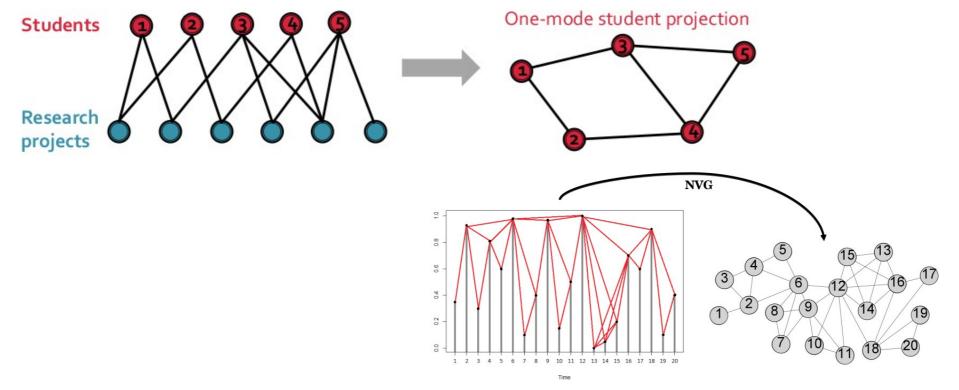
#### **Network Construction**



#### Pedro Ribeiro

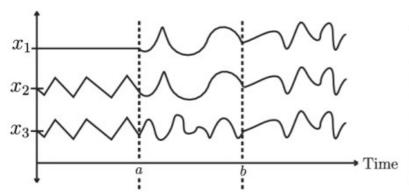
(DCC/FCUP & CRACS/INESC-TEC)

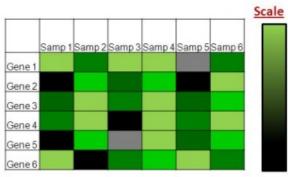


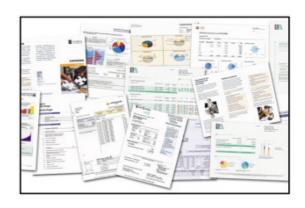


(Mainly selected slides from Jure Leskovec, Lucas Lacasa and Vanessa Silva)

#### Raw data is often **NOT** a network

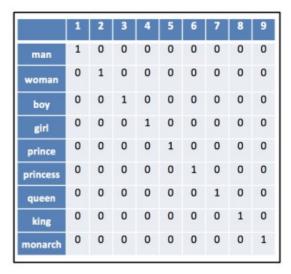






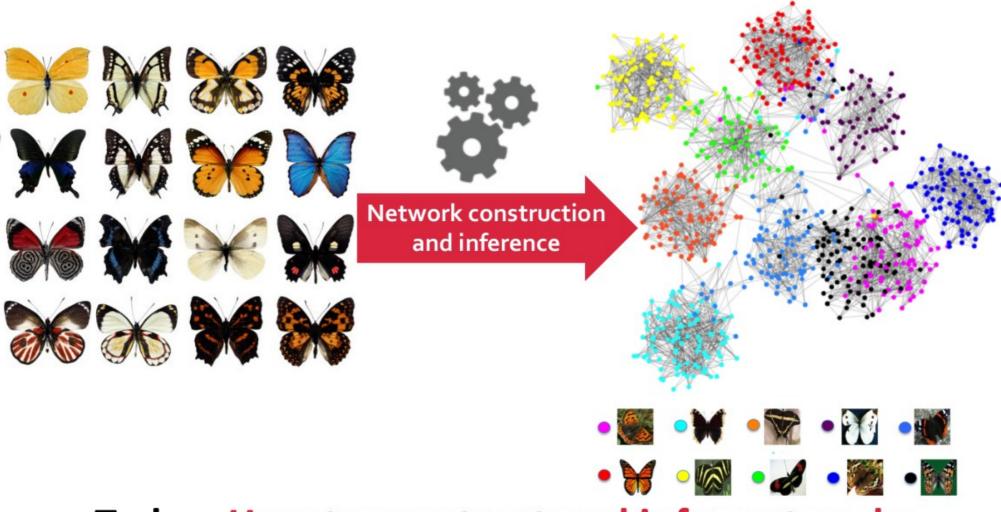






Feature matrices, relationship tables, time series, document corpora, image datasets, etc.

#### How to construct networks?



Today: How to construct and infer networks from raw data?

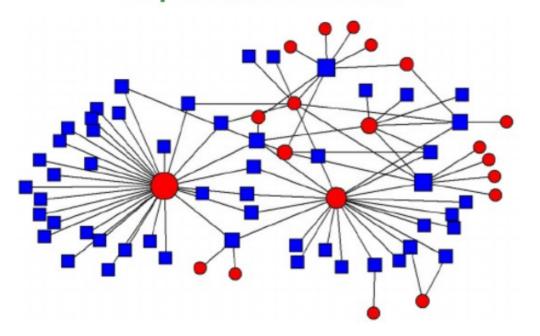
### **Plan for Today**

- Multi-mode network transformations
  - K-partite graphs and projections
  - Graph Contractions
- K-nearest neighbor graphs
- Network deconvolution
  - Direct and indirect effects
- From time-series to graphs
  - Visibility and quantile graphs

# Multi-Mode Network Transformations

## **Bipartite and K-partite Networks**

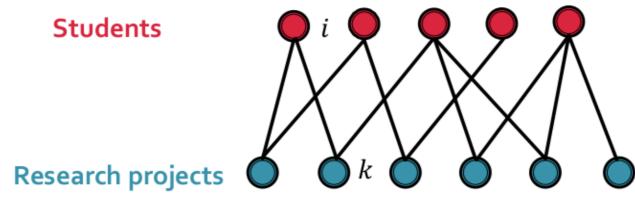
- Most of the time, when we create a network, all nodes represent objects of the same type:
  - People in social nets, bus stops in route nets, genes in gene nets
- Multi-partite networks have multiple types of nodes, where edges exclusively go from one type to the other:
  - 2-partite student net: Students <-> Research projects
  - 3-partite movie net: Actors <-> Movies <-> Movie Companies



Network on the left is a social bipartite network. Blue squares stand for people and red circles represent organizations

#### **One-mode Projections: Example**

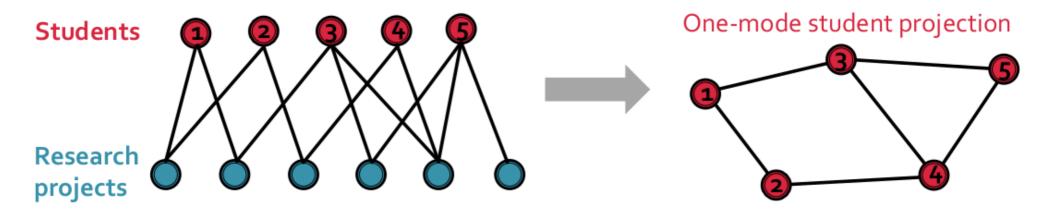
- Example: Bipartite student-project network:
  - Edge: Student i works on research project k



- Two network <u>projections</u> of student-project network:
  - Student network: Students are linked if they work together in one or more projects
  - Project network: Research projects are linked if one or more students work on both projects
- In general: K-partite network has K one-mode network projections

#### **One-mode Projections: Example**

Example: Projection of bipartite student-project network onto the student mode:

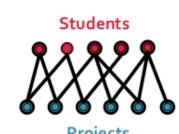


- Consider students 3, 4, and 5 connected in a triangle:
  - Triangle can be a result of:
    - Scenario #1: Each pair of students work on a different project
    - Scenario #2: Three students work on the same project
  - One-mode network projections discard some information:
    - Cannot distinguish between #1 and #2 just by looking at the projection

#### **Constructing One-mode Projections**

- One-mode projection onto student mode:
  - #(projects) that students i and j work together on is equivalent to the number of paths of length 2 connecting i and j in the bipartite network
- Let C be incidence matrix of student-project net:

$$C_{ik} = \begin{cases} 1 & \text{if } i \text{ works on project } k \\ 0 & \text{otherwise} \end{cases}$$

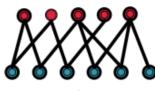


- rioject
- C is an  $n \times m$  binary non-symmetric matrix:
  - n is #(students), m is #(projects)

#### **Constructing One-mode Projections**

- Idea: Use C to construct various one-mode network projections
- Weighted student network:

$$B_{ij} = \begin{cases} w_{ij}, \#(\text{projects}) \text{ that } i \text{ and } j \text{ collaborate on } \\ 0 \text{ otherwise} \end{cases}$$



Students

Project

- $B_{ij} = \sum_{k=1}^{m} C_{ik}C_{jk}$ , i.e., the number of **paths of length 2** connecting students i and j in the bipartite network
- $\mathbf{B} = \mathbf{C}\mathbf{C}^T$  and  $B_{ii}$  represents #(projects) that student i works on
- Similarly, weighted project network:

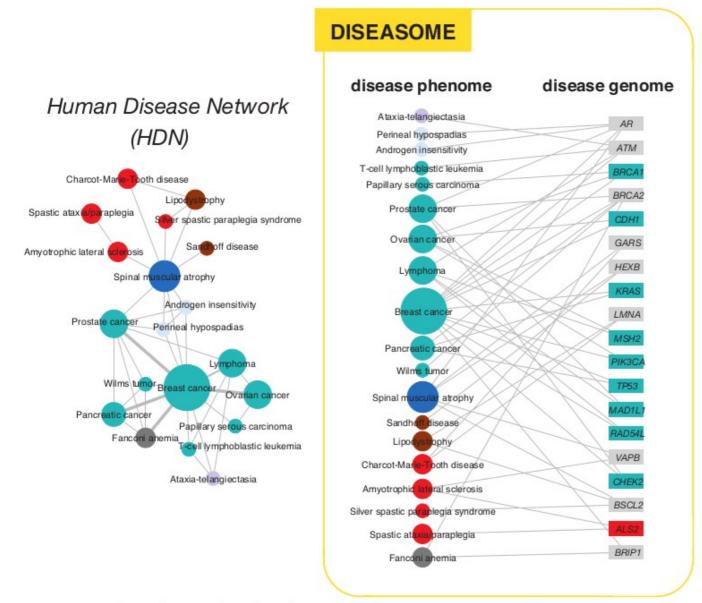
$$D_{kl} = \begin{cases} w_{kl} \text{ , #(students) that work on } k \text{ and } l \\ 0 \text{ otherwise} \end{cases}$$

- $D_{kl} = \sum_{i=1}^{n} C_{ik}C_{il}$ , i.e., the number of **paths of length 2** connecting projects k and l in the bipartite network
- $D = C^T C$  and  $D_{kk}$  represents #(students) that work on project k
- Next: Use B and D to obtain different network projections

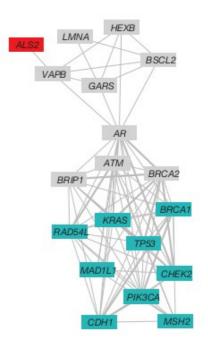
#### **Constructing One-mode Projections**

- Construct network projections by applying a node similarity measure to B and D
- Two node similarity measures:
  - Common neighbors: #(shared neighbors of nodes)
    - Student network: i and j are linked if they work together in r or more projects, i.e., if  $B_{ij} \ge r$
    - **Project network:** k and l are linked if r or more students work on both projects, i.e., if  $D_{kl} \ge r$
  - Jaccard index:
    - Common neighbors with a penalization for each non-shared neighbor:
      - Ratio of shared neighbors in the complete set of neighbors for 2 nodes
    - Student network: i and j are linked if they work together in at least p fraction of their projects, i.e., if  $B_{ij}/(B_{ii}+B_{jj}-B_{ij}) \ge p$
    - Project network: k and l are linked if at least p fraction of their students work on both projects, i.e., if  $D_{kl}/(D_{kk}+D_{ll}-D_{kl}) \ge p$

#### **Example: Human Disease Network**



Disease Gene Network (DGN)

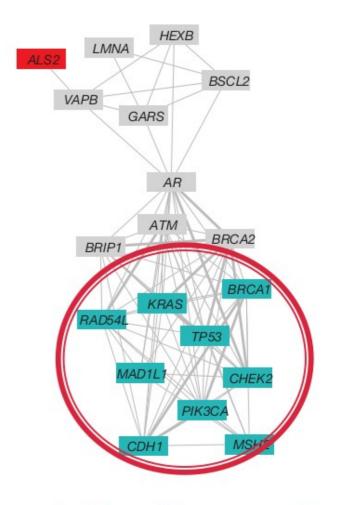


Kwang-Il Goh et al., The human disease network. PNAS, 104:21, 2007.

#### **Example: Human Disease Network**

- Issue: Folded gene network contains many cliques:
  - Why do cliques arise in the folded gene network?
    - Homework 1
- Cliques make the network difficult to analyze:
  - Computational complexity of many algorithms depends on the size and number of large cliques
- Solution: Use graph contraction to eliminate cliques

Disease Gene Network (DGN)



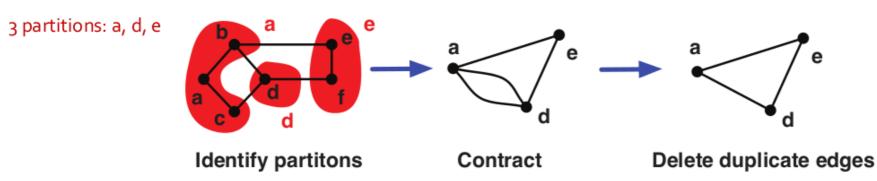
A clique of 9 gene nodes

#### **Graph Contraction**

- Graph contraction: Technique for computing properties of networks in parallel:
  - Divide-and-conquer principle
- Idea:
  - Contract the graph into a smaller graph, ideally a constant fraction smaller
  - Recurse on the smaller graph
  - Use the result from the recursion along with the initial graph to calculate the desired result
- Next: How to contract ("shrink") a graph?

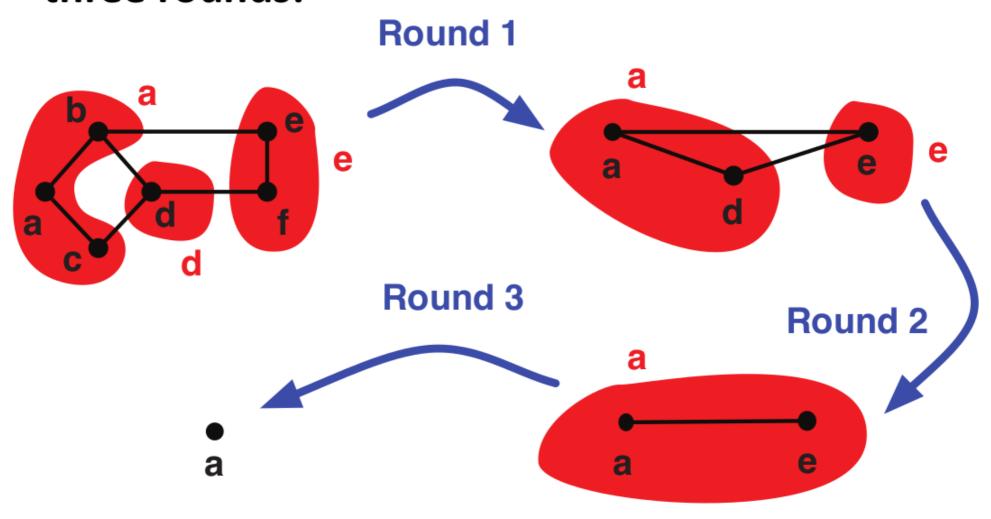
# **Graph Contraction: Algorithm**

- Start with the input graph G:
  - 1. Select a **node-partitioning** of G to guide the contraction:
    - Partitions are disjoint and they include all nodes in G
  - 2. Contract each partition into a single node, a supernode
  - Drop edges internal to a partition
  - 4. Reroute cross edges to corresponding supernodes
  - 5. Set G to be the smaller graph; Repeat
- Example: one round of graph contraction:



#### **Graph Contraction: Example**

Contracting a graph down to a single node in three rounds:



#### Different Types of Node Partitioning

- Partitions should be disjoint and include all nodes in G
- Three types of node-partitioning:
  - Each partition is a (maximal) clique of nodes:



Each partition is a single node or two connected nodes:

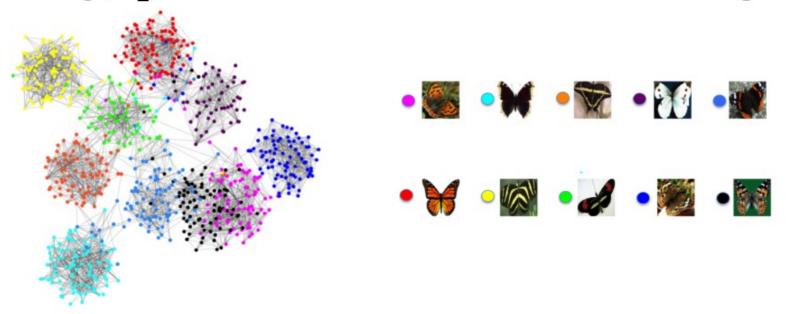


Each partition is a star of nodes, etc.

# K-Nearest Neighbors Graph Construction

# K-nearest Neighbor Graph

- K-nearest neighbor graph (K-NNG) for a set of objects V is a directed graph with vertex set V:
  - Edges from each  $v \in V$  to its K most similar objects in V under a given similarity measure:
    - e.g., Cosine similarity for text
    - e.g., l<sub>2</sub> distance of CNN-derived features for images

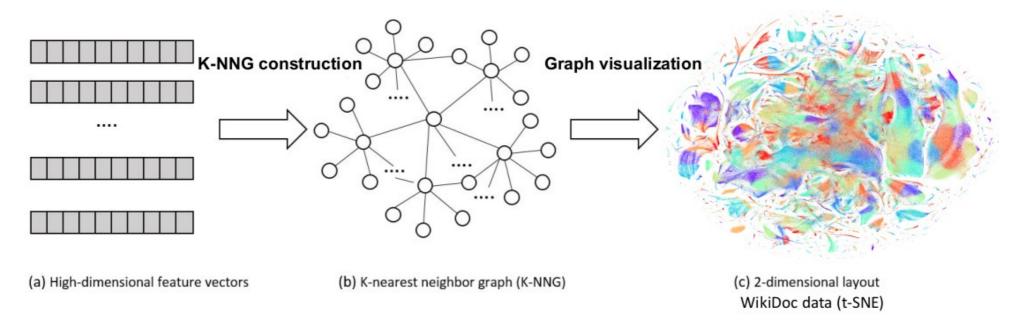


# Why should we build K-NNG's?

- K-NNG construction is an important operation:
  - Recommender systems: connect users with similar product rating patterns, then make recommendations based on the user's graph neighbors
  - Document retrieval systems: connect documents with similar content, quickly answer input queries
  - Other problems in clustering, visualization, information retrieval, data mining, manifold learning
- K-NNGs allow us to use network methods on datasets with no explicit graph structure

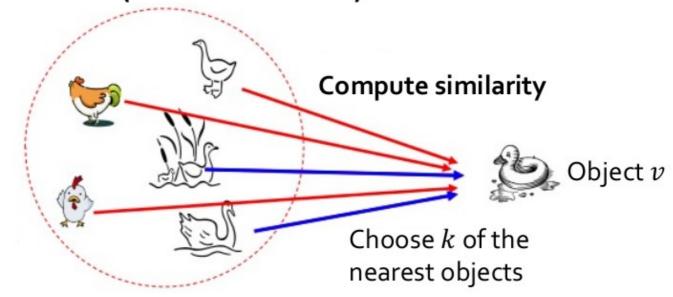
### **Example: K-NNG in Visualization**

- Problem: Visualize large high-dim data in 2D space
- Traditional approach:
  - Compute similarities between objects
  - Project objects into a 2D space by preserving the similarities
  - Does not scale to millions of objects and hundreds of dimensions
- K-NNG can substantially reduce computational costs



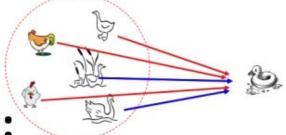
#### K-NNG: a Brute Force Approach

- Let's construct a K-NNG by brute-force:
  - Given n objects V and a distance metric  $\sigma: V \times V \to [0, \infty)$
  - For each possible pair of (u, v), compute  $\sigma(u, v)$
  - For each v, let  $B_K(v)$  be v's K-NN, i.e., the K objects in V (other than v) most similar to v



#### K-NNG: a Brute Force Approach

• Computational cost of brute-force:  $O(n^2)$ 



- Issues with brute-force approach:
  - Not scalable: Practical for only small datasets
  - Not general: Many custom heuristics designed to speed up computations:
    - Many heuristics are specific to a similarity measure
  - Not efficient: Compute all neighbors for every v
    - We only need k nearest neighbors for every v

# **Today: NN-Descent Approach**

- Can we do better than brute-force?
- Yes, and we will learn about it today!
- NN-Descent [Dong et al., WWW 2011]:
  - Efficient algorithm to approximate K-NNG construction with arbitrary similarity measure
- Other published methods (not covered today):
  - Locality Sensitive Hashing (LSH): A new hash function needs to be designed for a new similarity measure
  - Recursive Lanczos bisection: Recursively divide the dataset, so objects in different partitions are not compared
  - K-NN search problem: If K-NN problem is solved, K-NNG can be constructed by running a K-NN query for each  $v \in V$

# **NN-Descent: Key Principle**

Key principle: A neighbor of a neighbor is also likely to be a neighbor

- Use this principle in a NN-Descent method:
  - Start with an approximation of the K-NNG, B
  - Improve B by exploring each point's neighbors' neighbors as defined by the current approximation
  - Stop when no improvement can be made

#### **NN-Descent: Notation**



#### Let:

- V be a metric space with distance metric  $d: V \times V \to [0, \infty)$ ,  $\sigma = -d$  is the similarity measure
- $B_K(v)$  be v's K-NN
- $R_K(v) = \{u \in V; v \in B_K(u)\}$  be v's reverse K-NN
- B[v] be current approximation of  $B_K(v)$
- $B'[v] = \bigcup_{v' \in B[v]} B[v']$  be neighbors of v's neighbors
- For any r > 0, let r-ball around v be:  $B_r(v) = \{u \in V; d(u,v) \le r\}$

#### NN-Descent: Overview



Def: Metric space V is growth-restricted if there exists a constant c, such that:

$$|B_{2r}(v)| \le c|B_r(v)|, \ \forall v \in V$$

- The smallest such c is growing constant of V
- Approach:
  - Start with an approximation of the K-NNG, B
  - Use the growing constant of V to show that B can be improved by comparing each object v against its current neighbors' neighbors B'[v]
- Next: Use the growing-constant argument on B

#### **NN-Descent: Overview**

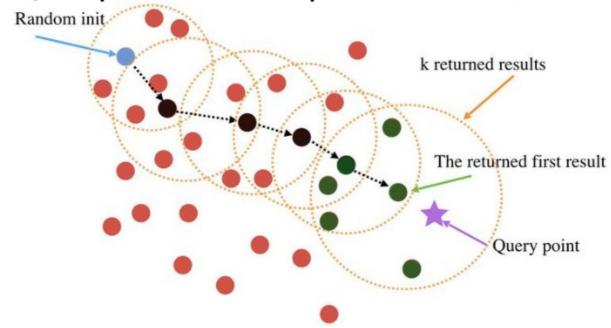


#### Two assumptions:

- Let c be the growing constant of V and let  $K = c^3$
- Have an approximate K-NNG B that is reasonably good:
  - For a fixed radius r, for all v, B[v] contains K neighbors that are uniformly distributed in  $B_r(v)$
- Lemma: B'[v] is likely to contain K nearest neighbors in  $B_{r/2}(v)$
- **Corollary:** We expect to **halve the maximal distance** to the set of approximate K nearest neighbors by exploring B'[v] for every v

# NN-Descent: Algorithm Details

- **Lemma** suggests the following algorithm:
  - Pick a large enough K(depending on growing constant c)
  - Start from a random K-NNG approximation
  - For each v, find K nearest objects by exploring v's neighbors' neighbors, B'
  - Repeat; stop when no improvement can be made



#### Algorithm 1: NNDESCENT

**Data**: dataset V, similarity oracle  $\sigma$ , K

Result: K-NN list B

begin

$$B[v] \leftarrow \text{Sample}(V, K) \times \{\infty\}, \quad \forall v \in V$$

$$loop$$

$$R \leftarrow \text{Reverse}(B)$$

$$\overline{B}[v] \leftarrow B[v] \cup R[v], \quad \forall v \in V;$$

$$c \leftarrow 0 \quad //\text{update counter}$$

$$for \ v \in V \text{ do}$$

$$c \leftarrow \overline{B}[v], u_2 \in \overline{B}[u_1] \text{ do}$$

$$c \leftarrow c + \text{UpdateNN}(B[v], \langle u_2, l \rangle)$$

$$return B \text{ if } c = 0$$

A. Start by picking a random approximation of K-NN for each object

**B**. Improve the approximation by comparing each object against its current neighbors' neighbors, including K-NN and reverse K-NN

**C**. Stop when no improvement can be made

function Sample(S, n) **return** Sample n items from set S

function Reverse(B)

begin

$$R[v] \longleftarrow \{u \mid \langle v, \dots \rangle \in B[u]\} \quad \forall v \in V$$
 return  $R$ 

function UPDATENN $(H, \langle u, l, \ldots \rangle)$ 

Update K-NN heap H; return 1 if changed, or 0 if not.

### **Experimental Setup: Data**

#### Datasets:

- Corel: Each image is segmented into 14 regions, a feature is extracted from each region
- Audio: Each sentence is described by 192 features
- Shape: Each shape is described by 544-dim feature vector
- DBLP: Each record includes authors' names and pub. title
- Flickr: Each image is segmented into regions, a pixel-based feature is extracted from each region
- Similarity measures: L1, L2, Cosine, Jaccard, EMD

Dataset	# Objects	Dimension	Similarity Measures
Corel	662,317	14	$l_1, l_2$
Audio	54,387	192	$l_1, l_2$
Shape	28,775	544	$l_1, l_2$
DBLP	857,820	N/A	Cosine, Jaccard
Flickr	100,000	N/A	EMD

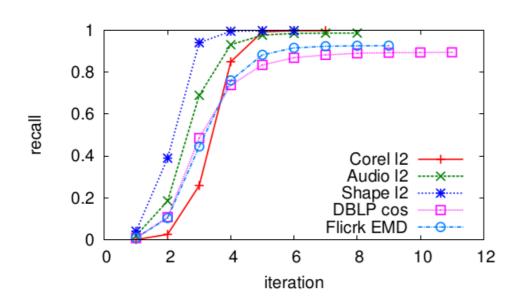
(EMD: earth mover's distance)

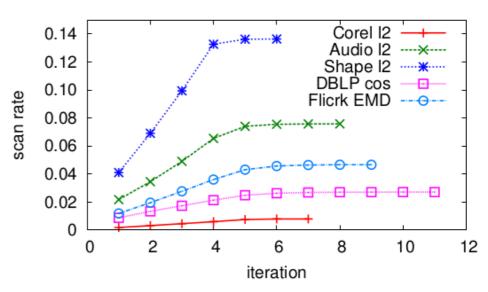
#### **Experimental Setup: Measures**

- Use recall as an accuracy measure:
  - Ground-truth: true K-NNs obtained by scanning the datasets in brute force
  - Recall of one object is the number of its true K-NN members found divided by K
  - Recall of an approximate K-NNG is the average recall of all objects
- Use #(sim. evaluations) as a measure of computational cost:

scan rate = 
$$\frac{\#(\text{similarity evaluations})}{n(n-1)/2}$$

#### **Exp: Overall Performance**

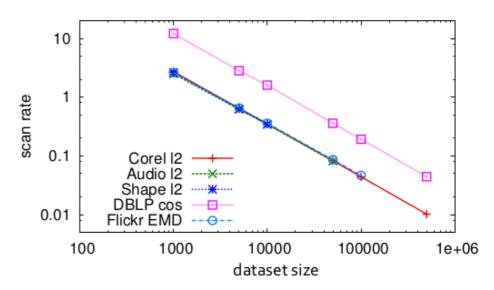




- Similar performance trends on different datasets
- Fast convergence across all datasets:
  - Curves are close to their final recall after 5 iterations
  - All curves converge within 12 iterations

#### **Exp: Performance as Data scales**

Size	Corel	Audio	Shape	DBLP	Flickr	
	$l_2$	$l_2$	$l_2$	cos	EMD	
1K	1.000	0.999	1.000	0.959	0.999	
5K	1.000	0.996	0.992	0.970	0.991	
10K	1.000	0.993	0.998	0.970	0.983	
50K	0.999	0.988	-	0.951	0.953	
100K	0.999	-	-	0.940	0.925	
500K	0.997	-	-	0.907	-	
(recall values						



 Run experiments on samples of the full datasets and observe changes in recall and scan rate as sample size grows

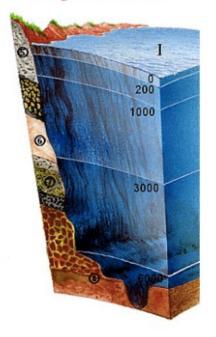
#### Results:

- As dataset grows, there is only a minor decline in recall
- All curves form parallel straight lines in the scan rate vs. dataset size:
  - NN-descent has a polynomial time complexity
  - Fit the scan rate curves to obtain empirical complexity of NN-Descent:
    - $O(n^{1.14}) \ll O(n^2)$  (=brute-force)

#### **Network Deconvolution**

#### **Motivation**

- Networks represent dependencies among objects:
  - Co-authorships between scientists
  - Friendships between people
  - Who-eats-whom in food webs
  - Bonds between molecular residues
  - Regulatory relationships between genes
- Indirect dependencies occur because of transitive effects of correlation
- Problem: How to separate direct dependencies from indirect ones?



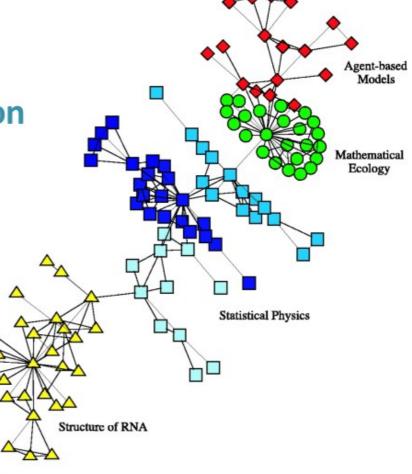
# **Application: Co-Authorship**

Goal: Distinguish strong and weak collaborations between scientists

Collaboration tie strengths depend on publication details, such as:

 #(papers) each pair of scientists has collaborated on

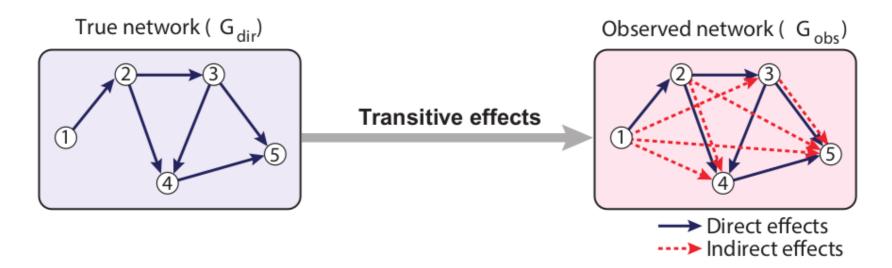
#(co-authors) on each of the papers



- Strength of ties are important for:
  - Recommending friends and colleagues
  - Recognizing conflicts of interest
  - Evaluating authors' contribution to teams

#### **Observed Network**

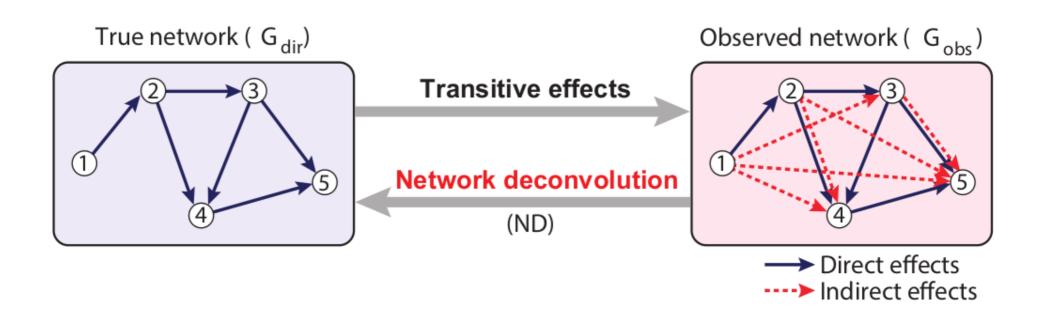
Observed network: Combined direct and indirect effects:



- Indirect edges might be due to higher-order interactions (e.g., 1→4)
- Each edge might contain both direct and indirect components (e.g., 2→4)

#### **Network Deconvolution**

- Goal: Reverse the effect of transitive information flow across all indirect paths:
  - Recover true direct network (blue edges, G<sub>dir</sub>) based on observed network (combined blue and red edges, G<sub>obs</sub>)

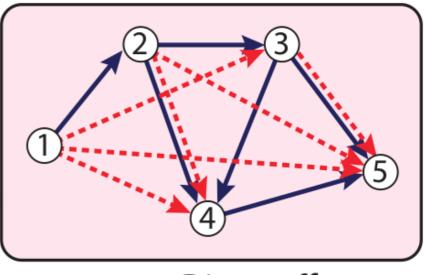


Feizi et al., Nature Biotechnology, 31:8, 2013.

## **Network Deconvolution: Challenge**

- Direct edges in a network can lead to indirect relationships:
  - Transitive information flow
- Indirect effects can be of length:
  - **2** (e.g.,  $1 \rightarrow 2 \rightarrow 3$ )
  - **3** (e.g.,  $1 \rightarrow 2 \rightarrow 3 \rightarrow 5$ )
  - higher-order
- Indirect effects can combine:
  - Both direct and indirect effects (e.g., 2→4)
  - Multiple indirect effects along varying paths (e.g., 2→3→5, 2→4→5)

Observed network ( G<sub>obs</sub>)



→ Direct effects
Indirect effects

Details

• Transitive effects in  $G_{\rm obs}$  can be expressed as an infinite sum of  $G_{\rm dir}$  and all indirect effects:

$$G_{\rm obs} = G_{\rm dir} + G_{\rm indir}$$

Indirect effects can be of increasing lengths:

$$G_{\text{indir}} = G_{\text{dir}}^2 + G_{\text{dir}}^3 + G_{\text{dir}}^4 + \cdots$$

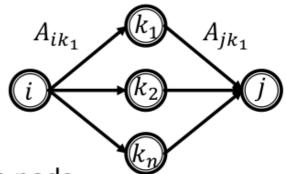


- 2<sup>nd</sup> order effects:  $G_{dir}^2 = A_{dir}^2$ 
  - The number of edges in  $G_{\mathrm{obs}}$  of indirect paths of length 2
- 3<sup>rd</sup> order effects:  $G_{dir}^3 = A_{dir}^3$ 
  - The number of edges in  $G_{\mathrm{obs}}$  of indirect paths of length 3

# **Powers of Adjacency Matrices**

- Let's raise adjacency matrix A<sub>dir</sub> to the second power:
  - The (i,j)-th entry of  $A_{dir}^2$  is:

$$A_{\mathrm{dir}}^{2}(i,j) = \sum_{k=1}^{n} A_{\mathrm{dir}}(i,k) A_{\mathrm{dir}}(k,j)$$



- This sum is only greater than zero if there exists a node k for which  $A_{dir}(i,k)$  and  $A_{dir}(k,j)$  are both nonzero:
  - There exists a node k that is connected to both nodes i and j
  - The sum counts the number of neighbors that nodes i and j share
  - The sum counts the paths of length 2 between nodes i and j
- This reasoning is valid for higher powers of  $A_{\rm dir}$ :
  - $A_{\text{dir}}^3(i,j)$  counts the paths of length 3 between i and j
  - $A_{\text{dir}}^4(i,j)$  counts the paths of length 4 between i and j

Details

Idea: Model indirect flow as power series of direct flow:

$$G_{\mathrm{obs}} = G_{\mathrm{dir}} + G_{\mathrm{dir}}^2 + G_{\mathrm{dir}}^3 + G_{\mathrm{dir}}^4 + \cdots$$
Converges with correct scaling Indirect effects

Transitive closure of  $G_{\rm dir}$ 

- **Note:** Linear scaling of  $G_{\rm obs}$  so that max absolute eigenvalue of  $G_{\rm dir} < 1$ :
  - Indirect effects decay exponentially with path length
  - Infinite series converges

- Transitive closure of G<sub>dir</sub> can be expressed as an infinite sum of:
  - True direct network, G<sub>dir</sub>
  - All indirect effects along paths of increasing lengths,  $G_{dir}^2$ ,  $G_{dir}^3$ ,  $G_{dir}^4$ , ...
- Idea: Can be written in a closed form as an infiniteseries sum using Taylor series expansions:

$$G_{\text{obs}} = G_{\text{dir}} + G_{\text{dir}}^2 + G_{\text{dir}}^3 + G_{\text{dir}}^4 + \dots = G_{\text{dir}}(I + G_{\text{dir}} + G_{\text{dir}}^2 + G_{\text{dir}}^3 + \dots) = G_{\text{dir}}(I - G_{\text{dir}})^{-1}$$

Note: Let X be any square matrix with max absolute eigenvalue < 1. Then the following series converges:  $I + X + X^2 + X^3 + \cdots$ The series converges to:  $\sum_{k=0}^{\infty} X^k = (1-X)^{-1}$ 

Details

 Using Taylor series expansions we get a closedform expression for G<sub>obs</sub>:

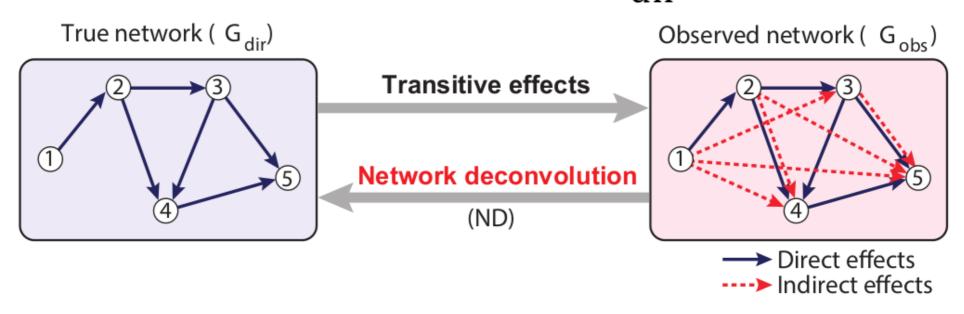
$$G_{\text{obs}} = G_{\text{dir}}(I - G_{\text{dir}})^{-1}$$

- In network deconvolution:
  - Observed network  $G_{obs}$  is known
  - True direct network  $G_{\rm dir}$  needs to be recovered
- Finally, we get a closed-form solution for  $G_{dir}$ :

$$G_{\rm dir} = G_{\rm obs} (I + G_{\rm obs})^{-1}$$

## Net. Deconvolution: Recap

• Use closed-form expression for  $G_{\rm obs}$  to recover true direct network  $G_{\rm dir}$ 



Transitive closure: 
$$G_{obs} = G_{dir} + G_{dir}^2 + G_{dir}^3 + ... = G_{dir}(I - G_{dir})^{-1}$$

Network deconvolution: 
$$G_{dir} = G_{obs}(I + G_{obs})^{-1}$$

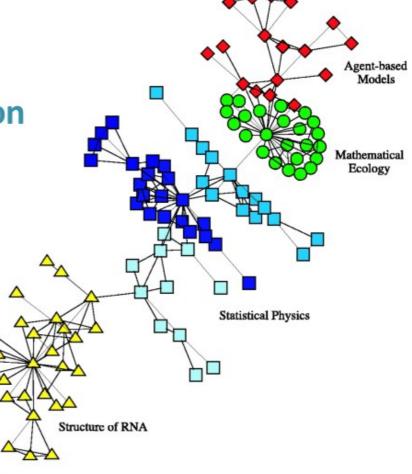
# **Application: Co-Authorship**

Goal: Distinguish strong and weak collaborations between scientists

Collaboration tie strengths depend on publication details, such as:

 #(papers) each pair of scientists has collaborated on

#(co-authors) on each of the papers



- Strength of ties are important for:
  - Recommending friends and colleagues
  - Recognizing conflicts of interest
  - Evaluating authors' contribution to teams

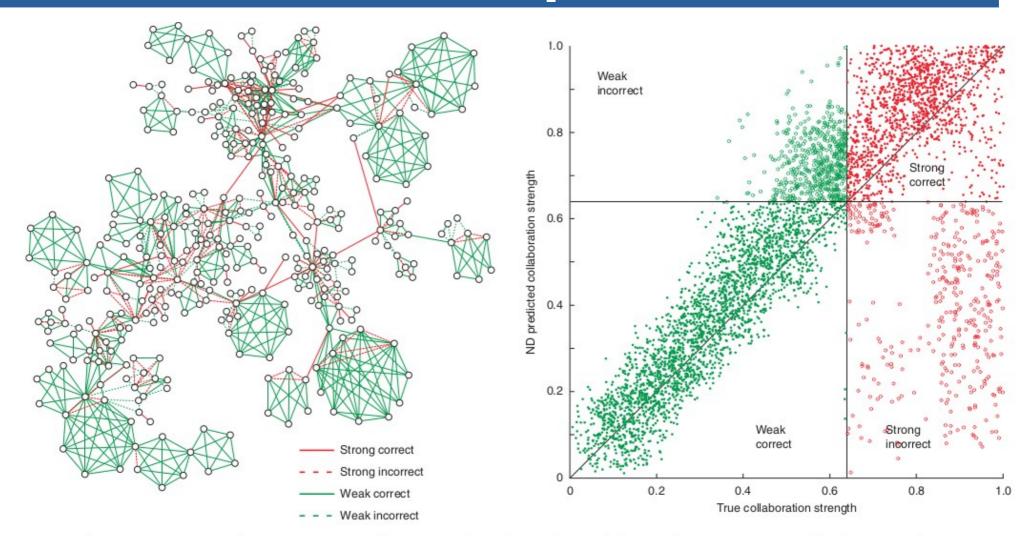
# **Application: Co-Authorship**

- Data: Unweighted network of scientists working in the field of network science:
  - Two authors are linked if they co-authored at least one paper
- Setup: Apply ND on the co-authorship network:
  - ND returns a weighted network whose:
    - Transitive closure most closely captures the input network
    - Weights represent the inferred strength of direct interactions
  - Output: Rank co-authorship edges by the ND-assigned weights

#### Ground-truth data:

- True collaboration strengths are computed by summing the number of co-authored papers and down-weighting each paper by the number of additional co-authors
- Compute correlation between ND-assigned weights and true collaboration strengths

### **Co-Authorship: Results**



- Agreement between the rank obtained by the true collaboration strength and the rank provided by the ND weight,  $R^2 = 0.76$
- Conclusion: ND predict collaboration tie strengths solely by using network topology (i.e., not using other publication details)

# **Application: Gene Network**

- Goal: Infer a gene regulatory network from gene feature vectors describing gene activity:
  - Nodes represent genes

Edges represent regulatory relationships between regulators and their target genes

- Well-studied problem in bioinformatics:
  - A dataset is a gene-by-condition expression matrix
  - Expression matrix is noisy with many indirect measurements

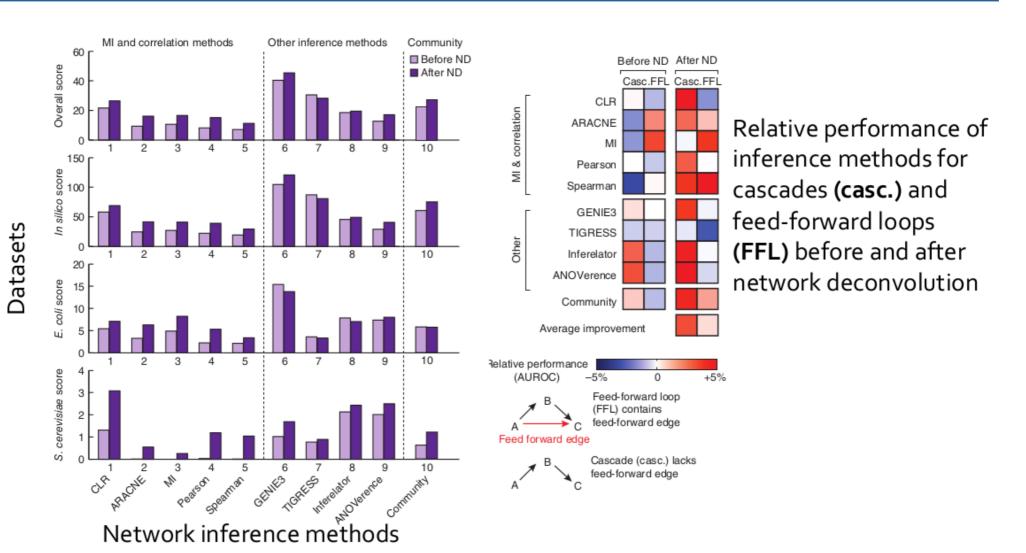
#### **Gene Network: Data**

- 3 datasets: Gene expression datasets from: bacterium E. coli, yeast S. cerevisiae, and a simulated env (in silico)
- Setup: Use ND to improve network inference methods by eliminating indirect edges in the inferred networks:
  - Infer a gene regulatory network using a particular network inference method
  - Apply ND to the inferred network to deconvolve the network
  - Evaluate deconvolved network against ground-truth data

#### Ground-truth data:

 True positive regulatory relationships (i.e., edges) are defined as a set of interactions experimentally validation in a laboratory

### **Gene Network: Results**



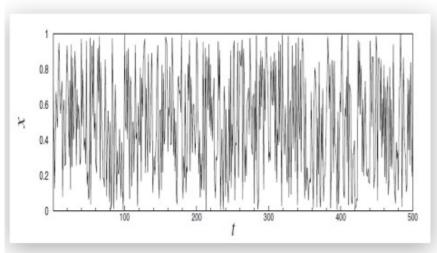
ND improves the performance of top-performing network inference methods

### **Network Deconvolution: Recap**

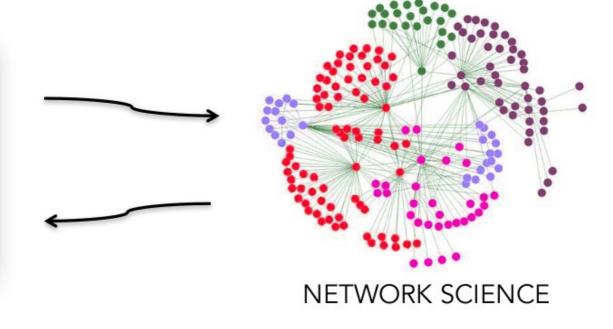
- General approach to identify direct dependencies between objects in a network:
  - Remove spurious edges that are due to indirect effects
  - Decrease over-estimated edge weights
  - Rescale edge weights so that they correspond to direct dependencies between objects
- Other published methods (not covered today):
  - Partial correlations and random matrix theory
  - Graphical models, e.g., Graphical lasso, Bayesian nets,
     Markov random fields
  - Causal inference models

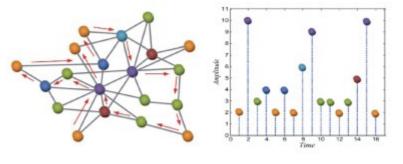
# Time Series meets Network Science

### **Time Series and Network Science**

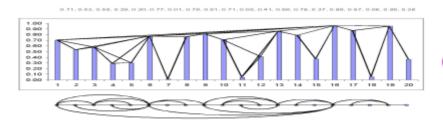






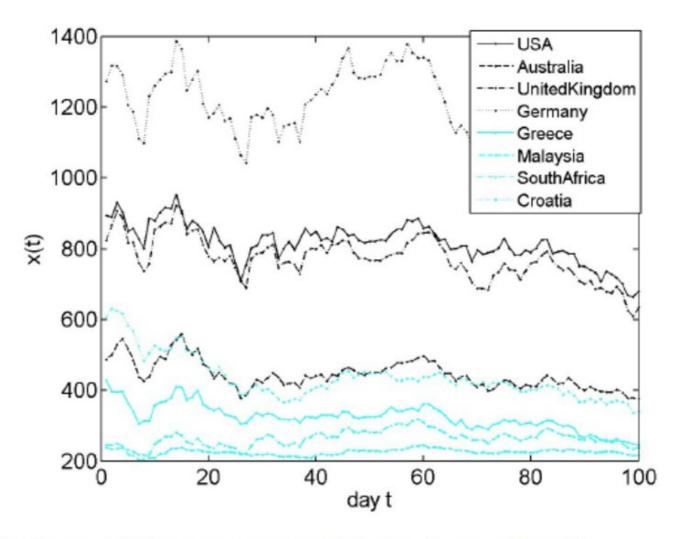


Signal processing of graphs



Graph-theoretical time series analysis

N=8 world stock markets, daily indices, n=100 days.

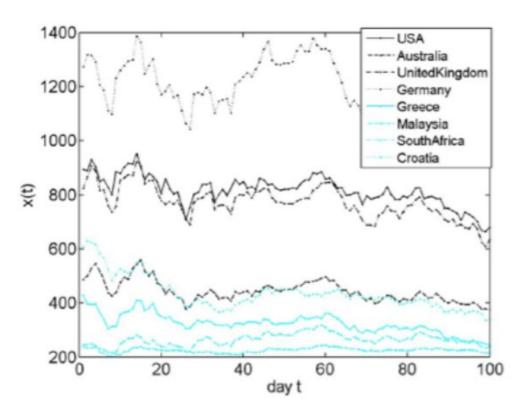


Similar indices, links among world stock markets?

A similarity measure sim(i, j) quantifies the level of

- correlation or coupling between  $X_i$  and  $X_j$  (undirected link)
- causality from  $X_i$  and  $X_j$ , and vice versa (directed link).

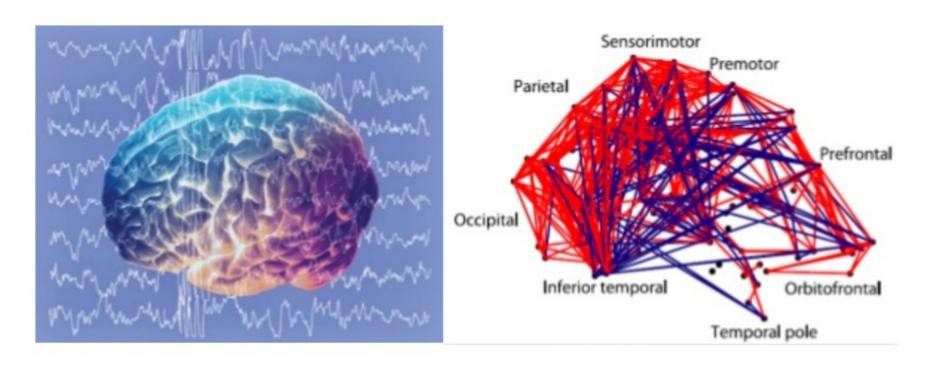
A standard similarity measure is again  $Corr(X_i, X_j) = r_{X_i, Y_j}$ .





One can interpret this matrix as a weighted adjacency matrix!

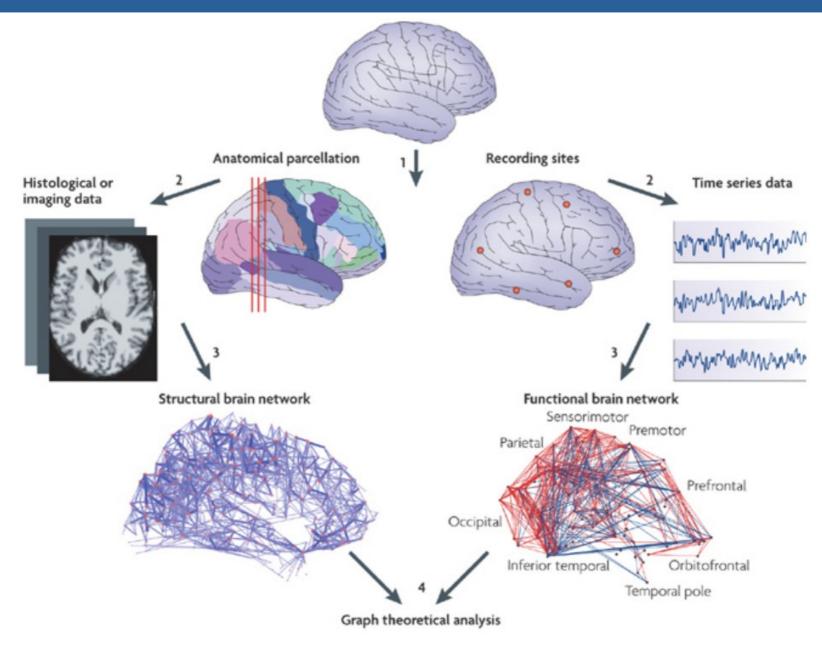
Correlation network



#### **Functional networks**

One can measure signals from the brain (EEG, fmri) at different regions and extract a correlation network from the multivariate time series.

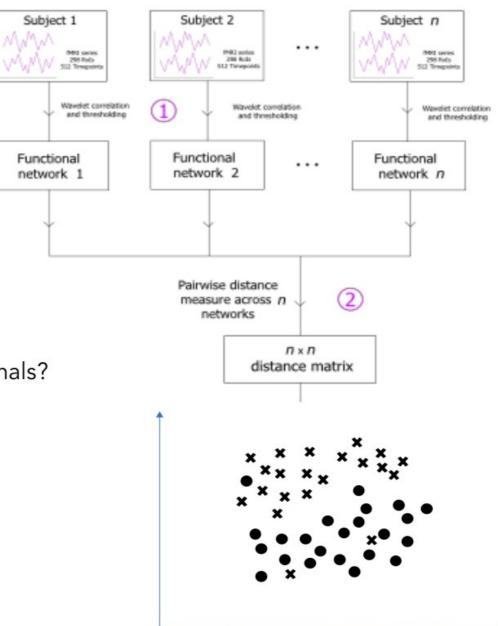
This network describes correlations between the activity of different regions of the brain, and it's called a **functional network**.



Bullmore, Sporns, Nature Reviews Neuroscience 10 (2009)

Typical study: unsupervised clustering of diseases

Can we predict which subject have schizophrenia by looking at brain signals?



Visibility graphs were defined in computational geometry/computer science as the backbone graph capturing visibility paths (intervisible locations) in landscapes

- Each node represents a location
- Two locations are connected by a link if they are visible



Visibility graphs were defined in computational geometry/computer science as the backbone graph capturing visibility paths (intervisible locations) in landscapes

- Each node represents a location
- Two locations are connected by a link if they are visible



#### 1D LANDSCAPES CAN BE CONSIDERED AS TIME SERIES

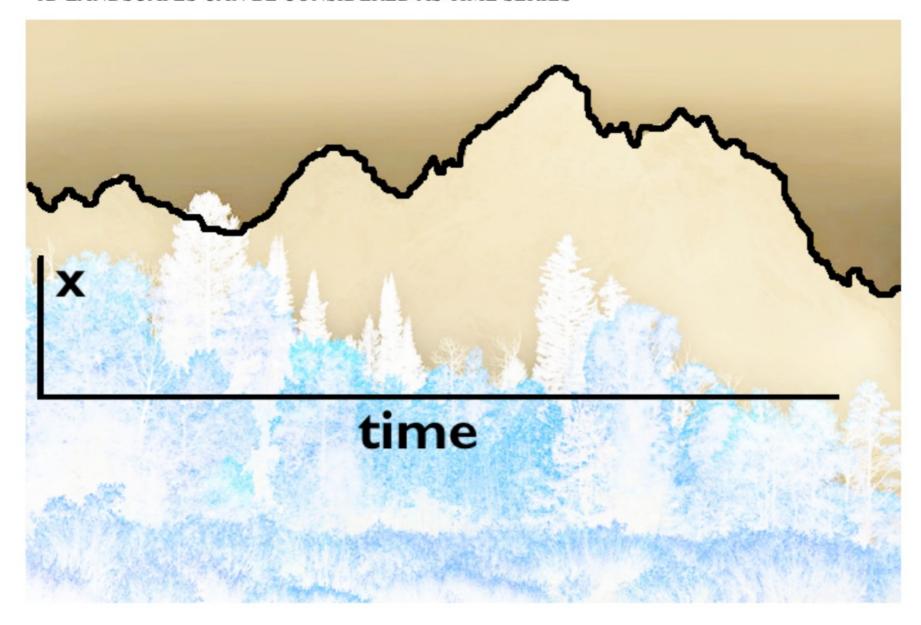


Pedro Ribeiro - Network Construction

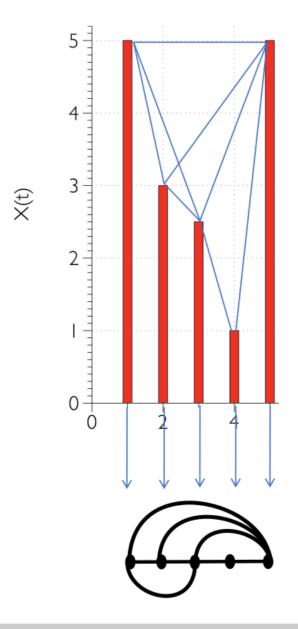
#### 1D LANDSCAPES CAN BE CONSIDERED AS TIME SERIES



1D LANDSCAPES CAN BE CONSIDERED AS TIME SERIES



#### **Natural Visibility Algorithm**



#### For a time series of N data:

- \* each datum is mapped into a node
- \* two nodes are linked if a visibility criterion holds in the series

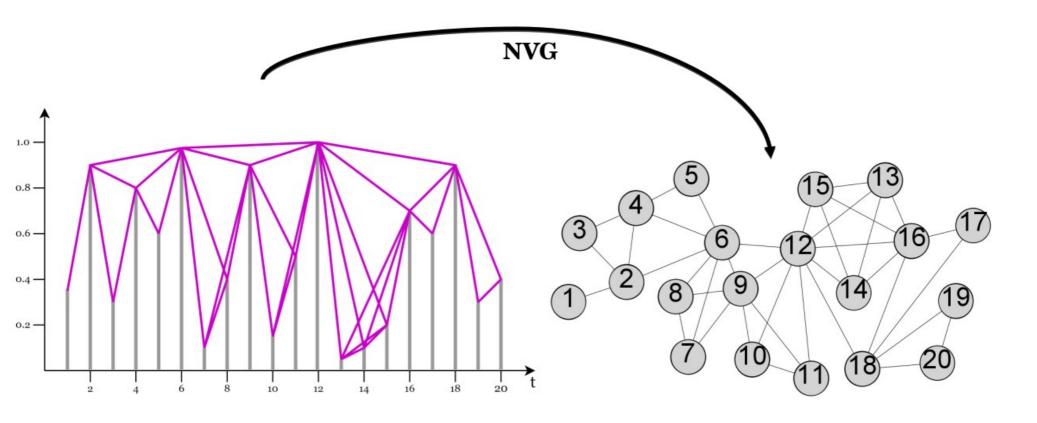
#### The resulting visibility graph:

- \* has N ordered nodes
- \* is connected by a Hamiltonian path
- \* is invariant under certain transformations in the series

Lacasa, Luque, Ballesteros, Luque, Nuño, PNAS 105 (2008)

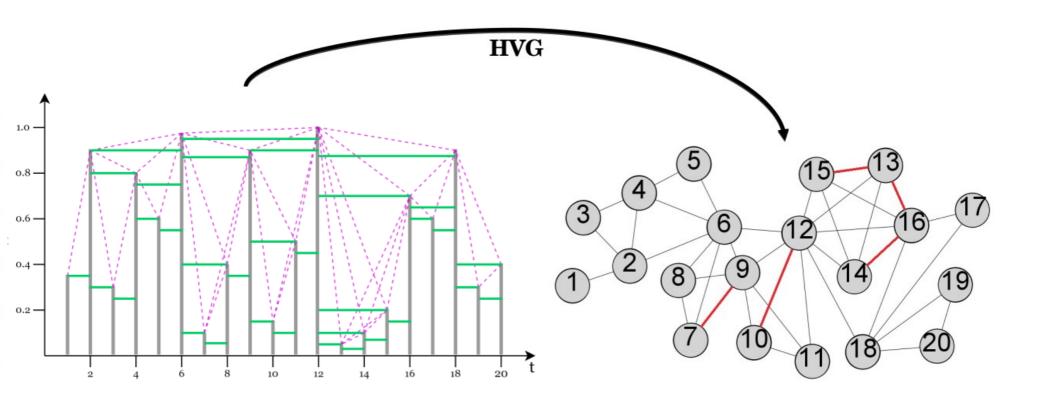
$$y_c = y_b + (y_a - y_b) \frac{(t_b - t_c)}{t_b - t_a}, \quad t_a < t_c < t_b$$

# Natural Visibility Graph



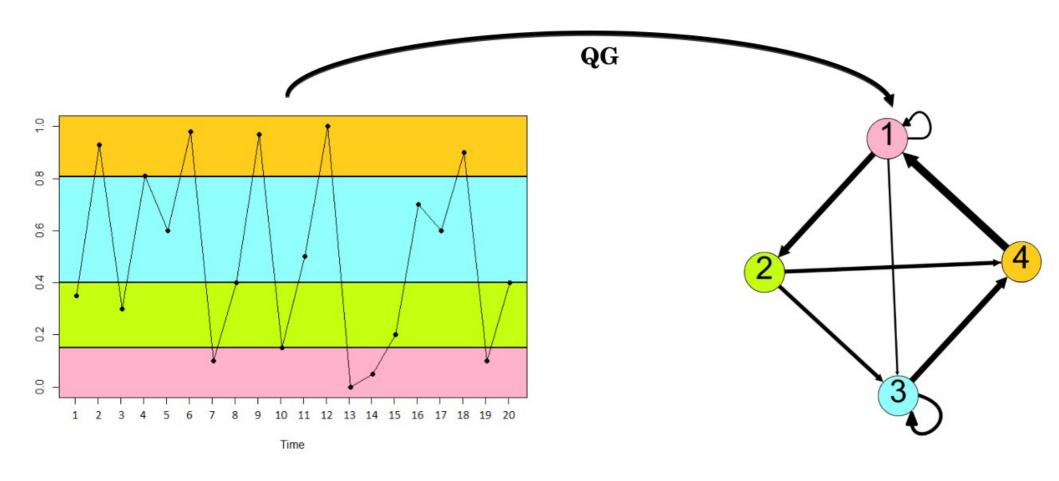
 $y_a, y_b > y_c, t_a < t_c < t_b$ 

# Horizontal Visibility Graph



# **Quantile Graphs**

# Quantile Graph



Can simple topological measures of different networks distinguish different processes of time series?

Vanessa Silva MSc Thesis

# Time Series Clustering

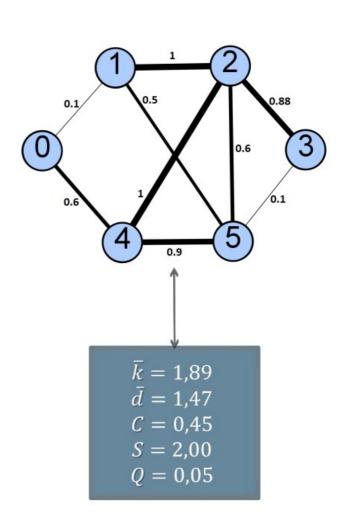
- Distance-based methods
  - ☐ Similarity between observations
    - e.g. Dynamic Time Warping
- Characteristics-based methods
  - Similarity between global characteristics
    - e.g. trend, frequency, autocorrelation, Hurst
- Network-based methods
  - Similarity between topological measures
    - e.g. average degree, number of communities, clustering coefficient

Can simple topological measures of different networks distinguish different processes of time series?

Vanessa Silva MSc Thesis

# **Topological Metrics**

- There is a vast set of topological metrics of graphs to study the particular characteristics of the system.
  - $\square$  Average Degree  $(\overline{k})$
  - $\Box$  Average Path Length  $(\overline{d})$
  - ☐ Global Clustering Coefficient (C)
  - ☐ Number of Communities (S)
  - Modularity (Q)



Can simple topological measures of different networks distinguish different processes of time series?

Vanessa Silva MSc Thesis

#### Method

- 1. Generate Complex Networks
  - a. NVG, HVG, and QGs
- 2. Calculate Metrics and Normalize
  - a.  $\bar{k}$ ,  $\bar{d}$ , C, S and Q
  - b. Min-Max normalization
- 3. Dimensionality Reduction
  - a. PCA and t-SNE
- 4. Clustering Analysis
  - 1. k-means

Can simple topological measures of different networks distinguish different processes of time series?

Vanessa Silva MSc Thesis

#### Time Series Models

- White Noise (i.i.d)
- Linear models

П	AR(1)	
11	AR(I)	

Smoother

 $\square$  AR(2)

Pseudo-Periodic

Stochastic Trend

Long Memory

Nonlinear models

□ SETAR.

Regimes

States

Integer Valued Data

☐ GARCH

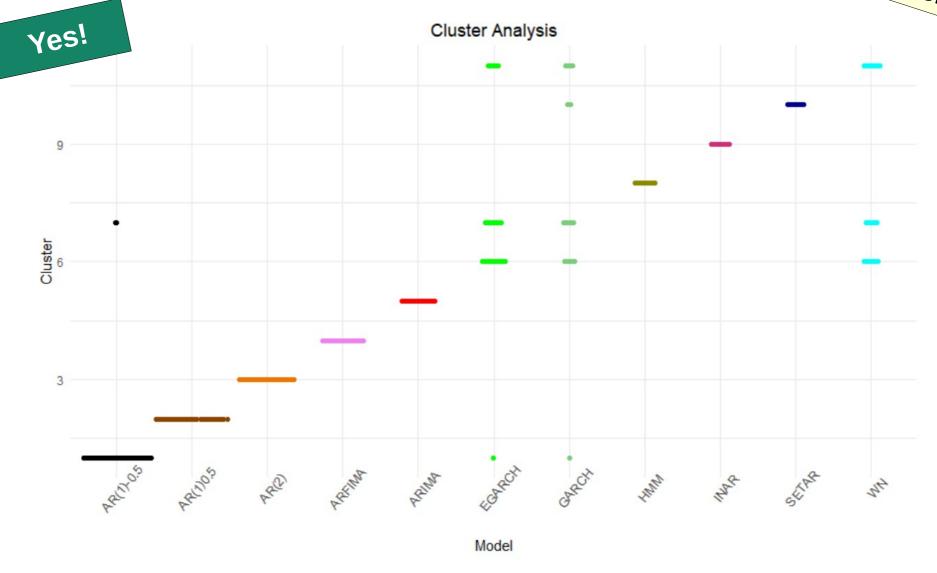
EGARCH

Conditional Heterocesdaticity and Asymmetry

Create randomized instances of each of these models

Can simple topological measures of different networks distinguish different processes of time series?

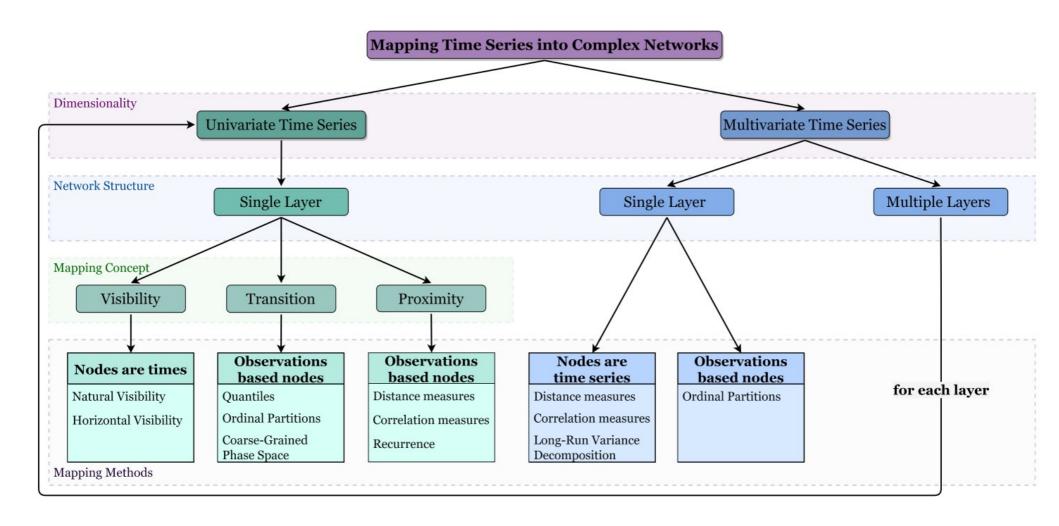
Vanessa Silva MSc Thesis



#### **More on TSA via NetSci**

Time Series Analysis via Network Science: Concepts and Algorithms\*

Vanessa Freitas Silva<sup>1</sup>, Maria Eduarda Silva<sup>2</sup>, Pedro Ribeiro<sup>1</sup>, and Fernando Silva<sup>1</sup>



Vanessa Silva PhD Thesis

International Journal of Data Science and Analytics https://doi.org/10.1007/s41060-024-00561-6

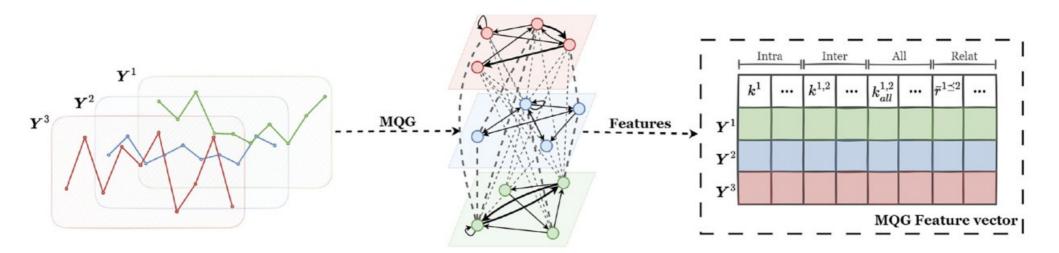
#### **REGULAR PAPER**



# Multilayer quantile graph for multivariate time series analysis and dimensionality reduction

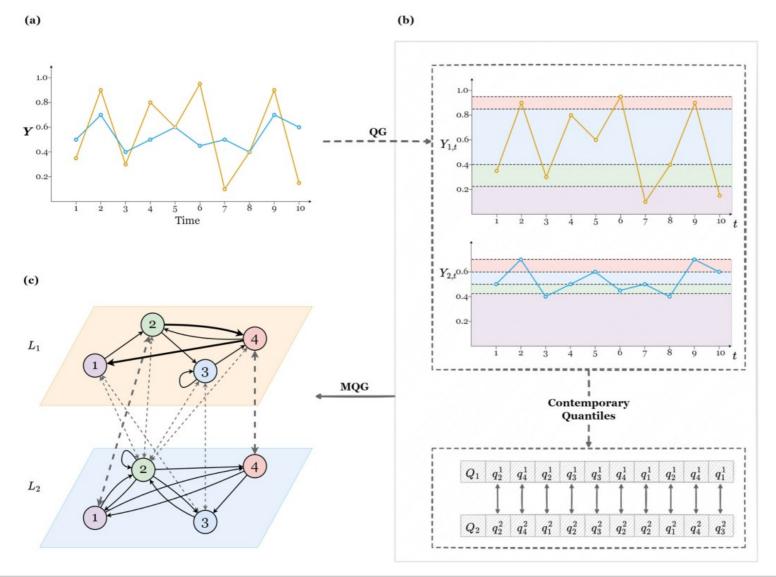
Vanessa Freitas Silva<sup>1</sup> · Maria Eduarda Silva<sup>2</sup> · Pedro Ribeiro<sup>1</sup> · Fernando Silva<sup>1</sup>

Received: 2 October 2023 / Accepted: 6 May 2024 © The Author(s) 2024



Vanessa Silva PhD Thesis

Multilayer quantile graph for multivariate time series analysis and dimensionality reduction





Data Mining and Knowledge Discovery (2025) 39:17 https://doi.org/10.1007/s10618-025-01089-4



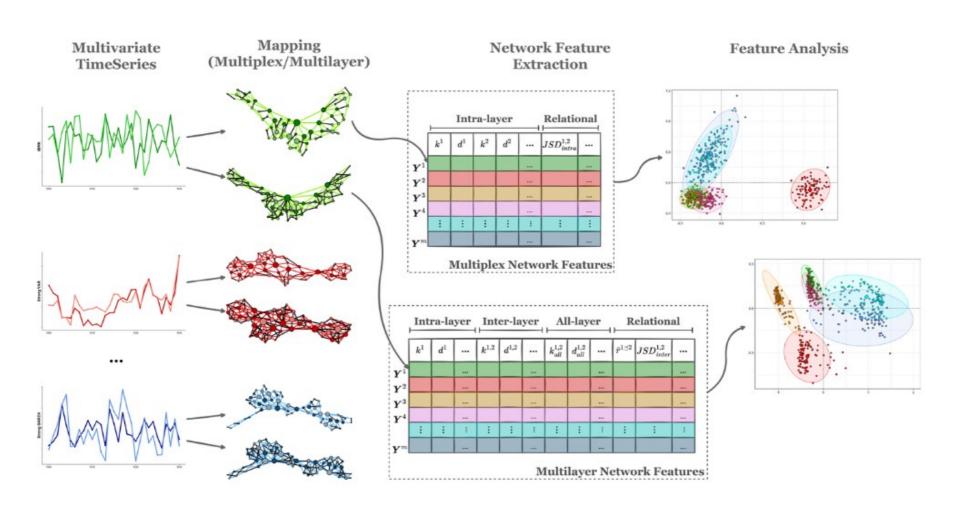
# Multilayer horizontal visibility graphs for multivariate time series analysis

Vanessa Freitas Silva<sup>1</sup> · Maria Eduarda Silva<sup>2</sup> · Pedro Ribeiro<sup>1</sup> · Fernando Silva<sup>1</sup>

Received: 6 February 2024 / Accepted: 4 January 2025 / Published online: 3 March 2025 © The Author(s) 2025

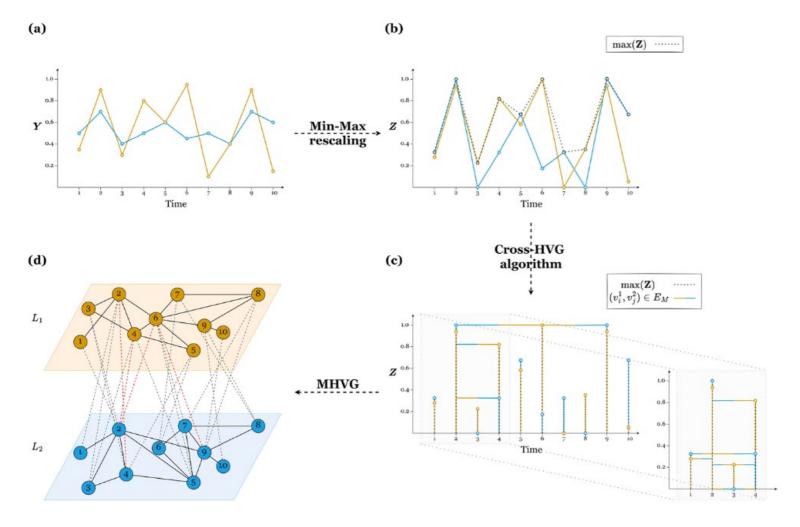
Vanessa Silva PhD Thesis

Multilayer horizontal visibility graphs for multivariate time series analysis



Vanessa Silva PhD Thesis

Multilayer horizontal visibility graphs for multivariate time series analysis



#### Vanessa Silva's Work

#### Time Series Analysis based on Complex Networks

#### Vanessa Alexandra Freitas da Silva

Master's degree in Networks and Informatics Systems Engineering
Computer Science Department
2018

#### Supervisor

Fernando Manuel Augusto da Silva, Full Professor, Faculty of Sciences, University of Porto

#### Co-supervisor

Pedro Manuel Pinto Ribeiro, Assistant Professor, Faculty of Sciences, University of Porto

#### Co-supervisor

Maria Eduarda da Rocha Pinto Augusto da Silva, Associate Professor, Faculty of Economics, University of Porto



#### Multidimensional Time Series Analysis: A Complex Networks Approach



Doctoral Program in Computer Science of the Universities of Minho, Aveiro and Porto (MAPi)
Computer Science Department
2023

# Time series forecasting via Network Science

#### Filipe Godinho Justiça

Master's degree in Data Science Computer Science Department 2022

#### Supervisor

Pedro Manuel Pinto Ribeiro, Assistant Professor, Faculty of Science, University of Porto

#### Co-supervisor

Maria Eduarda da Rocha Pinto Augusto da Silva, Associate Professor, Faculty of Economics, University of Porto



Associate Professor,

