**While** *q*  $\neq \emptyset$  /\* while there are still unprocessed nodes \*/

*u*  $\leftarrow q.dequeue()$  /\* remove first element of *q* \*/

**For** all neighbors *w* of *u* **do**

**If** *w* has not yet been visited **then** /\* new node \*/

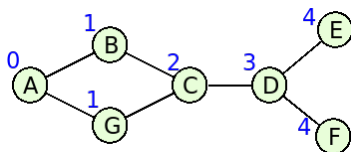
*q.enqueue*(*w*)

            mark *w* as visited

*w.distance*  $\leftarrow u.distance + 1$

# BFS example with distances

- Here is an illustration of a BFS (with distances) starting on node A:



- Initially we have  $q = \{A\}$  and  $A.distance = 0$
- We visit A, adding its neighbors ( $q = \{B, G\}$ ;  $B.distance = G.distance = 1$ )
- We visit B, adding its neighbors ( $q = \{G, C\}$ ;  $C.distance = 2$ )
- We visit G, adding its neighbors ( $q = \{C\}$ )
- We visit C, adding its neighbors ( $q = \{D\}$ ;  $D.distance = 3$ )
- We visit D, adding its neighbors ( $q = \{E, F\}$ ;  $E.distance = F.distance = 4$ )
- We visit E, adding its neighbors ( $q = \{F\}$ )
- We visit F, adding its neighbors ( $q = \{\}$ )
- $q$  empty, we finished our BFS



# BFS: Computing paths

- What if we want to **report the path** to reach a node with distance?
- We could simply store for each node  $v$  its "predecessor" ( $pred$ ), or the node that added  $v$  to the queue
- In this way, a path can be reconstructed by following the predecessor of the target node to get the path in inverse direction:  
**path to node  $v$ :**  $\dots \rightarrow pred(pred(pred(v))) \rightarrow pred(pred(v)) \rightarrow pred(v) \rightarrow v$
- Let's see what would change in the code

# BFS: Computing paths

- Added lines in red. *node.pred* stores its predecessor.

## BFS - Computing distances

**bfs**(node *v*):

*q*  $\leftarrow \emptyset$  /\* Queue of unvisited nodes \*/

*q.enqueue*(*v*)

*v.distance*  $\leftarrow 0$

*v.pred*  $\leftarrow v$  /\* source node - no predecessor \*/

mark *v* as visited /\* all other nodes should initially be unvisited \*/

**While** *q*  $\neq \emptyset$  /\* while there are still unprocessed nodes \*/

*u*  $\leftarrow q.dequeue()$  /\* remove first element of *q* \*/

**For** all neighbors *w* of *u* **do**

**If** *w* has not yet been visited **then** /\* new node \*/

*q.enqueue*(*w*)

            mark *w* as visited

*w.distance*  $\leftarrow u.distance + 1$

*w.pred*  $\leftarrow u$

## BFS: More applications (different graph types)

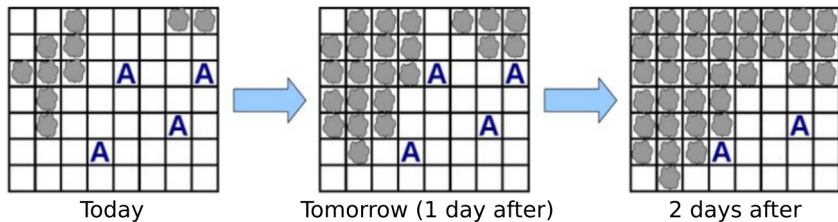
- BFS can be applied in many different graph types
- Consider for instance that you want to know the **minimum distance between** points **A** and **B** on a 2D maze:

#####		#####
#A.....#		#A12345#
####.###	--->	####4###
#B.....#	BFS starting in A	#876567#
#####		#####

- ▶ A node is a cell  $(x, y)$
- ▶ Neighbors are  $(x + 1, y)$ ,  $(x - 1, y)$ ,  $(x, y + 1)$  e  $(x, y - 1)$
- ▶ Everything else in the BFS is the same! (time:  $\mathcal{O}(\text{rows} \times \text{cols})$ )
- ▶ To store on the queue we need to represent a pair of coordinates (in C++ this could for instance be: `queue<pair<int, int>> q`).

## BFS: More applications (multiple sources)

- Let's see an old problem from a qualification phase of the National Olympiads in Informatics (ONI'2010)
- The problem was inspired by **Eyjafjallajökull volcano** eruption, whose ash cloud completely disrupted airplane traveling in Europe.
- Imagine that the **ash cloud** is given as a matrix and that in each time the cloud expands by one cell both horizontally and vertically. The A's are the airports.



# BFS: More applications (multiple sources)



- The problem asked for:
  - ▶ How many days until the **first airport** is covered by ashes
  - ▶ How many days until **all airports** are covered by ashes
- Let  $dist(A_i)$  be the distance of airport  $i$  up to any ash cloud
- The problems asks for the smallest  $dist(A_i)$  and the largest  $dist(A_i)$
- One option could be to make one BFS per airport  
 $\mathcal{O}(num\_airports \times rows \times cols)$
- Another option could be to make one BFS per ash cell  
 $\mathcal{O}(num\_ashes \times rows \times cols)$
- How to do better, using only one BFS?

# BFS: More applications (multiple sources)



- Idea: initialize the BFS queue with all ash positions!
- Everything else remains the same.

...#...	.. <b>1#1</b> ..	. <b>21#12</b> .	<b>321#123</b>	321#123
..##...	. <b>1##1</b> ..	<b>21##12</b> .	21##123	21##123
.####...	-> <b>1#####1</b> .	-> <b>1#####12</b> .	-> <b>1#####12</b> .	-> <b>1#####12</b> .
.....	<b>11111</b> ..	1111 <b>12</b> .	1111 <b>123</b>	1111123
##.....	<b>##1</b> ....	<b>##122</b> ..	<b>##1223</b> .	<b>##12234</b>

- The computed distances are exactly what we need
- Each cell will only be traversed once!  $O(\text{rows} \times \text{cols})$

## BFS: More applications (implicit graphs and game search)

- Let's see a final problem where there is no "explicit" graph  
*[original problem from IOI'1996]*
- Consider the following puzzle (almost like a 2D version of Rubik's cube)

► The initial board position is:

1	2	3	4
8	7	6	5

► In each turn you can make of these 3 movement types:

★ **Movement A:** swap upper and lower rows

8	7	6	5
1	2	3	4

★ **Movement B:** shift the rectangle to the right

4	1	2	3
5	8	7	6

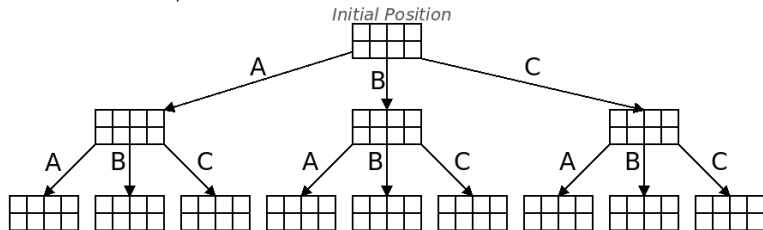
★ **Movement C:** clockwise rotation of the 4 inner cells

1	7	2	4
8	6	3	5

► **How many turns** do we need to reach a certain position?

## BFS: More applications (implicit graphs and game search)

- This can be solved with... **BFS!**
- The **initial node** is... the starting position.
- The **adjacent nodes** are... the positions you can reach using movements A, B or C.



- When we reach the desired position... we know the **shortest distance** (number of movements) to reach it!
- The "hardest" part is... knowing how to **represent and manipulate the board positions !** :)



# Graph Search - Wrap Up

- One of the most fundamental tasks with graphs is **graph search** (or **graph traversal**): passing through all the nodes using the links
- There are two fundamental graph search methodologies that vary on **order in which they traverse the nodes**:
  - ▶ **Depth-First Search - DFS**  
Traverse the entire subgraph connected to a neighbor before entering the next neighbor node
  - ▶ **Breadth-First Search - BFS**  
Traverse the nodes by increasing distance of number of links to reach them
- Besides the slides and theses two classes presentations here are two other **visualizations** of these traversal algorithms:
  - ▶ VisuAlgo: Graph Traversal (DFS/BFS)
  - ▶ David Galles' visualizations: DFS and BFS